### Last class

- Fitness level
  - Original fitness level
  - Refined fitness level
- Drift analysis
  - Additive drift
  - Multiplicative drift
  - Negative drift
- Switch analysis
- Results of running time analysis





# Heuristic Search and Evolutionary Algorithms Lecture 11: Evolutionary Algorithms for Multi-objective Optimization Chao Qian (钱超)

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$$max_{x \in \mathcal{X}} \left( f_1(x), f_2(x), \dots, f_m(x) \right)$$

feasible solution space, consisting of all solutions satisfying the constraints

• *x* weakly dominates *y*, denoted as  $x \ge y$ , if

 $\forall i \in \{1, 2, \dots, m\}: f_i(x) \ge f_i(y)$ 

- x dominates y, denoted as x > y, if  $\forall i \in \{1, 2, ..., m\}$ :  $f_i(x) \ge f_i(y)$  and  $\exists i \in \{1, 2, ..., m\}$ :  $f_i(x) > f_i(y)$
- *x* is incomparable with *y*, if neither  $x \ge y$  nor  $y \ge x$

$$max_{x\in\mathcal{X}} \left( f_1(x), f_2(x), \dots, f_m(x) \right)$$



$$max_{x \in \mathcal{X}} \left( f_1(x), f_2(x), \dots, f_m(x) \right)$$

A solution is **Pareto optimal** if no other solution dominates it

The collection of objective vectors of all Pareto optimal solutions is called the Pareto front

The goal of multi-objective optimization is to find a set of solutions whose objective vectors cover the Pareto front

$$max_{x \in \mathcal{X}} \left( f_1(x), f_2(x), \dots, f_m(x) \right)$$

However, the size of Pareto front can be exponentially large

In practice, we want to find a set of solutions that is good in terms of:

- Convergence (to the Pareto front)
- **Diversity** (along the Pareto front)

# Multi-objective optimization

Multi-objective optimization: optimize multiple objectives (which are usually conflicting) simultaneously

$$max_{x\in\mathcal{X}} \left( f_1(x), f_2(x), \dots, f_m(x) \right)$$



**Bi-objective** minimization

## Example of multi-objective optimization



## Example of multi-objective optimization



- Accuracy: the higher the better
- Complexity: the smaller the better

### Example of multi-objective optimization



### Multi-objective evolutionary algorithms

- EAs for multi-objective optimization are usually called Multi-Objective Evolutionary Algorithms (MOEAs)
- Almost all types of EAs have their multi-objective version
- Become a prosperous sub-area of EAs since 1985



# Variants of MOEA

• Pareto dominance based: NSGA-II, SPEA-II, ...



K. Deb, A. Pratap, S. Agarwal and T. Meyarivan. A fast and elitist multiobjective genetic algorithm: NSGA-II. *IEEE Transactions on Evolutionary Computation*, 2002. (Google scholar引用: 43345)

Performance indicator based: SMS-EMOA, HyPE, ....



<u>N. Beume</u>, B. Naujoks and M. Emmerich. SMS-EMOA: Multiobjective selection based on dominated hypervolume. *European Journal of Operational Research*, 2007. (Google scholar引用: 1806)

• Decomposition based: MOEA/D, ....



Q. Zhang and H. Li. MOEA/D: A multiobjective evolutionary algorithm based on decomposition. *IEEE Transactions on Evolutionary Computation*, 2007. (Google scholar引用: 7097)

- NSGA-II: probably the most influential work on MOEAs
- Majority of papers on MOEAs emerge after this seminal work, and adopt similar framework as NSGA-II



### Framework of NSGA-II



### Non-dominated sorting

```
Input: P = \{x_1, x_2, ..., x_{\mu}\};
Initialize k = 1, Q = \emptyset
                          many redundant
While P \neq \emptyset Do
                          comparisons
   for each x_i \in P
      if x_i is not dominated by any x_i in P
         \operatorname{ran}k(x_i) = k;
         Q = Q \cup \{x_i\}
       end if
   end for
   P = P/Q;
   k = k + 1
End While
```



**Bi-objective** minimization

```
i = 1;
Fast non-dominated sorting
                                                        while F_i \neq \emptyset store the solutions
 for each x \in P
                   \longrightarrow the set of solutions
                                                                    with the next rank
                                                          Q = \emptyset;
   S_x = \emptyset; n_x = 0;
                           dominated by x
                                                           for each x \in F_i
    for each y \in P the number of solutions
                                                                               As x is
                                                             for each y \in S_x excluded now,
                           dominating x
       if x \succ y then
                                                                  n_y = n_y - 1 decrease n_y
          S_{\gamma} = S_{\gamma} \cup \{y\}
                           if x dominates y, add y to S_x
                                                                  if n_{\nu} = 0 then
       else if x \prec y then
                                                                     rank(y) = i + 1;
          n_x = n_x + 1
                          if y dominates x, increase n_x
                                                                                    y has the
                                                                     Q = Q \cup \{y\}
       end if
                                                                                     next rank
                                                                  end if
    end for
                                                             end for
   if n_x = 0 then x is ranked by 1
                                                           end for
     rank(x)=1; F_1 = F_1 \cup \{x\}
                                                           i = i + 1; F_i = Q
    end if
                                                        end while
 end for
```





**Bi-objective minimization** 

For the solutions with the same rank, which one is better?

