

- Multi-objective optimization
- NSGA-II
 SMS-EMOA
 MOEA/D

 Popular variants

 of MOEA





Heuristic Search and Evolutionary Algorithms

Lecture 12: Evolutionary Algorithms for Constrained Optimization

Chao Qian (钱超)

Associate Professor, Nanjing University, China

Email: qianc@nju.edu.cn Homepage: http://www.lamda.nju.edu.cn/qianc/

Constrained optimization

General formulation:



A solution is **(in)feasible** if it does (not) satisfy the constraints

The goal: find a feasible solution minimizing the objective *f*

Knapsack problem: given *n* items, each with a weight w_i and a value v_i , to select a subset of items maximizing the sum of values while keeping the summed weights within some capacity W_{max}



$$\arg \max_{x \in \{0,1\}^n} \sum_{i=1}^n v_i x_i \quad s. t. \sum_{i=1}^n w_i x_i \le W_{max}$$
$$x_i = 1: \text{ the } i\text{-th item is included}$$
objective function constraint

Example – minimum spanning tree

Minimum spanning tree problem: given an undirected connected graph G = (V, E) on n vertices and m edges with positive weights $w: E \rightarrow R^+$, to find a connected subgraph $E' \subseteq E$ with the minimum weight



arg
$$min_{x \in \{0,1\}^m} \sum_{i=1}^m w_i x_i$$
 s.t. $c(x) = 1$
objective function $x_i = 1$: the *i*-th edge is selected constraint $c(x)$: the number of connected components

Example – traveling salesman

Traveling salesman problem: given an undirected connected graph G = (V, E) on *n* vertices and *m* edges with positive weights $w: E \rightarrow R^+$, to find a Hamilton cycle with the minimum weight





How to deal with constraints when EAs are used for constrained optimization?

The optimization problems in real-world applications often come with constraints

The final output solution must satisfy the constraints

Common constraint handling strategies

- Penalty functions
- Stochastic ranking
- Repair functions
- Restricting search to the feasible region
- Decoder functions

Penalty functions: add penalties on the fitness of infeasible solutions



Penalty functions: add penalties on the fitness of infeasible solutions



Requirement: the optimal solutions of the original and transformed problems should be consistent

• e.g., all λ_i are equal, and large enough: compare the constraint violation degrees first; if they are the same, compare the objective values f

Penalty functions

Minimum spanning tree problem:

given an undirected connected graph G = (V, E) on n vertices and m edges with positive weights $w: E \rightarrow \mathbb{R}^+$, to find a connected subgraph $E' \subseteq E$ with the minimum weight



$$\arg \min_{x \in \{0,1\}^m} \sum_{i=1}^m w_i x_i$$
 s.t. $c(x) = 1$



Penalty functions: add penalties on the fitness of infeasible solutions



How to set an appropriate value for λ ?

Stochastic ranking

Consider two solutions x_1 and x_2 satisfying

$$f(x_1) < f(x_2)$$
 and $\phi(x_1) > \phi(x_2)$

• λ is small: the comparison is based on the objective function

$$\lambda < \frac{f(x_2) - f(x_1)}{\phi(x_1) - \phi(x_2)} \Rightarrow f(x_1) + \lambda \phi(x_1) < f(x_2) + \lambda \phi(x_2)$$

• λ is large: the comparison is based on the penalty function

$$\lambda > \frac{f(x_2) - f(x_1)}{\phi(x_1) - \phi(x_2)} \Rightarrow f(x_1) + \lambda \phi(x_1) > f(x_2) + \lambda \phi(x_2)$$

The value of λ determines whether the comparison is based on the objective function or the penalty function

Stochastic ranking

Procedure for ranking λ solutions:

