

Last class

- Multi-objective optimization

- NSGA-II

- SMS-EMOA

- MOEA/D

Popular variants
of MOEA

Heuristic Search and Evolutionary Algorithms

Lecture 12: Evolutionary Algorithms for Constrained Optimization

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Constrained optimization

General formulation:

$$\begin{array}{ll} \min_{x \in \mathcal{X}} & f(x) \\ \text{s. t.} & g_i(x) = 0, \quad 1 \leq i \leq q; \\ & h_i(x) \leq 0, \quad q + 1 \leq i \leq m \end{array}$$

objective function

equality constraints

inequality constraints

A solution is **(in)feasible** if it does (not) satisfy the constraints

The goal: find a feasible solution minimizing the objective f

Example – knapsack

Knapsack problem: given n items, each with a weight w_i and a value v_i , to select a subset of items maximizing the sum of values while keeping the summed weights within some capacity W_{max}



$$\arg \max_{x \in \{0,1\}^n} \sum_{i=1}^n v_i x_i \quad s. t. \quad \sum_{i=1}^n w_i x_i \leq W_{max}$$

$x_i = 1$: the i -th item is included

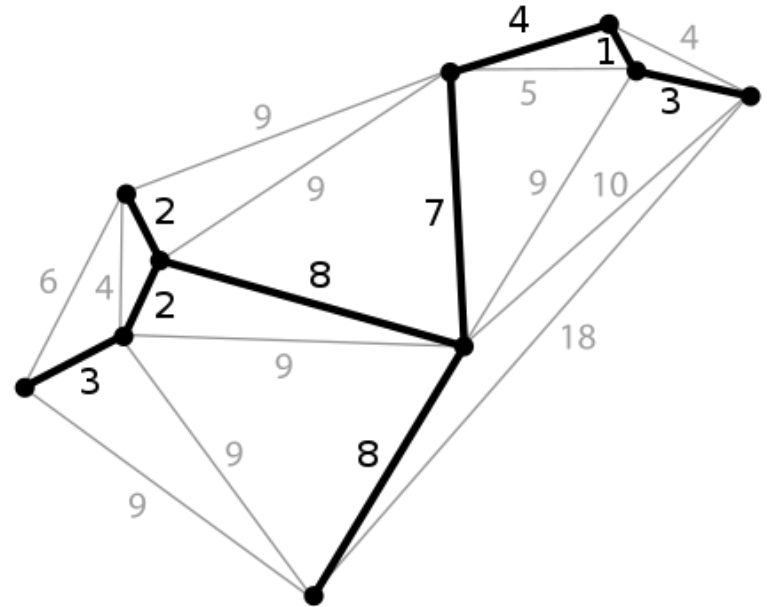
objective function

constraint

Example – minimum spanning tree

Minimum spanning tree problem:

given an undirected connected graph $G = (V, E)$ on n vertices and m edges with positive weights $w: E \rightarrow \mathbb{R}^+$, to find a **connected subgraph** $E' \subseteq E$ with the minimum weight



$$\arg \min_{x \in \{0,1\}^m} \sum_{i=1}^m w_i x_i \quad s. t. \quad c(x) = 1$$

objective function

$x_i = 1$: the i -th edge is selected

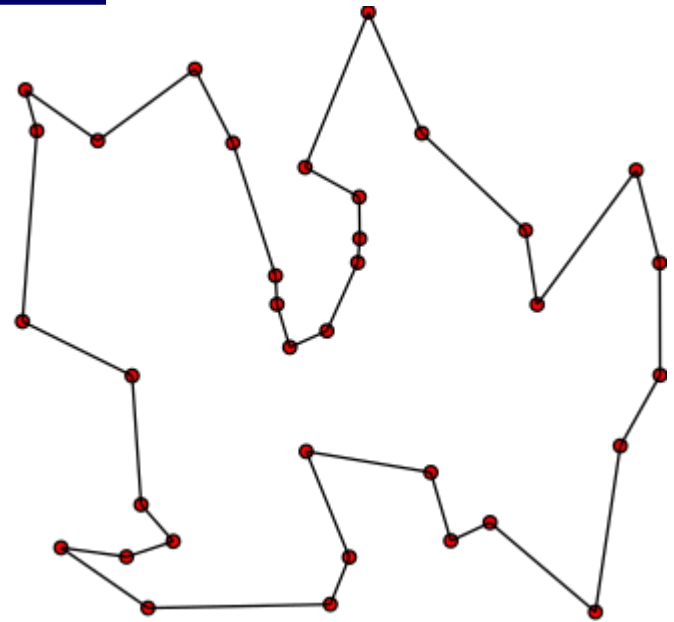
constraint

$c(x)$: the number of connected components

Example – traveling salesman

Traveling salesman problem:

given an undirected connected graph $G = (V, E)$ on n vertices and m edges with positive weights $w: E \rightarrow \mathbb{R}^+$, to find a **Hamilton cycle** with the minimum weight



$$\arg \min_x w(x) \quad s. t. \quad x \text{ is a Hamilton cycle}$$

Objective function: the sum of the edge weights on the cycle

Constraint: visit each vertex exactly once, starting and ending in the same vertex

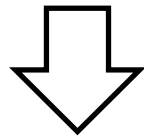
EAs for constrained optimization

How to deal with constraints when EAs are used for constrained optimization?

The optimization problems in real-world applications often come with constraints

Constraint handling strategies

The final output solution must satisfy the constraints

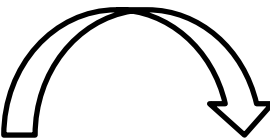


Common constraint handling strategies

- Penalty functions
- Repair functions
- Restricting search to the feasible region
- Decoder functions

Penalty functions

Penalty functions: add penalties on the fitness of infeasible solutions

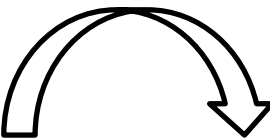
constrained  **unconstrained**

$$\begin{array}{ll} \min & f(x) \\ \text{s.t.} & g_i(x) = 0, \quad 1 \leq i \leq q; \\ & h_i(x) \leq 0, \quad q + 1 \leq i \leq m \end{array}$$
$$\min f(x) + \sum_{i=1}^m \lambda_i \cdot f_i(x)$$

the i -th constraint violation degree $f_i(x) = \begin{cases} |g_i(x)| & 1 \leq i \leq q \\ \max\{0, h_i(x)\} & q + 1 \leq i \leq m \end{cases}$

Penalty functions

Penalty functions: add penalties on the fitness of infeasible solutions

constrained  **unconstrained**

$$\begin{array}{ll} \min & f(x) \\ \text{s.t.} & g_i(x) = 0, \quad 1 \leq i \leq q; \\ & h_i(x) \leq 0, \quad q + 1 \leq i \leq m \end{array}$$
$$\min f(x) + \sum_{i=1}^m \lambda_i \cdot f_i(x)$$

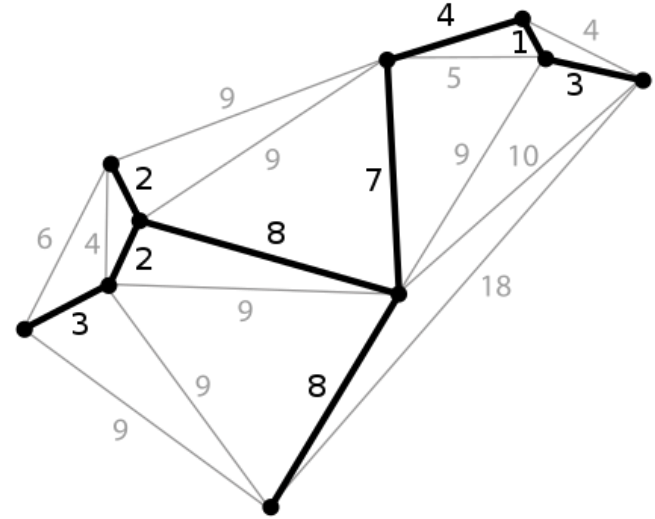
Requirement: the optimal solutions of the original and transformed problems should be consistent