### Crowding distance assignment $f_2$ Input: $Q = \{x_1, x_2, ..., x_l\}$ with the same rank; for each *j*, set $Q[j]_{distance} = 0$ $f_1(Q[j+1]) - f_1(Q[j-1])$ for each objective $f_i$ the *j*-th solution in Q $f_2(Q[j+1])$ $Q = sort(Q, f_i)$ ; in ascending order $-f_2(Q[j-1])$ $Q[1]_{distance} = \infty;$ boundary solutions $Q[l]_{distance} = \infty;$ for j = 2 to l - 1 $Q[j]_{distance} = Q[j]_{distance} + \underbrace{f_i(Q[j+1]) - f_i(Q[j-1])}_{f_i.max - f_i.min}$ normalization end for Prefer end for Crowding distance: the larger the better diversity

Crowded comparison employed by NSGA-II

Given a set *P* of solutions, for any two solutions *x*, *y* in *P*, *x* is better than *y*, if

- $\operatorname{rank}(x) < \operatorname{rank}(y)$
- or rank(x) = rank(y) but distance(x) > distance(y)



### Framework of NSGA-II





### N + N survivor selection



**NSGA-II:** population size 40, SBX crossover with  $\eta = 20$ , crossover probability 0.9, polynomial mutation with  $\eta = 20$ , mutation probability 1/n

DTLZ1:

$$\begin{array}{l} \text{Minimize } f_1(\mathbf{x}) = \frac{1}{2} x_1 x_2 \cdots x_{M-1} (1 + g(\mathbf{x}_M)), \\ \text{Minimize } f_2(\mathbf{x}) = \frac{1}{2} x_1 x_2 \cdots (1 - x_{M-1}) (1 + g(\mathbf{x}_M)), \\ \vdots \\ \text{Minimize } f_{M-1}(\mathbf{x}) = \frac{1}{2} x_1 (1 - x_2) (1 + g(\mathbf{x}_M)), \\ \text{Minimize } f_M(\mathbf{x}) = \frac{1}{2} (1 - x_1) (1 + g(\mathbf{x}_M)), \\ \text{subject to } 0 \le x_i \le 1, \quad \text{for } i = 1, 2, \dots, n. \end{array}$$
 the vector containing the last  $n - M + 1$  variables  $g(\mathbf{x}_M) = 100 \left[ \mathbf{x}_M + \sum_{x_i \in \mathbf{X}_M} (x_i - 0.5)^2 - \cos(20\pi(x_i - 0.5)) \right]$ 

### For NSGA-II solving DTLZ1 with M = 2 and n = 512



**NSGA-II**: population size 40, SBX crossover with  $\eta = 20$ , crossover probability 0.9, polynomial mutation with  $\eta = 20$ , mutation probability 1/n

DTLZ3:

 $\begin{array}{l} \text{Min. } f_1(\mathbf{x}) = (1 + g(\mathbf{x}_M)) \cos(x_1 \pi/2) \cdots \cos(x_{M-2} \pi/2) \cos(x_{M-1} \pi/2), \\ \text{Min. } f_2(\mathbf{x}) = (1 + g(\mathbf{x}_M)) \cos(x_1 \pi/2) \cdots \cos(x_{M-2} \pi/2) \sin(x_{M-1} \pi/2), \\ \text{Min. } f_3(\mathbf{x}) = (1 + g(\mathbf{x}_M)) \cos(x_1 \pi/2), \\ \vdots & \vdots \\ \text{Min. } f_M(\mathbf{x}) = (1 + g(\mathbf{x}_M)) \sin(x_1 \pi/2), \\ \text{with } g(\mathbf{x}_M) = 100 \left[ |\mathbf{x}_M| + \sum_{x_i \in \mathbf{X}_M} (x_i - 0.5)^2 - \cos(20\pi(x_i - 0.5)) \right], \\ 0 \le x_i \le 1, \quad \text{for } i = 1, 2, \dots, n. \\ \end{array}$   $\begin{array}{l} \text{the vector} \\ \text{containing the last} \\ n - M + 1 \text{ variables} \end{array}$ 