1:	$I_j = j, \forall j \in \{1, 2, \dots, \lambda\}$	┝→
2:	for $i = 1$ to N do	-
3:	for $j = 1$ to $\lambda - 1$ do	_
4:	sample $u \in U(0, 1)$	
5:	if $\phi(I_j) = \phi(I_{j+1}) = 0$ or $u < P_f$ then	
6:	$\mathbf{if} \ f(I_j) > f(I_{j+1}) \ \mathbf{then}$	_
7:	$swap(I_j, I_{j+1})$	k
8:	end if	· \
9:	else	*
10:	if $\phi(I_j) > \phi(I_{j+1})$ then	
11:	$swap(I_j, I_{j+1})$	
12:	end if	
13:	end if	
14:	end for	
15:	if no <i>swap</i> done then]
16:	break	
17:	end if]
18:	end for	

the initial ranking is generated at random

if both individuals are feasible, the comparison is based on the objective function with prob. 1; otherwise, the prob. is P_f

exchange the solutions in the j-th and (j + 1)-th positions

the procedure is terminated when no change in the rank ordering occurs within a complete loop **Repair functions:** repair infeasible solutions to feasible

Example - Knapsack: given *n* items, each with a weight w_i and a value v_i , to select a subset of items maximizing the sum of values while keeping the summed weights within some capacity W_{max}



 $\arg \max_{x \in \{0,1\}^n} \sum_{i=1}^n v_i x_i \quad \text{s.t.} \sum_{i=1}^n w_i x_i \le W_{max}$

 v_i : 4,2,6,10,4,3,7,2; w_i : 2,3,3,8,6,5,7,1; $W_{max} = 25$ infeasible 1 1 0 1 1 0 1 1 feasible 1 1 0 1 1 0 0 1

Repairing: scan from left to right, and keep the value 1 if the summed weight does not exceed *W*_{max} **Restricting search to the feasible region:** preserving feasibility by special initialization and reproduction

Example - traveling salesman: given an undirected connected graph G = (V, E) on n vertices and m edges with positive weights $w: E \rightarrow \mathbb{R}^+$, to find a Hamilton cycle with the minimum weight



 $\arg \min_x w(x)$ s.t. x is a Hamilton cycle

Integer vector representation: the order of visiting vertexes

Permutation is feasible

Initialize with permutation; Apply mutation and recombination operators for permutation representation **Decoder functions:** map each genotype to a feasible phenotype

Example - Knapsack: given *n* items, each with a weight w_i and a value v_i , to select a subset of items maximizing the sum of values while keeping the summed weights within some capacity W_{max}



 $\arg \max_{x \in \{0,1\}^n} \sum_{i=1}^n v_i x_i \quad \text{s.t. } \sum_{i=1}^n w_i x_i \le W_{max}$

 v_i : 4,2,6,10,4,3,7,2; w_i : 2,3,3,8,6,5,7,1; $W_{max} = 25$ genotype 1 1 0 1 0 1 1 phenotype 1 0 1 0 1 0

Decoding: scan from left to right, and keep the value 1 if the summed weight does not exceed *W*_{max}

The final output solution must satisfy the constraints

Common constraint handling strategies

- Penalty functions
- Stochastic ranking
- Repair functions
- Restricting search to the feasible region
- Decoder functions

Other effective constraint handling strategies?

(1+1)-EA for MST

Minimum spanning tree (MST):

- Given: an undirected connected graph G = (V, E) on n vertices and m edges with positive integer weights $w: E \to \mathbb{N}^+$
- The Goal: find a connected subgraph $E' \subseteq E$ with the minimum weight

Formulation: $\arg \min_{x \in \{0,1\}^m} \sum_{i=1}^m w_i x_i$ s.t. c(x) = 1

 $x \in \{0,1\}^m \leftrightarrow \text{a subgraph}$

 $x_i = 1$ means that edge e_i is selected

(1+1)-EA: Given a pseudo-Boolean function *f*:

1. $x \coloneqq$ randomly selected from $\{0,1\}^n$.

- 2. Repeat until some termination criterion is met
- 3. $x' \coloneqq$ flip each bit of x with probability 1/n.



Theorem. [Neumann & Wegener, TCS'07; Doerr et al., Algorithmica'12] The expected running time of the (1+1)-EA solving the MST problem is $O(m^2(\log n + \log w_{max}))$.

$$\arg\min_{\boldsymbol{x}\in\{0,1\}^m}\sum_{i=1}^m w_i x_i \quad s.t. \ c(\boldsymbol{x}) = 1$$

Bi-objective reformulation min $(c(\mathbf{x}), \sum_{i:x_i=1} w_i)$

Theorem. [Neumann & Wegener, Nature Computing'05] The expected running time of the GSEMO solving the MST problem is $O(mn (n + \log w_{max}))$.