- e.g., all λ_i are equal, and large enough: compare the constraint violation degrees first; if they are the same, compare the objective values f

Penalty functions

Minimum spanning tree problem:

given an undirected connected graph $G = (V, E)$ on n vertices and m edges with positive weights $w: E \rightarrow \mathbb{R}^+$, to find a connected subgraph $E' \subseteq E$ with the minimum weight



$$\arg \min_{x \in \{0,1\}^m} \sum_{i=1}^m w_i x_i \quad s.t. \quad c(x) = 1$$

Fitness function:

$$\min (c(x) - 1) \cdot w_{ub} + \sum_{i: x_i=1} w_i$$

Constraint violation degree \rightarrow $(c(x) - 1)$

$n^2 \cdot w_{max}$ \rightarrow w_{ub}

Original objective function \rightarrow $\sum_{i: x_i=1} w_i$

Repair functions

Repair functions: repair infeasible solutions to feasible

Example - Knapsack: given n items, each with a weight w_i and a value v_i , to select a subset of items maximizing the sum of values while keeping the summed weights within some capacity W_{max}



$$\arg \max_{x \in \{0,1\}^n} \sum_{i=1}^n v_i x_i \quad s. t. \quad \sum_{i=1}^n w_i x_i \leq W_{max}$$

$v_i: 4, 2, 6, 10, 4, 3, 7, 2; w_i: 2, 3, 3, 8, 6, 5, 7, 1; W_{max} = 25$

infeasible

1	1	0	1	1	0	1	1
---	---	---	---	---	---	---	---

feasible

1	1	0	1	1	0	0	1
---	---	---	---	---	---	---	---

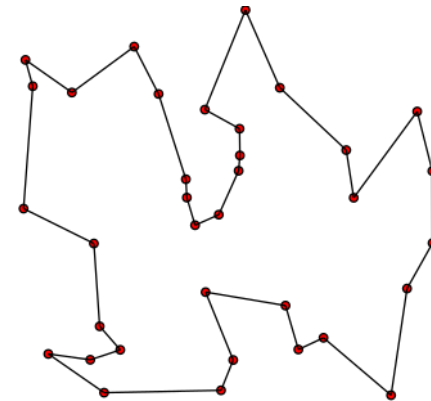


Repairing: scan from left to right, and keep the value 1 if the summed weight does not exceed W_{max}

Restricting search to the feasible region

Restricting search to the feasible region: preserving feasibility by special initialization and reproduction

Example - traveling salesman: given an undirected connected graph $G = (V, E)$ on n vertices and m edges with positive weights $w: E \rightarrow \mathbb{R}^+$, to find a Hamilton cycle with the minimum weight



$$\arg \min_x w(x) \quad s. t. \quad x \text{ is a Hamilton cycle}$$

Integer vector representation:
the order of visiting vertexes

Permutation
is feasible

1	6	2	5	7	4	8	3
---	---	---	---	---	---	---	---

**Initialize with permutation;
Apply mutation and
recombination operators for
permutation representation**

Decoder functions

Decoder functions: map each genotype to a feasible phenotype

Example - Knapsack: given n items, each with a weight w_i and a value v_i , to select a subset of items maximizing the sum of values while keeping the summed weights within some capacity W_{max}



$$\arg \max_{x \in \{0,1\}^n} \sum_{i=1}^n v_i x_i \quad s. t. \quad \sum_{i=1}^n w_i x_i \leq W_{max}$$

$v_i: 4, 2, 6, 10, 4, 3, 7, 2; w_i: 2, 3, 3, 8, 6, 5, 7, 1; W_{max} = 25$

genotype

1	1	0	1	1	0	1	1
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phenotype

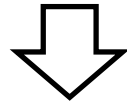
1	1	0	1	1	0	0	1
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Decoding: scan from left to right, and keep the value 1 if the summed weight does not exceed W_{max}

Constraint handling strategies

The final output solution must satisfy the constraints



Common constraint handling strategies

- Penalty functions
- Repair functions
- Restricting search to the feasible region
- Decoder functions

Other effective constraint handling strategies?

(1+1)-EA for MST

Minimum spanning tree (MST):

- **Given:** an undirected connected graph $G = (V, E)$ on n vertices and m edges with positive integer weights $w: E \rightarrow \mathbb{N}^+$
- **The Goal:** find a connected subgraph $E' \subseteq E$ with the minimum weight

Formulation: $\arg \min_{\mathbf{x} \in \{0,1\}^m} \sum_{i=1}^m w_i x_i \quad s. t. \quad c(\mathbf{x}) = 1$

$\mathbf{x} \in \{0,1\}^m \leftrightarrow$ a subgraph

$x_i = 1$ means that edge e_i is selected

(1+1)-EA for MST

(1+1)-EA: Given a pseudo-Boolean function f :

1. $\mathbf{x} :=$ randomly selected from $\{0,1\}^n$.
2. Repeat until some termination criterion is met
3. $\mathbf{x}' :=$ flip each bit of \mathbf{x} with probability $1/n$.
4. if $f(\mathbf{x}') \leq f(\mathbf{x})$
5. $\mathbf{x} = \mathbf{x}'$.

Using the strategy of
penalty functions

Fitness function:

$$\min (c(\mathbf{x}) - 1) \cdot w_{ub} + \sum_{i:x_i=1} w_i$$

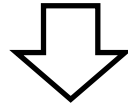
Diagram illustrating the fitness function components:

- $(c(\mathbf{x}) - 1)$ is circled in red and labeled "Constraint violation degree".
- w_{ub} is circled in red and labeled $n^2 \cdot w_{max}$.
- $\sum_{i:x_i=1} w_i$ is circled in red and labeled "Original objective function".

Theorem. [Neumann & Wegener, TCS'07; Doerr et al., Algorithmica'12] The expected running time of the (1+1)-EA solving the MST problem is $O(m^2(\log n + \log w_{max}))$.

MST by MOEAs

$$\arg \min_{\mathbf{x} \in \{0,1\}^m} \sum_{i=1}^m w_i x_i \quad \text{s.t.} \quad c(\mathbf{x}) = 1$$



Bi-objective reformulation $\min (c(\mathbf{x}), \sum_{i:x_i=1} w_i)$

Theorem. [Neumann & Wegener, Nature Computing'05] The expected running time of the GSEMO solving the MST problem is $O(mn(n + \log w_{max}))$.

Penalty functions: $O(m^2(\log n + \log w_{max}))$

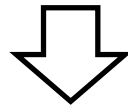
Bi-objective reformulation: $O(mn(n + \log w_{max}))$

Bi-objective reformulation is better
for dense graphs, e.g., $m \in \Theta(n^2)$



MST by MOEAs

$$\arg \min_{\mathbf{x} \in \{0,1\}^m} \sum_{i=1}^m w_i x_i \quad \text{s.t.} \quad c(\mathbf{x}) = 1$$



Bi-objective reformulation $\min (c(\mathbf{x}), \sum_{i:x_i=1} w_i)$

GSEMO: Given a pseudo-Boolean function vector \mathbf{f} :

1. $\mathbf{x} :=$ randomly selected from $\{0,1\}^n$. Keep the non-dominated solutions generated so-far
2. $P := \{\mathbf{x}\}$.
3. Repeat until some termination criterion is met
4. Choose \mathbf{x} from P uniformly at random.
5. $\mathbf{x}' :=$ flip each bit of \mathbf{x} with probability $1/n$.
6. if $\nexists \mathbf{z} \in P$ such that $\mathbf{z} < \mathbf{x}'$
7. $P := (P - \{\mathbf{z} \in P \mid \mathbf{x}' \preceq \mathbf{z}\}) \cup \{\mathbf{x}'\}$.

