Last class

- Genetic algorithms
- Evolutionary strategies
- Evolutionary programming
- Genetic programming
- Differential evolution
- Particle swarm optimization
- Ant colony optimization
- Estimation of distribution algorithms

Historical EA variants

Recent EA variants





Heuristic Search and Evolutionary Algorithms

Lecture 9: Theoretical Analysis of Evolutionary Algorithms

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Theoretical analysis

Develop solid, rigorous, and reliable knowledge

- empirical studies are limited to the experimented cases
- overcome experiment difficulties
- derive provable conclusions

Particularly for evolutionary algorithms (EAs)

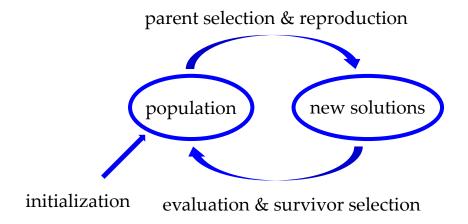
- when to use them?
- what are their merits and drawbacks?
- how different configurations affect their performance?
- design better EAs

• • •

Theoretical analysis of EAs

EAs have been widely used in real applications

GA, ES, EP, GP, PSO, ACO, DE, EDA,



- EAs are complex and randomized
 - ➤ The components of EAs, e.g., mutation, recombination, selection and population, can be complex
 - ➤ With the same input, the output by independent runs can be different

Theoretical analysis is very difficult



Schema theorem [Holland, 1975]

Proposed to explain how the population of EAs changes in steps

Consider a binary solution space $\{0,1\}^5$ =

A schema *H* is a template with "#"= "any", which defines a subspace

The order o(H): the number of positions that do not have #

The defining length d(H): the distance between the outermost defined positions



Schema theorem [Holland, 1975]

Proposed to explain how the population of EAs changes in steps

Study the change of m(H, t)

the number of individuals belonging to H in the population at time t

Consider simple GA (SGA)

Representation	Binary representation
Recombination	One-point crossover
Mutation	Bit-wise mutation
Parent selection	Fitness proportional selection
Survivor selection	Generational

- 1. with prob. p_c , apply one-point crossover, otherwise copy them
- 2. for each resulting solution, apply bit-wise mutation



Schema theorem [Holland, 1975]

Proposed to explain how the population of EAs changes in steps

Study the change of m(H, t) of SGA

the probability of not disrupting *H* by bit-wise mutation

$$E[m(H,t+1)] \ge m(H,t) \cdot \left[\frac{\overline{f_H}}{\overline{f}} \cdot \left(1 - \left(p_c \cdot \frac{d(H)}{n-1}\right)\right) \cdot \left(1 - p_m\right)^{o(H)}\right]$$

the average fitness of individuals belonging to *H* in the population

the average fitness of individuals in the population

the probability of not disrupting *H* by one-point crossover



Schema theorem [Holland, 1975]

Proposed to explain how the population of EAs changes in steps

Study the change of m(H, t) of SGA

$$E[m(H,t+1)] \ge m(H,t) \cdot \frac{\overline{f_H}}{\overline{f}} \cdot \left(1 - \left(p_c \cdot \frac{d(H)}{n-1}\right)\right) \cdot (1 - p_m)^{o(H)}$$

Low-order and short schemata of above-average fitness will increase their instances from generation to generation

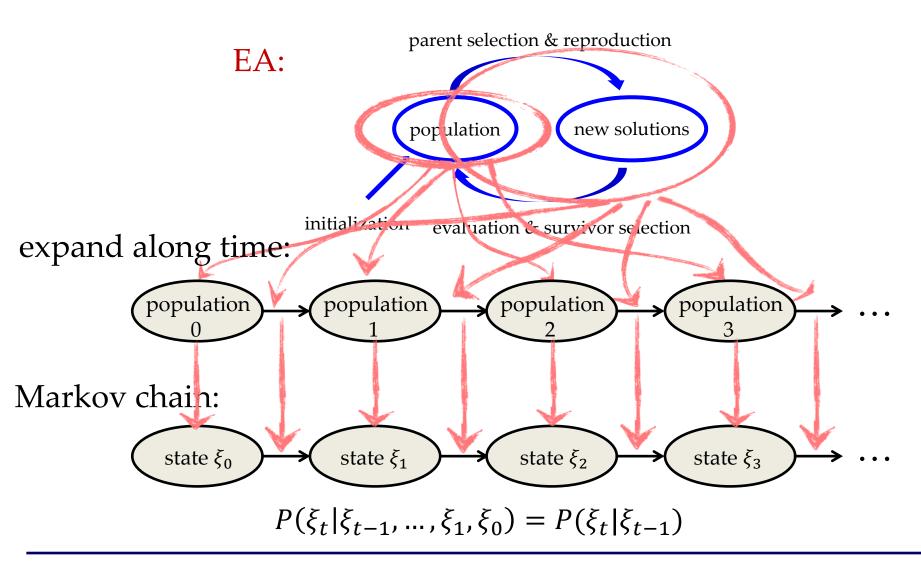
- Critiqued from several directions, and even wrong
- Cannot explain the global performance of EAs