Penalty functions: $O(m^2(\log n + \log w_{max}))$

Bi-objective reformulation: $O(mn(n + \log w_{max}))$

Bi-objective reformulation is better for dense graphs, e.g., $m \in O(n^2)$

7.

$$\arg\min_{\boldsymbol{x}\in\{0,1\}^m}\sum_{i=1}^m w_i x_i \quad s.t. \ c(\boldsymbol{x}) = 1$$

Bi-objective reformulation min $(c(\mathbf{x}), \sum_{i:x_i=1} w_i)$

GSEMO: Given a pseudo-Boolean function vector *f*:

Keep the non-dominated $x \coloneqq$ randomly selected from $\{0,1\}^n$. 1. solutions generated so-far

2.
$$P \coloneqq \{x\}$$
.

- Repeat until some termination criterion is met 3.
- Choose **x** from *P* uniformly at random. 4.

5.
$$x' \coloneqq \text{flip each bit of } x \text{ with probability } 1/n.$$

6. if
$$\nexists z \in P$$
 such that $z \prec x'$

$$P := (P - \{ z \in P \mid x' \leq z \}) \cup \{ x' \}.$$

Main idea:

(1) obtain the empty subgraph 0^n

(2) obtain a minimum spanning tree

The analysis of phase (1): $\min(c(\mathbf{x}), w(\mathbf{x}) = \sum_{i:x_i=1} w_i)$



Main idea:

- (1) obtain the empty subgraph 0^n
- (2) obtain a minimum spanning tree

The analysis of phase (1): $\min(c(\mathbf{x}), w(\mathbf{x}) = \sum_{i:x_i=1} w_i)$

Using multiplicative drift analysis:

- design the distance function: $V(P) = min \{w(x) \mid x \in P\}$
- analyze the expected drift:

$$\begin{split} \mathsf{E}[V(\xi_t) - V(\xi_{t+1}) \mid \xi_t = P] &\geq \frac{1}{n} \cdot \frac{1}{m} (1 - \frac{1}{m})^{m-1} \cdot \sum_{i=1}^{|x^*|} (w(x^*) - w(y^i)) \\ &= \frac{1}{n} \cdot \frac{1}{m} (1 - \frac{1}{m})^{m-1} \cdot w(x^*) \\ &= \frac{1}{n} \cdot \frac{1}{m} (1 - \frac{1}{m})^{m-1} \cdot V(\xi_t) \end{split}$$

Main idea:

(1) obtain the empty subgraph 0^n

(2) obtain a minimum spanning tree

The analysis of phase (1): $\min(c(\mathbf{x}), w(\mathbf{x}) = \sum_{i:x_i=1} w_i)$

Using multiplicative drift analysis:

- design the distance function: $V(P) = min \{w(x) \mid x \in P\}$
- analyze the expected drift: $E[V(\xi_t) V(\xi_{t+1}) | \xi_t = P] \ge \frac{1}{emn} V(\xi_t)$
- Upper bound on the expected running time:

$$\sum_{P} \pi_{0}(P) \cdot \frac{1 + \ln \left(V(P) / V_{min} \right)}{\delta} \le emn(1 + \ln \left(mw_{max} \right))$$
$$V(P) \le mw_{max} \qquad V_{min} \ge 1$$

Main idea:

(1) obtain the empty subgraph 0^n

(2) obtain a minimum spanning tree

The analysis of phase (1): $\min(c(\mathbf{x}), w(\mathbf{x}) = \sum_{i:x_i=1} w_i)$

Using multiplicative drift analysis:

- design the distance function: $V(P) = min \{w(x) \mid x \in P\}$
- analyze the expected drift: $E[V(\xi_t) V(\xi_{t+1}) | \xi_t = P] \ge \frac{1}{emn} V(\xi_t)$
- Upper bound on the expected running time:

 $\sum_{P} \pi_{0}(P) \cdot \frac{1 + \ln \left(V(P) / V_{min} \right)}{\delta} \leq emn(1 + \ln \left(mw_{max} \right))$ $\in O(mn \left(\log n + \log w_{max} \right))$

The analysis of phase (2): $min (c(x), w(x) = \sum_{i:x_i=1} w_i)$

- x^i : the Pareto optimal solution with *i* connected components
- the found Pareto optimal solutions will always be kept
- follow the path: $x^n \to x^{n-1} \to \dots \to x^2 \to x^1 \to a$ minimum spanning tree

The probability is at least $\frac{1}{n} \frac{1}{m} (1 - \frac{1}{m})^{m-1} \ge \frac{1}{emn}$

The expected running time is at most: $(n-1) \cdot emn \in O(mn^2)$

The expected running time of phase (1): $O(mn(\log n + \log w_{max}))$

The total expected running time: $O(mn(n + \log w_{max}))$

$$\arg\min_{\boldsymbol{x}\in\{0,1\}^m}\sum_{i=1}^m w_i x_i \quad s.t. \ c(\boldsymbol{x}) = 1$$

Bi-objective reformulation min $(c(\mathbf{x}), \sum_{i:x_i=1} w_i)$

Theorem. [Neumann & Wegener, Nature Computing'05] The expected running time of the GSEMO solving the MST problem is $O(mn (n + \log w_{max}))$.

Penalty functions: $O(m^2(\log n + \log w_{max}))$

Bi-objective reformulation: $O(mn(n + \log w_{max}))$

Bi-objective reformulation is better for dense graphs, e.g., $m \in O(n^2)$

More examples

Problem	Penalty functions	Bi-objective reformulation
Set cover	exponential	$O(mn(\log c_{max} + \log n))$ [Friedrich et al., ECJ'10]
Minimum cut	exponential	$O(Fm(\log c_{max} + \log n))$ [Neumann et al., Algorithmica'11]
Minimum label spanning tree	$\Omega(ku^k)$	<i>O</i> (<i>k</i> ² log <i>k</i>) [Lai et al., TEC'14]
Minimum cost coverage	exponential	$O(Nn(\log n + \log w_{max} + N))$ [Qian et al., IJCAI'15]
		Better

Bi-objective reformulation

Main idea:

1. transform the original constrained optimization problem into a bi-objective optimization problem



Bi-objective reformulation

Main idea:

1. transform the original constrained optimization problem into a bi-objective optimization problem

constrained



bi-objective

min f(x)

s.t. $g_i(x) = 0$, $1 \le i \le q$; $h_i(x) \le 0$, $q + 1 \le i \le m$

min $(f(x), \sum_{i=1}^{m} f_i(x))$

- 2. employ a multi-objective EA to solve the transformed problem *constraint violation degree = 0*
- 3. output the feasible solution from the generated nondominated solution set

Constraint handling strategies

The final output solution must satisfy the constraints

Common constraint handling strategies

- Penalty functions
- Stochastic ranking
- Repair functions
- Restricting search to the feasible region
- Decoder functions
- Bi-objective reformulation

Better algorithms?

Subset selection is to select a subset of size *k* from a total set of *n* items for optimizing some objective function



Application - sparse regression

Sparse regression [Tropp, TIT'04]: select a few observation variables to best approximate the predictor variable by linear regression



Application - influence maximization

Influence maximization [Kempe et al., KDD'03]: select a subset of users from a social network to maximize its influence spread



Item v_i : a social network user

Objective *f*: influence spread, measured by the expected number of social network users activated by diffusion

Application - document summarization

Document summarization [Lin & Bilmes, ACL'11]: select a few sentences to best summarize the documents



Application - sensor placement

Sensor placement [Krause & Guestrin, IJCAI'09 Tutorial] : select a few places to install sensors such that the information gathered is maximized