Proof

Main idea:

- (1) obtain the empty subgraph 0^n
- (2) obtain a minimum spanning tree

The analysis of phase (1): $\min (c(\mathbf{x}), w(\mathbf{x}) = \sum_{i:x_i=1} w_i)$

Using multiplicative drift analysis:

- design the distance function: $V(P) = \min \{w(\mathbf{x}) \mid \mathbf{x} \in P\}$
- analyze the expected drift:

the minimum weight
in the population

the resulting solution

$$E[V(\xi_t) - V(\xi_{t+1}) \mid \xi_t = P] \geq \frac{1}{n} \cdot \frac{1}{m} \left(1 - \frac{1}{m}\right)^{m-1} \cdot \sum_{i=1}^{|\mathbf{x}^*|} (w(\mathbf{x}^*) - w(\mathbf{y}^i))$$

select the solution \mathbf{x}^* with the smallest $w(\mathbf{x})$ value, and flip only one 1-bit

Proof

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Using multiplicative drift analysis:

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- analyze the expected drift:

$$\begin{aligned} E[V(\xi_t) - V(\xi_{t+1}) \mid \xi_t = P] &\geq \frac{1}{n} \cdot \frac{1}{m} \left(1 - \frac{1}{m}\right)^{m-1} \cdot \sum_{i=1}^{|\mathbf{x}^*|} (w(\mathbf{x}^*) - w(\mathbf{y}^i)) \\ &= \frac{1}{n} \cdot \frac{1}{m} \left(1 - \frac{1}{m}\right)^{m-1} \cdot w(\mathbf{x}^*) \\ &= \frac{1}{n} \cdot \frac{1}{m} \left(1 - \frac{1}{m}\right)^{m-1} \cdot V(\xi_t) \end{aligned}$$

Proof

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Using multiplicative drift analysis:

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- analyze the expected drift: $E[V(\xi_t) - V(\xi_{t+1}) \mid \xi_t = P] \geq \frac{1}{emn} V(\xi_t)$

Upper bound on the expected running time:

$$\sum_P \pi_0(P) \cdot \frac{1 + \ln(V(P)/V_{min})}{V(P)} \leq emn(1 + \ln(mw_{max}))$$

$V(P) \leq mw_{max}$ $V_{min} \geq 1$

Proof

Main idea:

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Using multiplicative drift analysis:

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Upper bound on the expected running time:

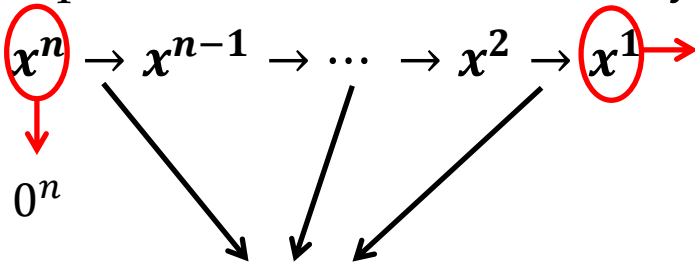
$$\sum_P \pi_0(P) \cdot \frac{1 + \ln (V(P)/V_{min})}{\delta} \leq emn(1 + \ln (mw_{max}))$$
$$\in O(mn (\log n + \log w_{max}))$$

Proof

The analysis of phase (2): $\min (c(\mathbf{x}), w(\mathbf{x}) = \sum_{i:x_i=1} w_i)$

\mathbf{x}^i : the Pareto optimal solution with i connected components

- the found Pareto optimal solutions will always be kept
- follow the path: $\mathbf{x}^n \rightarrow \mathbf{x}^{n-1} \rightarrow \dots \rightarrow \mathbf{x}^2 \rightarrow \mathbf{x}^1$ a minimum spanning tree



the probability is at least: $\frac{1}{n} \frac{1}{m} \left(1 - \frac{1}{m}\right)^{m-1} \geq \frac{1}{emn}$

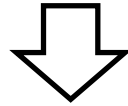
The expected running time is at most: $(n-1) \cdot emn \in O(mn^2)$

The expected running time of phase (1): $O(mn(\log n + \log w_{max}))$

The total expected running time: $O(mn(n + \log w_{max}))$

MST by MOEAs

$$\arg \min_{\mathbf{x} \in \{0,1\}^m} \sum_{i=1}^m w_i x_i \quad \text{s.t.} \quad c(\mathbf{x}) = 1$$



Bi-objective reformulation $\min (c(\mathbf{x}), \sum_{i:x_i=1} w_i)$

Theorem. [Neumann & Wegener, Nature Computing'05] The expected running time of the GSEMO solving the MST problem is $O(mn(n + \log w_{max}))$.

Penalty functions: $O(m^2(\log n + \log w_{max}))$

Bi-objective reformulation: $O(mn(n + \log w_{max}))$

Bi-objective reformulation is better
for dense graphs, e.g., $m \in \Theta(n^2)$



More examples

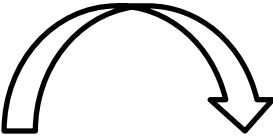
Problem	Penalty functions	Bi-objective reformulation
Set cover	<i>exponential</i>	$O(mn(\log c_{max} + \log n))$ [Friedrich et al., ECJ'10]
Minimum cut	<i>exponential</i>	$O(Fm(\log c_{max} + \log n))$ [Neumann et al., Algorithmica'11]
Minimum label spanning tree	$\Omega(ku^k)$	$O(k^2 \log k)$ [Lai et al., TEC'14]
Minimum cost coverage	<i>exponential</i>	$O(Nn(\log n + \log w_{max} + N))$ [Qian et al., IJCAI'15]

Better

Bi-objective reformulation

Main idea:

1. transform the original **constrained** optimization problem into a **bi-objective** optimization problem

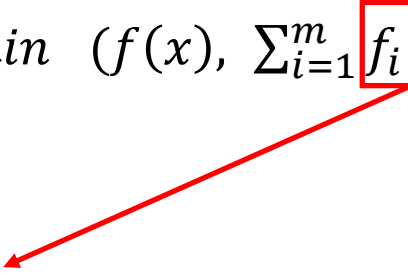
constrained  **bi-objective**

$$\begin{array}{ll} \min & f(x) \\ \text{s.t.} & g_i(x) = 0, \quad 1 \leq i \leq q; \\ & h_i(x) \leq 0, \quad q + 1 \leq i \leq m \end{array}$$

$\min (f(x), \sum_{i=1}^m f_i(x))$

$f_i(x) = \begin{cases} |g_i(x)| & 1 \leq i \leq q \\ \max\{0, h_i(x)\} & q + 1 \leq i \leq m \end{cases}$


constraint violation degree



Bi-objective reformulation

Main idea:

1. transform the original **constrained** optimization problem into a **bi-objective** optimization problem

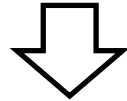
constrained  **bi-objective**

$$\begin{array}{ll} \min & f(x) \\ \text{s.t.} & g_i(x) = 0, \quad 1 \leq i \leq q; \\ & h_i(x) \leq 0, \quad q + 1 \leq i \leq m \end{array}$$
$$\min (f(x), \sum_{i=1}^m f_i(x))$$

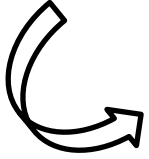
2. employ a multi-objective EA to solve the transformed problem
 3. output the feasible solution from the generated non-dominated solution set
- constraint violation degree = 0