Optimization-oriented theories

As an optimization algorithm, we concern:

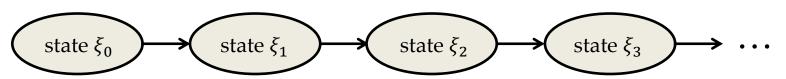
- does an EA converge?
- how fast an EA converges?
- •

Markov chain modeling



Markov chain modeling

Markov chain: $P(\xi_t | \xi_{t-1}, ..., \xi_1, \xi_0) = P(\xi_t | \xi_{t-1})$

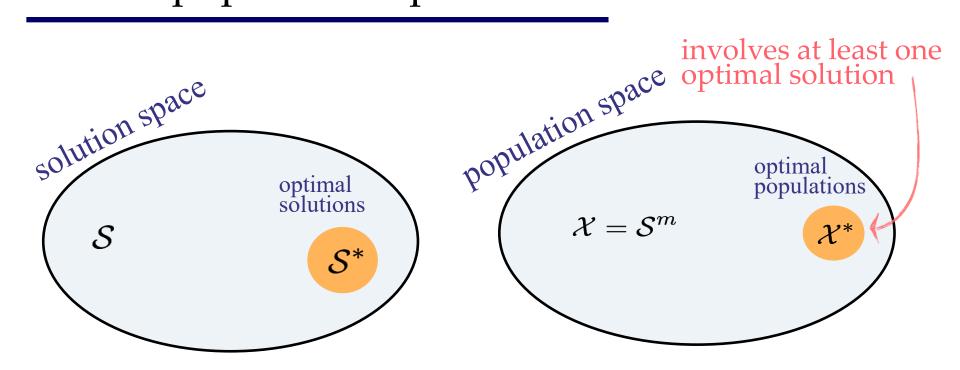


population space optimal solution solution space optimal solutions $\mathcal{X} = \mathcal{S}^m$ \mathcal{S}^*

involves at least one

 \mathcal{X}^*

Size of population space



What is the size of population space?

$$\binom{|\mathcal{S}|+m-1}{m}$$

Convergence

Does an EA converge to the optimal solutions?

 $\lim_{t \to +\infty} P(\xi_t \in \mathcal{X}^*) = 1$

An EA that

converges to the optimal solutions

[Rudolph, 1998]

1. uses global operators

$$\Rightarrow \forall x: P(\xi_{t+1} \in \mathcal{X}^* \mid \xi_t = x) > 0$$

2. preserves the best solution

$$P(\exists t : \xi_t \in \mathcal{X}^*) = 1 - \prod_{t=0}^{+\infty} P(\xi_t \notin \mathcal{X}^*) = 1 \iff \prod_{t=0}^{+\infty} P(\xi_t \notin \mathcal{X}^*) = 0$$

But life is limited! How fast does it converge?

Running time complexity

Convergence analysis

$$\lim_{t\to+\infty} P(\xi_t\in\mathcal{X}^*)=1\ ?$$

Running time analysis

$$\tau = \min \{ t \ge 0 \mid \xi_t \in \mathcal{X}^* \}$$

The leading theoretical aspect

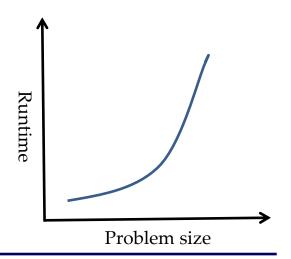
[Auger & Doerr, 2011; Neumann & Witt, 2012]

The number of iterations until finding an optimal or approximate solution for the first time

Running time complexity

- The number of iterations × the number of fitness evaluations in each iteration
- Usually grows with the problem size and expressed in asymptotic notations

e.g., (1+1)-EA solving LeadingOnes: $O(n^2)$



Running time complexity

Convergence analysis

$$\lim_{t\to+\infty} P(\xi_t \in \mathcal{X}^*) = 1$$
?