Water contamination detection

Fire detection

Item v_i : a place to install a sensor

Objective *f* : entropy

Subset selection





[Mathematical Programming 1978]

f: monotone and submodular The greedy algorithm: (1 - 1/e)-approximation Best Paper/Test of Time Award: [Kempe et al., KDD'03] [Das & Kempe, ICML'11] [Iyer & Bilmes, NIPS'13]

A subset $X \subseteq V$ can be naturally represented by a Boolean vector $x \in \{0,1\}^n$

• the *i*-th bit $x_i = 1$ if the item $v_i \in X$; $x_i = 0$ otherwise

•
$$X = \{v_i \mid x_i = 1\}$$

 $V = \{v_1, v_2, v_3, v_4, v_5\}$ a subset $X \subseteq V$ a Boolean vector $x \in \{0,1\}^5$
 \emptyset 00000

 $\{v_1\}$ \longleftrightarrow 10000

 $\{v_2, v_3, v_5\}$ 01101

 $\{v_1, v_2, v_3, v_4, v_5\}$ 11111

POSS algorithm

POSS algorithm [Qian, Yu and Zhou, NIPS'15]

$max_{X\subseteq V} f(X)$ s.t. $|X| \le k$ originalTransformation: \car{V} \car{V} $min_{X\subseteq V} (-f(X), |X|)$ bi-objective

Algorithm 1 POSS

Input: all variables $V = \{X_1, \ldots, X_n\}$, a given objective fand an integer parameter $k \in [1, n]$ **Parameter**: the number of iterations T **Output**: a subset of V with at most k variables Process: 1: Let $s = \{0\}^n$ and $P = \{s\}$. 2: Let t = 0. 3: while t < T do Select *s* from *P* uniformly at random. 4: 5: Generate s' by flipping each bit of s with prob. $\frac{1}{n}$. Evaluate $f_1(s')$ and $f_2(s')$. 6: 7: if $\exists z \in P$ such that $z \prec s'$ then $Q = \{ z \in P \mid s' \preceq z \}.$ 8: $P = (P \setminus Q) \cup \{\overline{s'}\}.$ 9: 10:end if t = t + 1. 11: 12: end while 13: return $\arg\min_{s \in P, |s| \le k} f_1(s)$

Initialization: put the special solution {0}^{*n*} into the population *P*

Parent selection & Reproduction: pick a solution x randomly from P, and flip each bit of x with prob. 1/n to generate a new solution

Evaluation & Survivor selection: if the new solution is not dominated, put it into *P* and weed out bad solutions

Output: select the best feasible solution

Sparse regression

Sparse regression: given all observation variables $V = \{v_1, ..., v_n\}$, a predictor variable *z* and a budget *k*, to find a subset $X \subseteq V$ such that

$$max_{X\subseteq V} \quad R_{z,X}^2 = \frac{\operatorname{Var}(z) - \operatorname{MSE}_{z,X}}{\operatorname{Var}(z)} \quad s.t. \quad |X| \le k$$

Var(z): variance of z

 $MSE_{z,X}$: mean squared error of predicting *z* by using observation variables in *X*