Constraint handling strategies

The final output solution must satisfy the constraints



Common constraint handling strategies

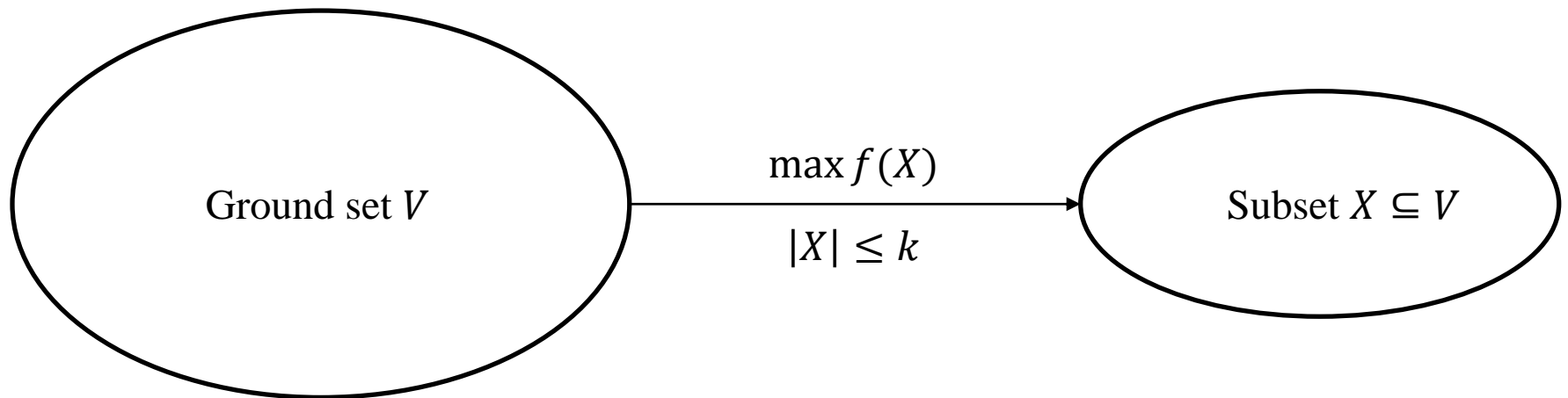
- Penalty functions
 - Repair functions
 - Restricting search to the feasible region
 - Decoder functions
- Search only in the feasible region
- **Bi-objective reformulation** allow infeasible solutions in the search
-  Better algorithms?

Subset selection

Subset selection is to select a subset of size k from a total set of n items for optimizing some objective function

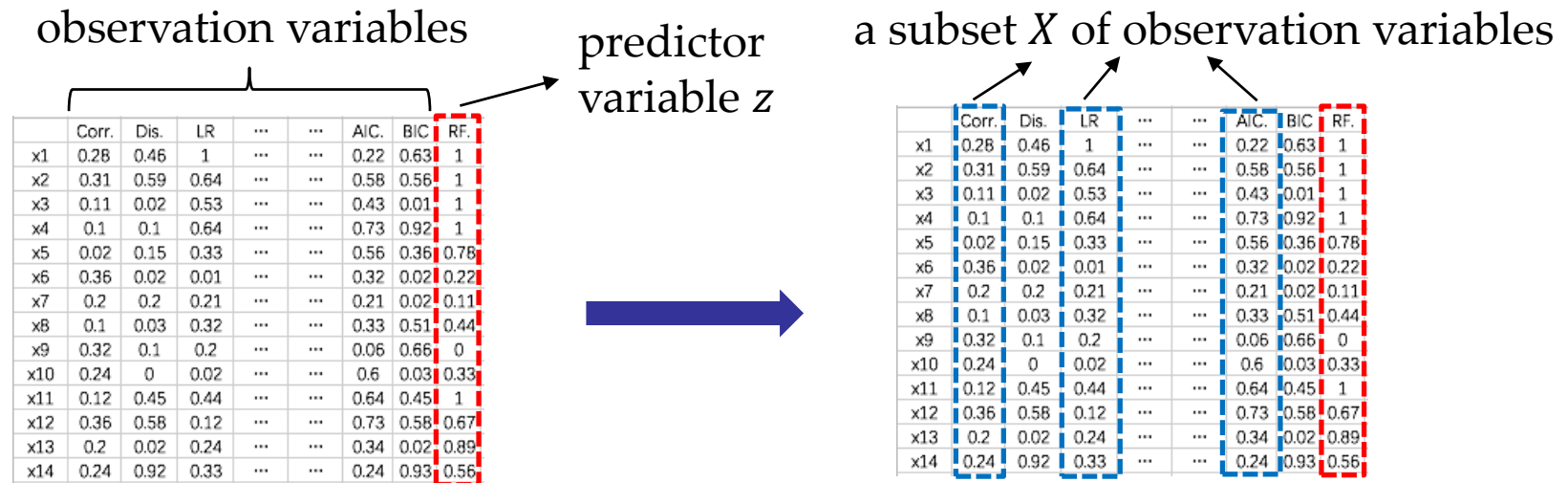
Formally stated: given all items $V = \{v_1, \dots, v_n\}$, an objective function $f: 2^V \rightarrow \mathbb{R}$ and a budget k , to find a subset $X \subseteq V$ such that

$$\max_{X \subseteq V} f(X) \quad \text{s.t.} \quad |X| \leq k.$$



Application - sparse regression

Sparse regression [Tropp, TIT'04]: select a few observation variables to best approximate the predictor variable by linear regression

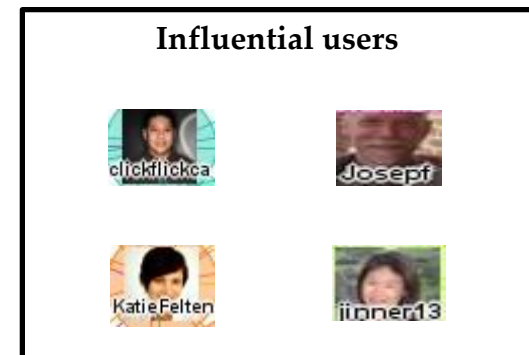
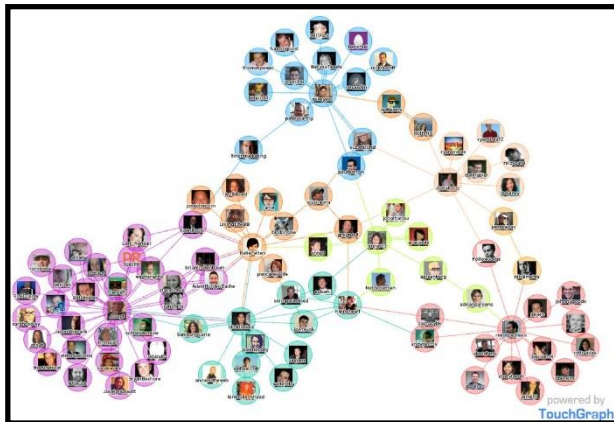


Item v_i : an observation variable

Objective f : squared multiple correlation $R_{z,X}^2 = \frac{\text{variance} - \text{mean squared error}}{\text{variance}}$

Application - influence maximization

Influence maximization [Kempe et al., KDD'03]: select a subset of users from a social network to maximize its influence spread



Item v_i : a social network user

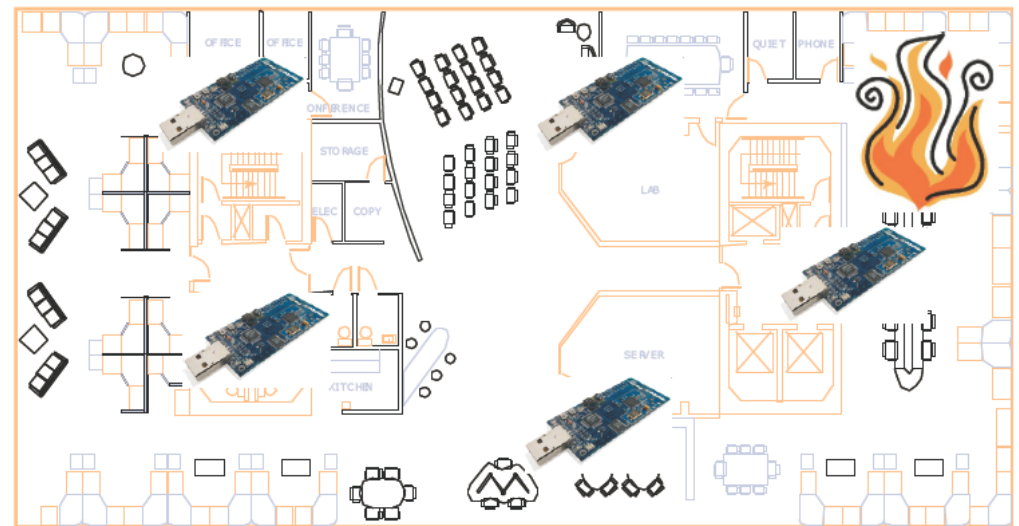
Objective f : influence spread, measured by the expected number of social network users activated by diffusion