Running time analysis

$$\tau = \min \{ t \ge 0 \mid \xi_t \in \mathcal{X}^* \}$$

The leading theoretical aspect

[Auger & Doerr, 2011; Neumann & Witt, 2012]

The number of iterations until finding an optimal or approximate solution for the first time

A quick guide to asymptotic notations:

Let g and f be two functions defined on the real numbers.

- $g \in O(f)$: $\exists M > 0$ such that $g(x) \leq M \cdot f(x)$ for all sufficiently large x
- $g \in \Omega(f)$: $f \in O(g)$
- $g \in \Theta(f)$: $g \in O(f)$ and $g \in \Omega(f)$

$$g \in O(f) \to g \le f$$

$$g \in \Omega(f) \to g \ge f$$

$$g \in \Theta(f) \to g = f$$

Running time complexity

Convergence analysis

$$\lim_{t\to+\infty} P(\xi_t\in\mathcal{X}^*)=1\ ?$$

Running time analysis

$$\tau = \min \{ t \ge 0 \mid \xi_t \in \mathcal{X}^* \}$$

The leading theoretical aspect

[Auger & Doerr, 2011; Neumann & Witt, 2012]

The number of iterations until finding an optimal or approximate solution for the first time

EAs are randomized algorithms

- They do not perform the same operations even if the input is the same
- They do not output the same result if run twice!

 τ is a random variable. We are interested in:

- $E[\tau]$
- $P(\tau \leq T)$

Expectation

[Expectation] The expectation of a discrete random variable *X* is

$$E[X] = \sum_{i} i \cdot P(X = i)$$

where the sum is over all values in the range of *X*.

[Binomial Random Variable] A binomial random variable $X \sim B(n, p)$ with parameters n and p represents the number of successes in n independent experiments each of which succeeds with probability p.

$$P(X=i) = \binom{n}{i} p^{i} (1-p)^{n-i} \qquad E[X] = np$$

Expectation

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$$E[X] = \sum_{i} i \cdot P(X = i)$$

where the sum is over all values in the range of *X*.

[Geometric Random Variable] A geometric random variable X with parameter p represents the number of trials until the first success, where each trial succeeds with probability p.

$$P(X = i) = (1 - p)^{i-1}p$$
 $E[X] = 1/p$

Properties of expectation

[Law of Total Probability] For disjoint $B_1, B_2, ..., B_n$ that $\bigcup_{i=1}^n B_i = \Omega$,

$$P(A) = \sum_{i} P(A \wedge B_i) = \sum_{i} P(A \mid B_i) P(B_i)$$

[Law of Total Expectation] For disjoint $B_1, B_2, ..., B_n$ that $\bigcup_{i=1}^n B_i = \Omega$,

$$E[X] = \sum_{i} E[X \mid B_{i}]P(B_{i})$$

[Linearity of Expectation] For any collection of discrete random variables $X_1, X_2, ..., X_n$ with finite expectations,

$$E\left[\sum_{i=1}^{n} X_i\right] = \sum_{i=1}^{n} E\left[X_i\right]$$

How to calculate the expectation

Two common ways of calculating E[X]:

• Let
$$X = X_1 + X_2 + \dots + X_n$$
, then $E[X] = \sum_{i=1}^n E[X_i]$

• $E[X] = E[E[X \mid Y]]$

Example: [Binomial Random Variable] A binomial random variable $X \sim B(n, p)$ with parameters n and p represents the number of successes in n independent experiments each of which succeeds with probability p.

$$P(X=i) = \binom{n}{i} p^{i} (1-p)^{n-i} \qquad E[X] = np$$

Tail inequalities

[Markov's inequality] Let X be a random variable taking only non-negative values, and E[X] its expectation. For any t > 0,

$$P(X \ge t) \le E[X]/t$$

[Chernoff bounds] Let $X_1, X_2, ..., X_n$ be independent Poisson trials, and $X = \sum_{i=1}^{n} X_i$. For any $\delta > 0$,

$$P(X \ge (1+\delta)E[X]) \le \left(\frac{e^{\delta}}{(1+\delta)^{1+\delta}}\right)^{E[X]}$$
$$P(X \le (1-\delta)E[X]) \le \left(\frac{e^{-\delta}}{(1-\delta)^{1-\delta}}\right)^{E[X]}$$

For a uniformly randomly sampled Boolean vector $\mathbf{x} \in \{0,1\}^n$, what is the probability of having no more than 2n/3 1-bits?