Experimental results

the size constraint: k = 8

exhaustive search			greedy algorithms			relaxation methods		
Data set	OPT	POSS	FR	FoBa	OMP	RFE	MCP	
housing	.7437±.0297	.7437±.0297	.7429±.0300•	.7423±.0301•	.7415±.0300•	.7388±.0304•	.7354±.0297•	
eunite2001	.8484±.0132	$.8482 \pm .0132$.8348±.0143•	.8442±.0144•	.8349±.0150•	.8424±.0153•	.8320±.0150•	
svmguide3	.2705±.0255	$.2701 \pm .0257$.2615±.0260•	.2601±.0279•	.2557±.0270•	.2136±.0325•	.2397±.0237•	
ionosphere	.5995±.0326	$.5990 \pm .0329$.5920±.0352•	.5929±.0346•	.5921±.0353•	.5832±.0415•	.5740±.0348•	
sonar	-	$.5365 \pm .0410$.5171±.0440•	.5138±.0432•	.5112±.0425•	.4321±.0636•	.4496±.0482•	
triazines	-	.4301±.0603	.4150±.0592•	.4107±.0600•	.4073±.0591•	.3615±.0712•	.3793±.0584•	
coil2000	-	$.0627 \pm .0076$.0624±.0076•	.0619±.0075•	.0619±.0075•	.0363±.0141•	.0570±.0075•	
mushrooms	-	.9912±.0020	.9909±.0021•	.9909±.0022•	.9909±.0022•	.6813±.1294•	.8652±.0474•	
clean1	-	$.4368 \pm .0300$.4169±.0299•	.4145±.0309•	.4132±.0315•	.1596±.0562•	.3563±.0364•	
w5a	-	.3376±.0267	.3319±.0247•	.3341±.0258•	.3313±.0246•	.3342±.0276•	.2694±.0385•	
gisette	-	$.7265 \pm .0098$.7001±.0116•	.6747±.0145•	.6731±.0134•	.5360±.0318•	.5709±.0123•	
farm-ads	-	$.4217 \pm .0100$.4196±.0101•	.4170±.0113•	.4170±.0113•	_	.3771±.0110•	
POSS: win/tie/loss		_	12/0/0	12/0/0	12/0/0	11/0/0	12/0/0	

• denotes that POSS is significantly better by the *t*-test with confidence level 0.05



POSS is significantly better than all the compared state-of-the art algorithms on all data sets

the number of iterations of POSS: $2ek^2n$

POSS can achieve the optimal polynomial-time approximation guarantee

Theorem 1. For subset selection with monotone objective functions, POSS using $E[T] \le 2ek^2n$ finds a solution *X* with $|X| \le k$ and

$$f(X) \ge (1 - e^{-\gamma}) \cdot \text{OPT.}$$

the optimal polynomial-time approximation guarantee for monotone *f* [Harshaw et al., ICML'19]

Lemma 1. For any $X \subseteq V$, there exists one item $\hat{v} \in V \setminus X$ such that

$$f(X \cup \{\hat{v}\}) - f(X) \ge \frac{\gamma}{k} (\text{OPT} - f(X))$$

submodularity ratio [Das & Kempe, ICML'11]

the optimal function value

Roughly speaking, the improvement by adding a specific item is proportional to the current distance to the optimum

Lemma 1. For any
$$X \subseteq V$$
, there exists one item $\hat{v} \in V \setminus X$ such that $f(X \cup {\hat{v}}) - f(X) \ge \frac{\gamma}{k}(\text{OPT} - f(X))$

a subset

Main idea:

• consider a solution
$$\mathbf{x}$$
 with $|\mathbf{x}| \le i$ and $f(\mathbf{x}) \ge \left(1 - \left(1 - \frac{\gamma}{k}\right)^i\right) \cdot \text{OPT}$





Lemma 1. For any $X \subseteq V$, there exists one item $\hat{v} \in V \setminus X$ such that $f(X \cup {\hat{v}}) - f(X) \ge \frac{\gamma}{k}(\text{OPT} - f(X))$

Main idea:

- consider a solution \mathbf{x} with $|\mathbf{x}| \leq i$ and $f(\mathbf{x}) \geq \left(1 \left(1 \frac{\gamma}{k}\right)^i\right) \cdot \text{OPT}$
- in each iteration of POSS:
 - > select x from the population P

a subset

flip one specific 0-bit of *x* to 1-bit
 (i.e., add the specific item *v̂* in Lemma 1)

$$\Rightarrow |\mathbf{x}'| = |\mathbf{x}| + 1 \leq i + 1 \text{ and } f(\mathbf{x}') \geq \left(1 - \left(1 - \frac{\gamma}{k}\right)^{i+1}\right) \cdot \text{OPT}$$

Lemma 1. For any
$$X \subseteq V$$
, there exists one item $\hat{v} \in V \setminus X$ such that

$$f(X \cup \{\hat{v}\}) - f(X) \ge \frac{\gamma}{k} (\text{OPT} - f(X))$$

$$f(x') - f(x) \ge \frac{\gamma}{k} \cdot (\text{OPT} - f(x))$$

$$f(x') \ge \left(1 - \frac{\gamma}{k}\right) f(x) + \frac{\gamma}{k} \cdot \text{OPT}$$

$$f(x) \ge \left(1 - \left(1 - \frac{\gamma}{k}\right)^{i}\right) \cdot \text{OPT}$$

$$f(x') \ge \left(1 - \left(1 - \frac{\gamma}{k}\right)^{i}\right) \cdot \text{OPT} = \left(1 - \left(1 - \frac{\gamma}{k}\right)^{i+1}\right) \cdot \text{OPT}$$