Application - sensor placement

Sensor placement [Krause & Guestrin, IJCAI'09 Tutorial] : select a few places to install sensors such that the information gathered is maximized



Water contamination detection

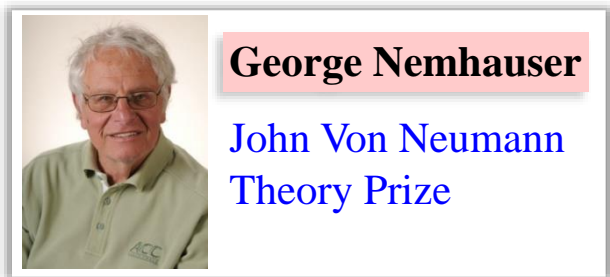
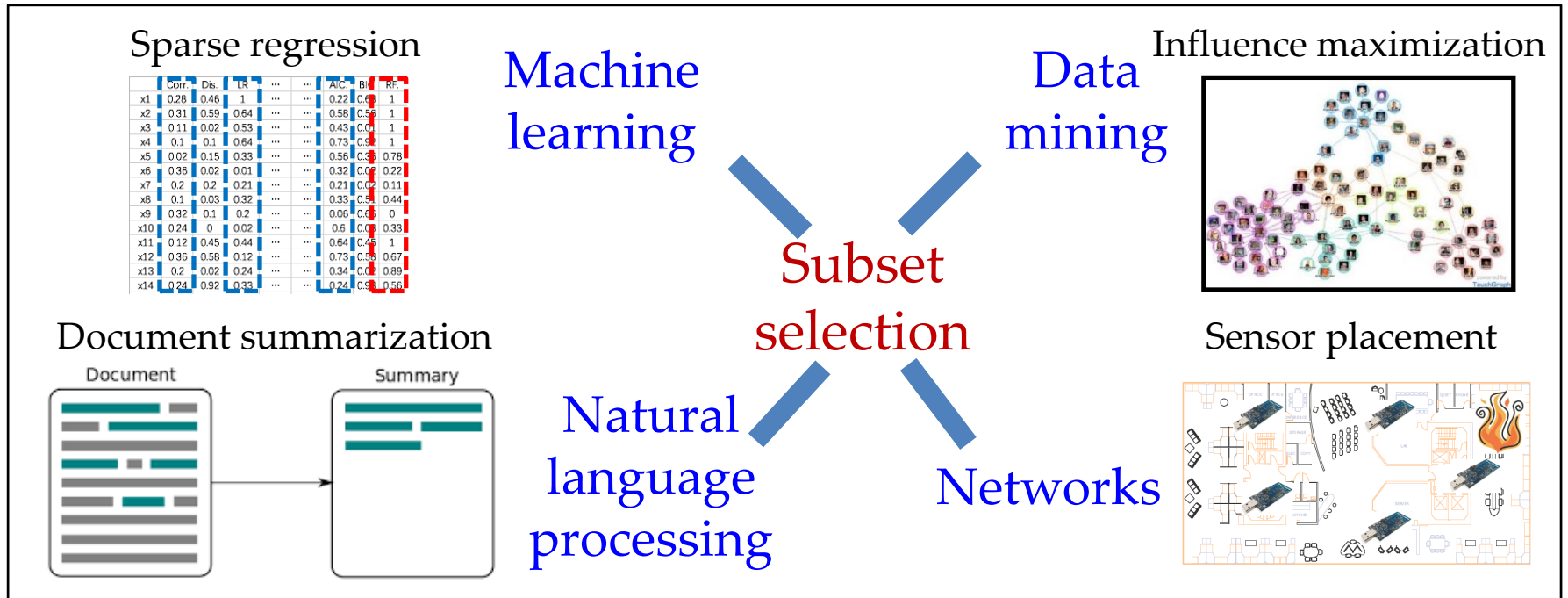


Fire detection

Item v_i : a place to install a sensor

Objective f : entropy

Subset selection



[Mathematical Programming 1978]

f : monotone and submodular

The greedy algorithm:

$(1 - 1/e)$ -approximation



Best Paper/Test of
Time Award:

[Kempe et al., KDD'03]

[Das & Kempe, ICML'11]

[Iyer & Bilmes, NIPS'13]

Subset representation

A subset $X \subseteq V$ can be naturally represented by a Boolean vector $\mathbf{x} \in \{0,1\}^n$

- the i -th bit $x_i = 1$ if the item $v_i \in X$; $x_i = 0$ otherwise
- $X = \{v_i \mid x_i = 1\}$

$V = \{v_1, v_2, v_3, v_4, v_5\}$	a subset $X \subseteq V$		a Boolean vector $\mathbf{x} \in \{0,1\}^5$
	\emptyset		00000
	$\{v_1\}$	\Leftrightarrow	10000
	$\{v_2, v_3, v_5\}$		01101
	$\{v_1, v_2, v_3, v_4, v_5\}$		11111

POSS algorithm

POSS algorithm [Qian, Yu and Zhou, NIPS'15]

Transformation:

$$\begin{array}{ll} \max_{X \subseteq V} f(X) \quad \text{s.t.} \quad |X| \leq k & \text{original} \\ \Downarrow & \\ \min_{X \subseteq V} (-f(X), |X|) & \text{bi-objective} \end{array}$$

Algorithm 1 POSS

Input: all variables $V = \{X_1, \dots, X_n\}$, a given objective f and an integer parameter $k \in [1, n]$

Parameter: the number of iterations T

Output: a subset of V with at most k variables

Process:

```
1: Let  $s = \{0\}^n$  and  $P = \{s\}$ .
2: Let  $t = 0$ .
3: while  $t < T$  do
4:   Select  $s$  from  $P$  uniformly at random.
5:   Generate  $s'$  by flipping each bit of  $s$  with prob.  $\frac{1}{n}$ .
6:   Evaluate  $f_1(s')$  and  $f_2(s')$ .
7:   if  $\nexists z \in P$  such that  $z \prec s'$  then
8:      $Q = \{z \in P \mid s' \preceq z\}$ .
9:      $P = (P \setminus Q) \cup \{s'\}$ .
10:  end if
11:   $t = t + 1$ .
12: end while
13: return  $\arg \min_{s \in P, |s| \leq k} f_1(s)$ 
```

Initialization: put the special solution $\{0\}^n$ into the population P

Parent selection & Reproduction: pick a solution x randomly from P , and flip each bit of x with prob. $1/n$ to generate a new solution

Evaluation & Survivor selection: if the new solution is not dominated, put it into P and weed out bad solutions

Output: select the best feasible solution

Sparse regression

Sparse regression: given all observation variables $V = \{v_1, \dots, v_n\}$, a predictor variable z and a budget k , to find a subset $X \subseteq V$ such that

$$\max_{X \subseteq V} R_{z,X}^2 = \frac{\text{Var}(z) - \text{MSE}_{z,X}}{\text{Var}(z)} \quad \text{s.t.} \quad |X| \leq k$$