Tail inequalities

[Markov's inequality] Let X be a random variable taking only non-negative values, and E[X] its expectation. For any t > 0,

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Union bound

[Union bound] For any finite or countably finite sequence of events E_1 , E_2 , ..., it holds that

$$P\left(\bigcup_{i\geq 1} E_i\right) \leq \sum_{i\geq 1} P(E_i)$$

Bit-wise mutation

For a Boolean vector $\mathbf{x} \in \{0,1\}^n$ with i 0-bits, after flipping each bit with prob. 1/n independently, what is the upper bound on the probability of decreasing the number of 0-bits by j?

$$E_i$$
: j specific 0-bits of x are flipped

$$\leq P\left(\bigcup_{i>1}E_i\right) \leq \binom{i}{j}\left(\frac{1}{n}\right)^j \longrightarrow P(E_i)$$

Example of running time analysis

An extremely simplified EA missing some features of *real* EAs



no population

(1+1)-EA

1: $s \leftarrow$ a randomly drawn solution from \mathcal{X}

2: **for** t=1,2,... **do**

3: $s' \leftarrow mutate(s)$

4: if $f(s') \ge f(s)$ then

5: $s \leftarrow s'$

6: end if

7: **terminate** if meets a stopping criterion

8: end for



randomly choose one bit and change its value

bit-wise mutation

flip each bit with prob. 1/n independently



for maximization, allow neutral changes

find an optimal solution

Example of running time analysis

Probing problem OneMax:

$$\underset{x \in \{0,1\}^n}{\text{arg max}} \sum_{i=1}^n x_i$$

count the number of 1 bits

fitness:
$$f(x) = \sum_{i=1}^{n} x_i$$

EAs do not have the knowledge of the problems

only able to call $f(\mathbf{x})$ no difference with any other function $f:\{0,1\}^n \to \mathbb{R}$

OneMax:
$$f(x) = \sum_{i=1}^{\infty} x_i$$

the solutions with the same number of 1-bits share the same f value

solutions solutions with 0 1-bits with 1 1-bits with 2 1-bits with n 1-bits S_0 S_1 S_2 S_2 S_n S_n

OneMax:
$$f(x) = \sum_{i=1}^{\infty} x_i$$

the solutions with the same number of 1-bits share the same f value

solutions solutions solutions with 0 1-bits with 1 1-bits with 2 1-bits

solutions with n 1-bits

$$(S_n) = S^*$$

OneMax:
$$f(x) = \sum_{i=1}^{n} x_i$$

the solutions with the same number of 1-bits share the same f value

solutions solutions s

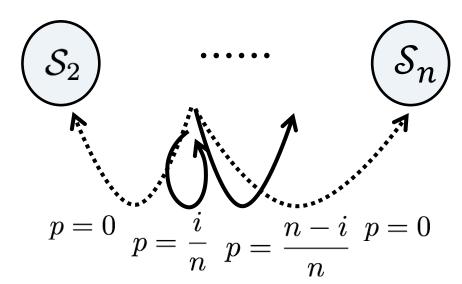
with 0 1-bits with 1 1-bits with 2 1-bits

solutions with 2 1-bits

solutions with *n* 1-bits

$$(S_0)$$

 (S_1)

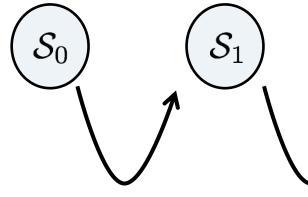


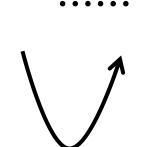
solutions with 0 1-bits with 1 1-bits with 2 1-bits

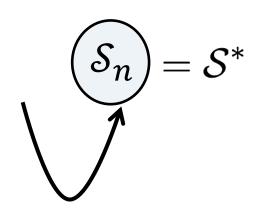
solutions

solutions

solutions with n 1-bits







probability of transition

$$p = 1$$

$$p = \frac{n-1}{n}$$

$$p = \frac{n - r}{n}$$

$$p = \frac{1}{n}$$

expected #iterations until the transition happens

$$\frac{n}{n-1}$$

$$\frac{n}{n-i}$$

$$\frac{n}{1}$$

OneMax:
$$f(x) = \sum_{i=1}^{n} x_i$$

expected #iterations until the transition happens

$$1 \qquad \frac{n}{n-1}$$

$$\sum_{i=1}^{n} \frac{n}{i} = nH_n \sim n \ln n$$

expected running time upper bound $O(n \log n)$

OneMax:
$$f(x) = \sum_{i=1}^{n} x_i$$

Let τ denote the running time, and $|x|_0$ denote the number of 0-bits of the initial solution