Lemma 1. For any $(X) \subseteq V$, there exists one item $\hat{v} \in V \setminus X$ such that $f(X \cup \{\hat{v}\}) - f(X) \ge \frac{\gamma}{k} (\text{OPT} - f(X))$

Main idea:

• consider a solution
$$\mathbf{x}$$
 with $|\mathbf{x}| \le i$ and $f(\mathbf{x}) \ge \left(1 - \left(1 - \frac{\gamma}{k}\right)^i\right) \cdot \text{OPT}$

in each iteration of POSS:

a subset

> select *x* from the population *P*, the probability: ¹/_{|P|}
 > flip one specific 0-bit of *x* to 1-bit, the probability: ¹/_n (1 − ¹/_n)^{n−1} ≥ ¹/_{en}

(i.e., add the specific item \hat{v} in Lemma 1)

→
$$|\mathbf{x}'| = |\mathbf{x}| + 1 \le i + 1$$
 and $f(\mathbf{x}') \ge \left(1 - \left(1 - \frac{\gamma}{k}\right)^{i+1}\right) \cdot \text{OPT}$
 $i \longrightarrow i + 1$ the probability: $\frac{1}{|P|} \cdot \frac{1}{en}$

http://www.lamda.nju.edu.cn/gianc/

en

Lemma 1. For any
$$\widehat{X} \subseteq V$$
, there exists one item $\widehat{v} \in V \setminus X$ such that
 $f(X \cup \{\widehat{v}\}) - f(X) \ge \frac{\gamma}{k} (OPT - f(X))$
Main idea:
a subset
o consider a solution \widehat{x} with $|\mathbf{x}| \le i$ and $f(\mathbf{x}) \ge \left(1 - \left(1 - \frac{\gamma}{k}\right)^i\right) \cdot OPT$
in each iteration of POSS:
 $i \longrightarrow i + 1$ the probability: $\frac{1}{|P|} \cdot \frac{1}{en} \xrightarrow{|P| \le 2k} \frac{1}{2ekn}$
For each size in
 $\{0, 1, ..., 2k - 1\},$
there exists at most
one solution in P

Lemma 1. For any $X \subseteq V$, there exists one item $\hat{v} \in V \setminus X$ such that $f(X \cup {\hat{v}}) - f(X) \ge \frac{\gamma}{k}(\text{OPT} - f(X))$

Main idea:

• consider a solution
$$x$$
 with $|x| \le i$ and $f(x) \ge \left(1 - \left(1 - \frac{\gamma}{k}\right)^i\right) \cdot \text{OPT}$

• in each iteration of POSS:

a subset

$$i \longrightarrow i+1$$
 the probability: $\frac{1}{|P|} \cdot \frac{1}{en} \quad |P| \le 2k \qquad \frac{1}{2ekn}$

 $i \longrightarrow i + 1$ the expected number of iterations: 2ekn

 $i = 0 \longrightarrow k$ the expected number of iterations: $k \cdot 2ekn$

Theoretical analysis: The advantage of biobjective reformulation for handling constraints

Algorithm design: The POSS algorithm for subset selection

Sparse regression								
	Corr.	Dis.	LR		3	AIC.	BIC	RF.
x1	0.28	0.46	1			0.22	0.63	1
x2	0.31	0.59	0.64			0.58	0.56	1
x3	0.11	0.02	0.53			0.43	0.01	1
x4	0.1	0.1	0.64			0.73	0.92	1
x5	0.02	0.15	0.33			0.56	0.36	0.78
х6	0.36	0.02	0.01			0.32	0.02	0.22
x7	0.2	0.2	0.21			0.21	0.02	0.11
x8	0.1	0.03	0.32			0.33	0.51	0.44
x9	0.32	0.1	0.2			0.06	0.66	0
d0	0.24	0	0.02			0.6	0.03	0.33
d1	0.12	0.45	0.44			0.64	0.45	1
d2	0.36	0.58	0.12			0.73	0.58	0.67
43	0.2	0.02	0.24			0.34	0.02	0.89
d 4	0.24	0.92	0.33			0.24	0.93	0.56