$\text{Var}(z)$: variance of z

$\text{MSE}_{z,X}$: mean squared error of predicting z by using observation variables in X

observation variables

	Corr.	Dis.	LR	AIC.	BIC	RF.
x1	0.28	0.46	1	0.22	0.63	1
x2	0.31	0.59	0.64	0.58	0.56	1
x3	0.11	0.02	0.53	0.43	0.01	1
x4	0.1	0.1	0.64	0.73	0.92	1
x5	0.02	0.15	0.33	0.56	0.36	0.78
x6	0.36	0.02	0.01	0.32	0.02	0.22
x7	0.2	0.2	0.21	0.21	0.02	0.11
x8	0.1	0.03	0.32	0.33	0.51	0.44
x9	0.32	0.1	0.2	0.06	0.66	0
x10	0.24	0	0.02	0.6	0.03	0.33
x11	0.12	0.45	0.44	0.64	0.45	1
x12	0.36	0.58	0.12	0.73	0.58	0.67
x13	0.2	0.02	0.24	0.34	0.02	0.89
x14	0.24	0.92	0.33	0.24	0.93	0.56

predictor variable z

a subset X of observation variables

	Corr.	Dis.	LR	AIC.	BIC	RF.
x1	0.28	0.46	1	0.22	0.63	1
x2	0.31	0.59	0.64	0.58	0.56	1
x3	0.11	0.02	0.53	0.43	0.01	1
x4	0.1	0.1	0.64	0.73	0.92	1
x5	0.02	0.15	0.33	0.56	0.36	0.78
x6	0.36	0.02	0.01	0.32	0.02	0.22
x7	0.2	0.2	0.21	0.21	0.02	0.11
x8	0.1	0.03	0.32	0.33	0.51	0.44
x9	0.32	0.1	0.2	0.06	0.66	0
x10	0.24	0	0.02	0.6	0.03	0.33
x11	0.12	0.45	0.44	0.64	0.45	1
x12	0.36	0.58	0.12	0.73	0.58	0.67
x13	0.2	0.02	0.24	0.34	0.02	0.89
x14	0.24	0.92	0.33	0.24	0.93	0.56

Experimental results

the size constraint: $k = 8$

the number of iterations of POSS: $2ek^2n$

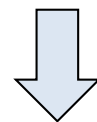
exhaustive search

greedy algorithms

relaxation methods

Data set	OPT	POSS	FR	FoBa	OMP	RFE	MCP
housing	.7437±.0297	.7437±.0297	.7429±.0300●	.7423±.0301●	.7415±.0300●	.7388±.0304●	.7354±.0297●
eunite2001	.8484±.0132	.8482±.0132	.8348±.0143●	.8442±.0144●	.8349±.0150●	.8424±.0153●	.8320±.0150●
svmguide3	.2705±.0255	.2701±.0257	.2615±.0260●	.2601±.0279●	.2557±.0270●	.2136±.0325●	.2397±.0237●
ionosphere	.5995±.0326	.5990±.0329	.5920±.0352●	.5929±.0346●	.5921±.0353●	.5832±.0415●	.5740±.0348●
sonar	–	.5365±.0410	.5171±.0440●	.5138±.0432●	.5112±.0425●	.4321±.0636●	.4496±.0482●
triazines	–	.4301±.0603	.4150±.0592●	.4107±.0600●	.4073±.0591●	.3615±.0712●	.3793±.0584●
coil2000	–	.0627±.0076	.0624±.0076●	.0619±.0075●	.0619±.0075●	.0363±.0141●	.0570±.0075●
mushrooms	–	.9912±.0020	.9909±.0021●	.9909±.0022●	.9909±.0022●	.6813±.1294●	.8652±.0474●
clean1	–	.4368±.0300	.4169±.0299●	.4145±.0309●	.4132±.0315●	.1596±.0562●	.3563±.0364●
w5a	–	.3376±.0267	.3319±.0247●	.3341±.0258●	.3313±.0246●	.3342±.0276●	.2694±.0385●
gisette	–	.7265±.0098	.7001±.0116●	.6747±.0145●	.6731±.0134●	.5360±.0318●	.5709±.0123●
farm-ads	–	.4217±.0100	.4196±.0101●	.4170±.0113●	.4170±.0113●	–	.3771±.0110●
POSS: win/tie/loss	–	–	12/0/0	12/0/0	12/0/0	11/0/0	12/0/0

- denotes that POSS is significantly better by the t -test with confidence level 0.05



POSS is significantly better than all the compared state-of-the-art algorithms on all data sets

Theoretical analysis

POSS can achieve the optimal polynomial-time approximation guarantee

Theorem 1. For subset selection with monotone objective functions, POSS using $E[T] \leq 2ek^2n$ finds a solution X with $|X| \leq k$ and

$$f(X) \geq (1 - e^{-\gamma}) \cdot \text{OPT}.$$

the optimal polynomial-time approximation guarantee
for monotone f [Harshaw et al., ICML'19]

Proof

Lemma 1. For any $X \subseteq V$, there exists one item $\hat{v} \in V \setminus X$ such that

$$f(X \cup \{\hat{v}\}) - f(X) \geq \frac{\gamma}{k} (\text{OPT} - f(X))$$

submodularity ratio [Das & Kempe, ICML'11]

the optimal function value

Roughly speaking, the improvement by adding a specific item is proportional to the current distance to the optimum

Proof

Lemma 1. For any $X \subseteq V$, there exists one item $\hat{v} \in V \setminus X$ such that

$$f(X \cup \{\hat{v}\}) - f(X) \geq \frac{\gamma}{k} (\text{OPT} - f(X))$$

Main idea: a subset

- consider a solution \mathbf{x} with $|\mathbf{x}| \leq i$ and $f(\mathbf{x}) \geq \left(1 - \left(1 - \frac{\gamma}{k}\right)^i\right) \cdot \text{OPT}$

$$i = 0$$

↑

initial solution 00 ... 0

$$|00 \dots 0| = 0$$

$$f(00 \dots 0) = 0$$

$$i = k$$

↓

$$1 - \left(1 - \frac{\gamma}{k}\right)^k = 1 - \left(1 - \frac{1}{k/\gamma}\right)^{(k/\gamma) \cdot \gamma}$$

let $m = k/\gamma$

$$\geq 1 - e^{-\gamma}$$

$$(1 - 1/m)^m \leq 1/e$$

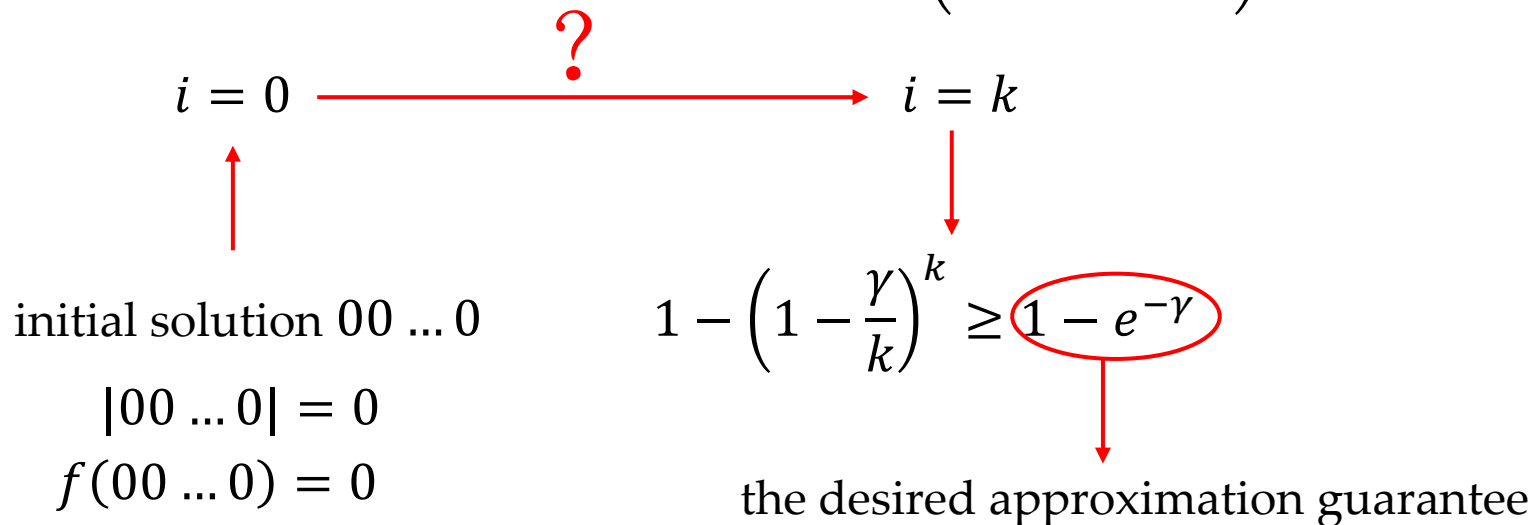
Proof

Lemma 1. For any $X \subseteq V$, there exists one item $\hat{v} \in V \setminus X$ such that

$$f(X \cup \{\hat{v}\}) - f(X) \geq \frac{\gamma}{k} (\text{OPT} - f(X))$$

Main idea: a subset

- consider a solution \mathbf{x} with $|\mathbf{x}| \leq i$ and $f(\mathbf{x}) \geq \left(1 - \left(1 - \frac{\gamma}{k}\right)^i\right) \cdot \text{OPT}$