### For NSGA-II solving DTLZ3 with M = 2 and n = 512



**NSGA-II**: population size 40, SBX crossover with  $\eta = 20$ , crossover probability 0.9, polynomial mutation with  $\eta = 20$ , mutation probability 1/n



### For NSGA-II solving WFG1 with M = 2 and n = 512





• Similar to NSGA-II, except the goodness measure for the solutions with the same rank

• Make use of quality indicators to measure the goodness

• Typically, the goodness of a solution is defined based on how much the quality indicator decreases if the solution is removed

Quality indicator: g(P), where P is a set of solutions



 $\Delta(x) = g(P) - g(P \setminus \{x\})$ 

Quality indicator loss: the larger the better

### SMS-EMOA

The quality indicator g(P) should be coherent with "convergence" and "diversity"

E.g., the hypervolume indicator





• The basic SMS-EMOA generates only one offspring solution



# SMS-EMOA: application illustration

SMS-EMOA: population size 40, SBX crossover with  $\eta = 20$ , crossover probability 0.9, polynomial mutation with  $\eta = 20$ , mutation probability 1/n

### DTLZ1:

Minimize 
$$f_1(\mathbf{x}) = \frac{1}{2}x_1x_2\cdots x_{M-1}(1+g(\mathbf{x}_M)),$$
  
Minimize  $f_2(\mathbf{x}) = \frac{1}{2}x_1x_2\cdots (1-x_{M-1})(1+g(\mathbf{x}_M)),$   
 $\vdots$   
Minimize  $f_{M-1}(\mathbf{x}) = \frac{1}{2}x_1(1-x_2)(1+g(\mathbf{x}_M)),$   
Minimize  $f_M(\mathbf{x}) = \frac{1}{2}(1-x_1)(1+g(\mathbf{x}_M)),$   
subject to  $0 \le x_i \le 1$ , for  $i = 1, 2, ..., n$ .

### DTLZ3:

 $\begin{array}{l} \text{Min. } f_1(\mathbf{x}) &= (1 + g(\mathbf{x}_M)) \cos(x_1 \pi/2) \cdots \cos(x_{M-2} \pi/2) \cos(x_{M-1} \pi/2), \\ \text{Min. } f_2(\mathbf{x}) &= (1 + g(\mathbf{x}_M)) \cos(x_1 \pi/2) \cdots \cos(x_{M-2} \pi/2) \sin(x_{M-1} \pi/2), \\ \text{Min. } f_3(\mathbf{x}) &= (1 + g(\mathbf{x}_M)) \cos(x_1 \pi/2) \cdots \sin(x_{M-2} \pi/2), \\ \vdots & \vdots \\ \text{Min. } f_M(\mathbf{x}) &= (1 + g(\mathbf{x}_M)) \sin(x_1 \pi/2), \\ \text{with } g(\mathbf{x}_M) &= 100 \left[ |\mathbf{x}_M| + \sum_{x_i \in \mathbf{X}_M} (x_i - 0.5)^2 - \cos(20\pi(x_i - 0.5)) \right], \\ &\quad 0 \leq x_i \leq 1, \quad \text{for } i = 1, 2, \dots, n. \end{array}$ 

WFG: Given  

$$\mathbf{z} = \{z_1, \dots, z_k, z_{k+1}, \dots, z_n\}$$
Minimise  

$$f_{m=1:M}(\mathbf{x}) = x_M + S_m h_m(x_1, \dots, x_{M-1})$$
where  

$$\mathbf{x} = \{x_1, \dots, x_M\} = \{\max(t_M^p, A_1)(t_1^p - 0.5) + 0.5, \dots, \\ \max(t_M^p, A_{M-1})(t_{M-1}^p - 0.5) + 0.5, t_M^p\}$$

$$\mathbf{t}^p = \{t_1^p, \dots, t_M^p\} \leftarrow [\mathbf{t}^{p-1} \leftarrow [\dots \leftarrow [\mathbf{t}^1 \leftarrow [\mathbf{z}_{[0,1]}]$$

$$\mathbf{z}_{[0,1]} = \{z_{1,[0,1]}, \dots, z_{n,[0,1]}\} = \{z_1/z_{1,\max}, \dots, z_n/z_{n,\max}\}$$

# SMS-EMOA: application illustration

### For SMS-EMOA solving DTLZ1 with M = 2 and n = 512



### SMS-EMOA vs. NSGA-II



# SMS-EMOA: application illustration

### For SMS-EMOA solving DTLZ3 with M = 2 and n = 512



### SMS-EMOA vs. NSGA-II



## SMS-EMOA: application illustration

### For SMS-EMOA solving WFG1 with M = 2 and n = 512



after 10<sup>6</sup> fitness evaluations after 10<sup>7</sup> fitness evaluations