Law of total expectation

$$E[\tau] = \sum_{i=0}^{n} E[\tau \mid |\mathbf{x}|_{0} = i] \cdot P(|\mathbf{x}|_{0} = i)$$

$$\geq \sum_{i=n/3}^{n} E[\tau \mid |\mathbf{x}|_{0} = i] \cdot P(|\mathbf{x}|_{0} = i)$$

$$\geq E[\tau \mid |\mathbf{x}|_{0} = n/3] \cdot P(|\mathbf{x}|_{0} \geq n/3)$$

$$\geq E[\tau \mid |\mathbf{x}|_{0} = n/3] \cdot 1/4$$

$$P(|\mathbf{x}|_{1} \leq 2n/3) \geq 1/4 \text{ by Markov's inequality}$$

OneMax:
$$f(x) = \sum_{i=1}^{n} x_i$$

$$E[\tau] \ge E[\tau \mid |x|_0 = n/3]) 1/4$$

In $(n-1) \ln n$ iterations, at least one of these n/3 0-bits is never flipped



The optimum is not found



$$\tau > (n-1) \ln n$$

the probability is lower bounded by

$$E[\tau] \ge E[\tau \mid |x|_0 = n/3]) 1/4$$

 $\ge (n-1) \ln n \ P(\tau > (n-1) \ln n) \cdot 1/4$
lower bound

In $(n-1) \ln n$ iterations, at least one of these n/3 0-bits is never flipped

- 1 1/n: a specific 0-bit is not flipped
- $(1-1/n)^t$: a specific 0-bit is never flipped in t iterations
- $1 (1 1/n)^t$: a specific 0-bit is flipped at least once in t iterations
- $(1-(1-1/n)^t)^{n/3}$: any of these n/3 0-bits is flipped at least once in t iterations

$$(1+1)\text{-EA with} \\ \text{bit-wise mutation} \\ E[\tau] \ge \boxed{E[\tau \mid |\mathbf{x}|_0 = n/3]} \quad 1/4 \\ \ge (n-1)\ln n \quad \boxed{P(\tau > (n-1)\ln n)} \quad 1/4 \\ \ge (n-1)\ln n \cdot \left(1 - (1-(1-1/n)^{(n-1)\ln n})^{n/3}\right) \cdot 1/4 \\ \ge 1/e \quad \ge (n-1)\ln n \cdot \left(1 - (1-e^{-\ln n})^{n/3}\right) \cdot 1/4 \\ \le 1/e \quad \ge (n-1)\ln n \cdot \left(1 - (1-1/n)^{n/3}\right) \cdot 1/4 \\ \le 1/e \quad \ge (n-1)\ln n \cdot \left(1 - (1-1/n)^{n/3}\right) \cdot 1/4 \\ \le 1/e \quad \ge (n-1)\ln n \cdot \left(1 - e^{-1/3}\right) \cdot 1/4 \in \Omega(n\log n)$$

Example of running time analysis

For (1+1)-EA solving OneMax
$$f(x) = \sum_{i=1}^{n} x_i$$

If using one-bit mutation,

expected running time upper bound $O(n \log n)$

If using bit-wise mutation,

expected running time lower bound $\Omega(n \log n)$

Not asymptotically faster

Running time analysis tools

When facing new situations, analyses starting from scratch are quite difficult

We need general running time analysis tools to guide the analysis

- Fitness level
- Drift analysis
- Switch analysis

Summary

- Schema theorem
- Markov chain modeling
- Convergence
- Running time complexity
- Expectation and tail inequalities
- Example of running time analysis

References

- A. E. Eiben and J. E. Smith. Introduction to Evolutionary Computing. Chapter 16.
- K. A. De Jong. Evolutionary Computation A Unified Approach. Chapter 6.
- G. Rudolph. Finite Markov chain results in evolutionary computation: A tour d'horizon. Fundamenta Informaticae, 1998, 35(1-4): 67-89.