Proof

Lemma 1. For any $X \subseteq V$, there exists one item $\hat{v} \in V \setminus X$ such that

$$f(X \cup \{\hat{v}\}) - f(X) \geq \frac{\gamma}{k} (\text{OPT} - f(X))$$

Main idea:

a subset

- consider a solution \mathbf{x} with $|\mathbf{x}| \leq i$ and $f(\mathbf{x}) \geq \left(1 - \left(1 - \frac{\gamma}{k}\right)^i\right) \cdot \text{OPT}$

- in each iteration of POSS:

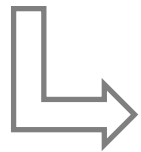
- select \mathbf{x} from the population P
- flip one specific 0-bit of \mathbf{x} to 1-bit
(i.e., add the specific item \hat{v} in Lemma 1)

→ $|\mathbf{x}'| = |\mathbf{x}| + 1 \leq i + 1$ and $f(\mathbf{x}') \geq \left(1 - \left(1 - \frac{\gamma}{k}\right)^{i+1}\right) \cdot \text{OPT}$

Proof

Lemma 1. For any $X \subseteq V$, there exists one item $\hat{v} \in V \setminus X$ such that

$$f(X \cup \{\hat{v}\}) - f(X) \geq \frac{\gamma}{k} (\text{OPT} - f(X))$$

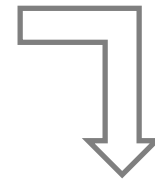


$$f(\mathbf{x}') - f(\mathbf{x}) \geq \frac{\gamma}{k} \cdot (\text{OPT} - f(\mathbf{x}))$$



$$f(\mathbf{x}') \geq \left(1 - \frac{\gamma}{k}\right) f(\mathbf{x}) + \frac{\gamma}{k} \cdot \text{OPT}$$

$$f(\mathbf{x}) \geq \left(1 - \left(1 - \frac{\gamma}{k}\right)^i\right) \cdot \text{OPT}$$



$$f(\mathbf{x}') \geq \left(1 - \frac{\gamma}{k}\right) \left(1 - \left(1 - \frac{\gamma}{k}\right)^i\right) \cdot \text{OPT} + \frac{\gamma}{k} \cdot \text{OPT} = \left(1 - \left(1 - \frac{\gamma}{k}\right)^{i+1}\right) \cdot \text{OPT}$$

Proof

Lemma 1. For any $X \subseteq V$, there exists one item $\hat{v} \in V \setminus X$ such that

$$f(X \cup \{\hat{v}\}) - f(X) \geq \frac{\gamma}{k} (\text{OPT} - f(X))$$

Main idea: a subset

- consider a solution \mathbf{x} with $|\mathbf{x}| \leq i$ and $f(\mathbf{x}) \geq \left(1 - \left(1 - \frac{\gamma}{k}\right)^i\right) \cdot \text{OPT}$
- in each iteration of POSS:

- select \mathbf{x} from the population P , the probability: $\frac{1}{|P|}$
- flip one specific 0-bit of \mathbf{x} to 1-bit, the probability: $\frac{1}{n} \left(1 - \frac{1}{n}\right)^{n-1} \geq \frac{1}{en}$
(i.e., add the specific item \hat{v} in Lemma 1)

$$|\mathbf{x}'| = |\mathbf{x}| + 1 \leq i + 1 \text{ and } f(\mathbf{x}') \geq \left(1 - \left(1 - \frac{\gamma}{k}\right)^{i+1}\right) \cdot \text{OPT}$$

$$i \longrightarrow i + 1 \quad \text{the probability: } \frac{1}{|P|} \cdot \frac{1}{en}$$

Proof

Lemma 1. For any $X \subseteq V$, there exists one item $\hat{v} \in V \setminus X$ such that

$$f(X \cup \{\hat{v}\}) - f(X) \geq \frac{\gamma}{k} (\text{OPT} - f(X))$$

Main idea:

a subset

- consider a solution \mathbf{x} with $|\mathbf{x}| \leq i$ and $f(\mathbf{x}) \geq \left(1 - \left(1 - \frac{\gamma}{k}\right)^i\right) \cdot \text{OPT}$
- in each iteration of POSS:

$$i \longrightarrow i + 1 \quad \text{the probability: } \frac{1}{|P|} \cdot \frac{1}{en} \xrightarrow{|P| \leq 2k} \frac{1}{2ekn}$$

- Exclude solutions with size at least $2k$
- The solutions in P are always incomparable

For each size in $\{0, 1, \dots, 2k - 1\}$, there exists at most one solution in P

Proof

Lemma 1. For any $X \subseteq V$, there exists one item $\hat{v} \in V \setminus X$ such that

$$f(X \cup \{\hat{v}\}) - f(X) \geq \frac{\gamma}{k} (\text{OPT} - f(X))$$

Main idea: a subset

- consider a solution \mathbf{x} with $|\mathbf{x}| \leq i$ and $f(\mathbf{x}) \geq \left(1 - \left(1 - \frac{\gamma}{k}\right)^i\right) \cdot \text{OPT}$
- in each iteration of POSS:

$$i \longrightarrow i + 1 \quad \text{the probability: } \frac{1}{|P|} \cdot \frac{1}{en} \xrightarrow{|P| \leq 2k} \frac{1}{2ekn}$$

$$i \longrightarrow i + 1 \quad \text{the expected number of iterations: } 2ekn$$

$$i = 0 \longrightarrow k \quad \text{the expected number of iterations: } k \cdot 2ekn$$

Theoretical analysis:
The advantage of bi-objective reformulation for handling constraints

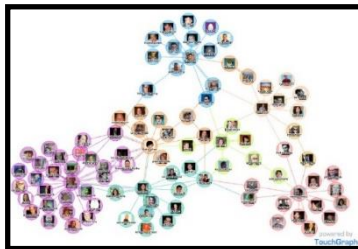


Algorithm design:
The POSS algorithm for subset selection

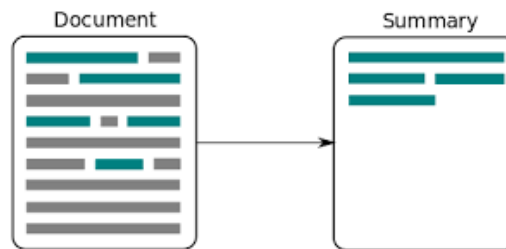
Sparse regression

	Corr.	Dis.	LR	AIC	BIC	RF
x1	0.28	0.46	1	0.22	0.63	1
x2	0.31	0.59	0.64	0.58	0.56	1
x3	0.11	0.02	0.53	0.43	0.01	1
x4	0.1	0.1	0.64	0.73	0.92	1
x5	0.02	0.15	0.33	0.56	0.36	0.78
x6	0.36	0.02	0.01	0.32	0.02	0.22
x7	0.2	0.2	0.21	0.21	0.02	0.11
x8	0.1	0.03	0.32	0.33	0.51	0.44
x9	0.32	0.1	0.2	0.06	0.66	0
x10	0.24	0	0.02	0.6	0.03	0.33
x11	0.12	0.45	0.44	0.64	0.45	1
x12	0.36	0.58	0.12	0.73	0.58	0.67
x13	0.2	0.02	0.24	0.34	0.02	0.89
x14	0.24	0.92	0.33	0.24	0.93	0.56

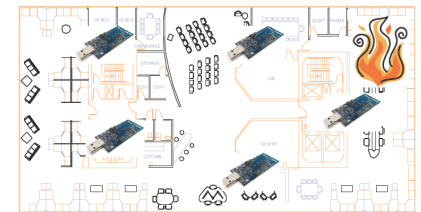
Influence maximization



Document summarization



Sensor placement



POSS algorithm

POSS algorithm [Qian, Yu and Zhou, NIPS'15]

Transformation:

$$\begin{array}{ll} \max_{X \subseteq V} f(X) \quad \text{s.t.} \quad |X| \leq k & \text{original} \\ \Downarrow & \\ \min_{X \subseteq V} (-f(X), |X|) & \text{bi-objective} \end{array}$$

Algorithm 1 POSS

Input: all variables $V = \{X_1, \dots, X_n\}$, a given objective f and an integer parameter $k \in [1, n]$

Parameter: the number of iterations T

Output: a subset of V with at most k variables

Process:

1: Let $s = \{0\}^n$ and $P = \{s\}$.