### SMS-EMOA vs. NSGA-II





 MOEA based on Decomposition (MOEA/D): old things become new again



• Weighted sum approach





An optimal solution for  $g^{ws}(x \mid \lambda)$ must be Pareto optimal

• Weighted sum approach



• Tchbycheff approach

$$min_{x \in \mathcal{X}} \left( f_1(x), f_2(x) \right)$$

 $min_{x \in \mathcal{X}} g^{t}(x \mid \boldsymbol{\lambda}, \boldsymbol{z}^{*}) = \max\{\lambda_{1} \mid f_{1}(x) - z_{1}^{*} \mid, \lambda_{2} \mid f_{2}(x) - z_{2}^{*} \mid\}$ where  $\lambda_{1} + \lambda_{2} = 1, \lambda_{1}, \lambda_{2} \ge 0$ 

 $\mathbf{z}^*$  is an Utopian point, where  $z_1^* < \min\{f_1(x)\}$  and  $z_2^* < \min\{f_2(x)\}$ 

For any Pareto optimal solution  $x^*$ , there is a  $\lambda$  such that  $x^*$  is optimal to  $g^t(x \mid \lambda, z^*)$ 

• Weighted  $L_p$  approach

$$min_{x \in \mathcal{X}} \left( f_1(x), f_2(x) \right)$$

 $min_{x \in \mathcal{X}} \ g^{t}(x \mid \lambda, \mathbf{z}^{*}) = \|(\lambda_{1} \mid f_{1}(x) - z_{1}^{*} \mid, \lambda_{2} \mid f_{2}(x) - z_{2}^{*} \mid)\|_{p}$ where  $\lambda_{1} + \lambda_{2} = 1, \lambda_{1}, \lambda_{2} \ge 0$ 

- $\mathbf{z}^*$  is an Utopian point, where  $z_1^* < \min\{f_1(x)\}$  and  $z_2^* < \min\{f_2(x)\}$
- p = 1: Weighted sum approach
- $p = \infty$ : Tchbycheff approach

## MOEA/D - optimization



For each sub-problem, one needs to find neighboring subproblems, e.g., sub-problems with close weight vectors

## MOEA/D - optimization



For optimizing each sub-problem in each iteration

- 1. Mating selection: obtain the current solutions of some neighbours
- **2. Reproduction:** generate a new solution by applying reproduction operators on its own solution and borrowed solutions
- 3. Replacement:
  - 3.1 replace its old solution by the new one if the new one is better
  - 3.2 pass the new solution on to some of its neighbours, and update its neighbor's solutions when better

MOEA/D: Tchbycheff decomposition approach, population size 40, SBX crossover with  $\eta = 20$ , crossover probability 0.9, polynomial mutation with  $\eta = 20$ , mutation probability 1/n

### DTLZ1:

Minimize 
$$f_1(\mathbf{x}) = \frac{1}{2}x_1x_2\cdots x_{M-1}(1+g(\mathbf{x}_M)),$$
  
Minimize  $f_2(\mathbf{x}) = \frac{1}{2}x_1x_2\cdots (1-x_{M-1})(1+g(\mathbf{x}_M)),$   
 $\vdots$ :  
Minimize  $f_{M-1}(\mathbf{x}) = \frac{1}{2}x_1(1-x_2)(1+g(\mathbf{x}_M)),$   
Minimize  $f_M(\mathbf{x}) = \frac{1}{2}(1-x_1)(1+g(\mathbf{x}_M)),$   
subject to  $0 \le x_i \le 1$ , for  $i = 1, 2, ..., n$ .

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$$\mathbf{t}^p = \{t_1^p, \dots, t_M^p\} \leftarrow [\mathbf{t}^{p-1} \leftarrow [\dots \leftarrow [\mathbf{t}^1 \leftarrow [\mathbf{z}_{[0,1]}], \dots, z_{n,[0,1]}] = \{z_1/z_{1,\max}, \dots, z_n/z_{n,\max}\}$$

### For MOEA/D solving DTLZ1 with M = 2 and n = 512



### For MOEA/D solving DTLZ3 with M = 2 and n = 512



### For MOEA/D solving WFG1 with M = 2 and n = 512



# Comparison on DTLZ1



The population after 10<sup>6</sup> fitness evaluations

# Comparison on DTLZ3



The population after 10<sup>6</sup> fitness evaluations

# Comparison on WFG1



The population after 10<sup>6</sup> fitness evaluations



- Multi-objective optimization
- NSGA-II
  SMS-EMOA
  MOEA/D
  Popular variants of MOEA

- A. E. Eiben and J. E. Smith. Introduction to Evolutionary Computing. Chapter 12.
- K. Deb. Multi-objective optimization using evolutionary algorithms. John Wiley & Sons, 2001.
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