2: Let $t = 0$.

3: **while** $t < T$ **do**

4: Select s from P uniformly at random.

5: Generate s' by flipping each bit of s with prob. $\frac{1}{n}$.

6: Evaluate $f_1(s')$ and $f_2(s')$.

7: **if** $\nexists z \in P$ such that $z \prec s'$ **then**

8: $Q = \{z \in P \mid s' \preceq z\}$.

9: $P = (P \setminus Q) \cup \{s'\}$.

10: **end if**

11: $t = t + 1$.

12: **end while**

13: **return** $\arg \min_{s \in P, |s| \leq k} f_1(s)$

Parent selection & Reproduction:
pick a solution \mathbf{x} randomly from P , and flip each bit of \mathbf{x} with prob. $1/n$ to generate a new solution

Using bit-wise mutation only

PORSS algorithm

PORSS algorithm [Qian, Bian and Feng, AAI'20]

Transformation: $\max_{X \subseteq V} f(X) \quad s.t. \quad |X| \leq k$ original

\Downarrow

$\min_{X \subseteq V} (-f(X), |X|)$ bi-objective

Algorithm 2 PORSS Algorithm

Input: $V = \{v_1, \dots, v_n\}$; objective $f : 2^V \rightarrow \mathbb{R}$; budget k

Parameter: the number T of iterations

Output: a subset of V with at most k items

Process:

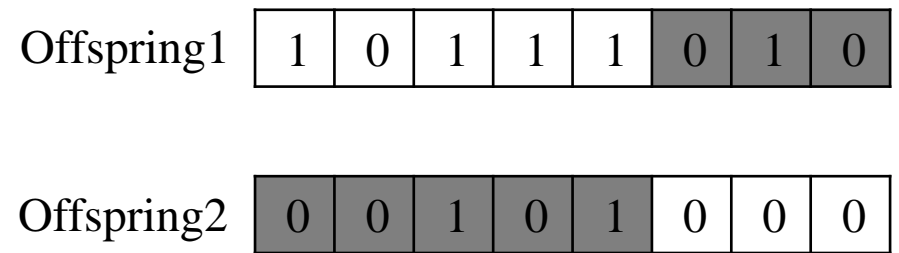
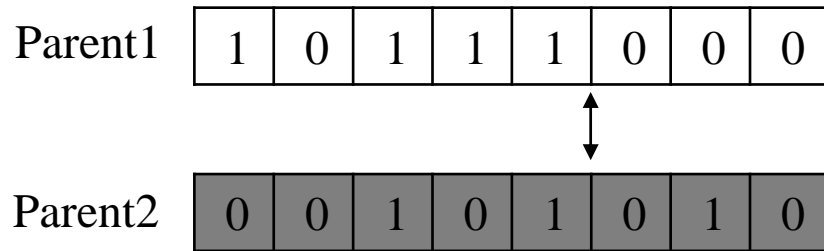
- 1: Let $x = 0^n$, $P = \{x\}$ and $t = 0$;
- 2: **while** $t < T$ **do**
- 3: Select x, y from P randomly with replacement;
- 4: Apply recombination on x, y to generate x', y' ;
- 5: Apply bit-wise mutation on x', y' to generate x'', y'' ;
- 6: **for each** $q \in \{x'', y''\}$
- 7: **if** $\nexists z \in P$ such that $z \prec q$ **then**
- 8: $P = (P \setminus \{z \in P \mid q \preceq z\}) \cup \{q\}$
- 9: **end if**
- 10: **end for**
- 11: $t = t + 1$
- 12: **end while**
- 13: **return** $\arg \max_{x \in P, |x| \leq k} f(x)$

Parent selection & Reproduction:

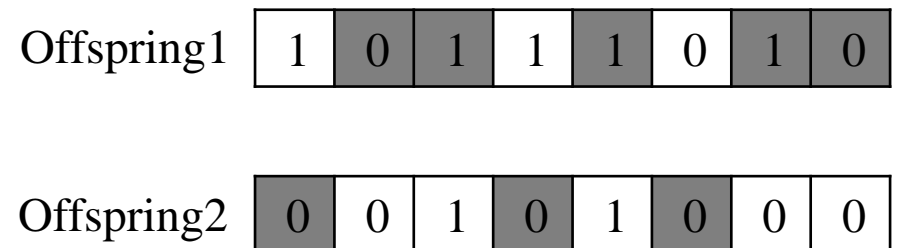
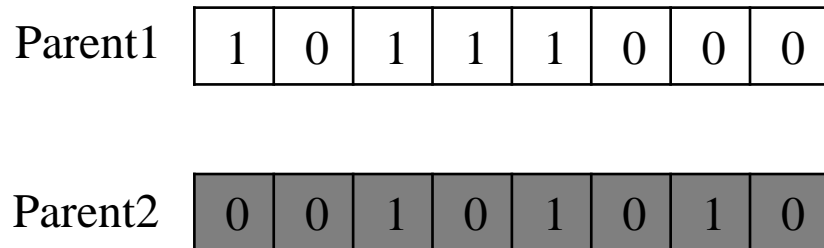
- pick two solutions randomly from P
- apply recombination operator
- apply bit-wise mutation operator

PORSS algorithm

- One-point crossover



- Uniform crossover



PORSS algorithm

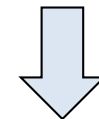
the size constraint: $k = 8$

State-of-the-art
algorithms

PORSS using one-
point crossover

PORSS using
uniform crossover

Data set	(#inst, #feat)	OPT	Greedy	POSS	PORSS _o	PORSS _u
<i>svmguide3</i>	(1243, 22)	0.221	0.214	0.220±0.001	0.220±0.001	0.221±0.001
<i>triazines</i>	(186, 60)	0.328	0.316	0.327±0.000	0.328±0.000	0.328±0.000
<i>clean1</i>	(476, 166)	–	0.371	0.386±0.004	0.387±0.006	0.393±0.005
<i>usps</i>	(7291, 256)	–	0.562	0.570±0.003	0.572±0.003	0.572±0.003
<i>scene</i>	(1211, 294)	–	0.254	0.268±0.003	0.272±0.002	0.271±0.002
<i>protein</i>	(17766, 356)	–	0.132	0.132±0.000	0.133±0.000	0.133±0.000
<i>colon-cancer</i>	(62, 2000)	–	0.890	0.906±0.011	0.909±0.018	0.911±0.014
<i>cifar10</i>	(50000, 3072)	–	0.069	0.070±0.001	0.070±0.001	0.071±0.001
<i>leukemia</i>	(72, 7129)	–	0.947	0.966±0.009	0.968±0.006	0.969±0.007
<i>smallNORB</i>	(24300, 18432)	–	0.461	0.535±0.007	0.547±0.003	0.550±0.002
POSS: Count of direct win			9.5	–	1	0
Average rank			3.95	2.95	1.85	1.25



PORSS performs the best

Summary

- Constrained optimization
- Constraint handling strategies
 - Penalty functions
 - Repair functions
 - Restricting search to the feasible region
 - Decoder functions
 - Bi-objective reformulation → Give an example of algorithm design guided by theoretical analysis

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