Influence maximization



Document summarization



Sensor placement



POSS algorithm

POSS algorithm [Qian, Yu and Zhou, NIPS'15]

$max_{X\subseteq V} f(X)$ s.t. $|X| \le k$ originalTransformation: \car{V} \car{V} \car{V} \car{V} $min_{X\subseteq V}$ (-f(X), |X|) \car{V} \car{V}

Algorithm 1 POSS

Input: all variables $V = \{X_1, \dots, X_n\}$, a given objective f and an integer parameter $k \in [1, n]$ **Parameter**: the number of iterations T **Output**: a subset of V with at most k variables Process: 1: Let $s = \{0\}^n$ and $P = \{s\}$. 2: Let t = 0. 3: while t < T do Select *s* from *P* uniformly at random. 4: 5: Generate s' by flipping each bit of s with prob. $\frac{1}{n}$. Evaluate $f_1(s')$ and $f_2(s')$. 6: if $\exists z \in P$ such that $z \prec s'$ then 7: $Q = \{ z \in P \mid s' \preceq z \}.$ 8: $P = (P \setminus Q) \cup \{\overline{s'}\}.$ 9: end if 10:t = t + 1. 11: 12: end while 13: return $\arg\min_{s \in P, |s| \le k} f_1(s)$

Parent selection & Reproduction:
pick a solution *x* randomly from *P*, and flip each bit of *x* with prob.
1/*n* to generate a new solution

Using bit-wise mutation only

PORSS algorithm

PORSS algorithm [Qian, Bian and Feng, AAAI'20]

$$max_{X\subseteq V} f(X)$$
 $s.t.$ $|X| \le k$ originalTransformation: \mathbf{V} $min_{X\subseteq V} (-f(X), |X|)$ bi-objective

Algorithm 2 PORSS Algorithm

Input: $V = \{v_1, \ldots, v_n\}$; objective $f : 2^V \to \mathbb{R}$; budget k **Parameter**: the number T of iterations **Output**: a subset of V with at most k items **Process**:

1: Let
$$x = 0^n$$
, $P = \{x\}$ and $t = 0$;

2: while
$$t < T$$
 do

- 3: Select $\boldsymbol{x}, \boldsymbol{y}$ from P randomly with replacement;
- 4: Apply recombination on x, y to generate x', y';
 5: Apply bit-wise mutation on x', y' to generate x'', y'';

```
6: for each q \in \{x'', y''\}
```

```
7: if \nexists z \in P such that z \prec q then
```

- 8: $P = (P \setminus \{ \boldsymbol{z} \in P \mid \boldsymbol{q} \leq \boldsymbol{z} \}) \cup \{ \boldsymbol{q} \}$
- 9: **end if**
- 10: **end for**
- 11: t = t + 1
- 12: end while

13: return $\arg \max_{\boldsymbol{x} \in P, |\boldsymbol{x}| \le k} f(\boldsymbol{x})$

Parent selection & Reproduction:

- pick two solutions randomly from *P*
- apply recombination operator
- apply bit-wise mutation operator

PORSS algorithm

• One-point crossover



Uniform crossover



Experimental results

the size constrai	nt: $k = 8$ Stat	e-of-the- orithms	art	PORSS using one point crossover	- PORSS us uniform c	ing rossover
Data set	(#inst, #feat)	OPT	Greedy	POSS	PORSS _o	$PORSS_u$
svmguide3	(1243, 22)	0.221	0.214	0.220 ± 0.001	0.220 ± 0.001	0.221±0.001
triazines	(186, 60)	0.328	0.316	$0.327 {\pm} 0.000$	$0.328 {\pm} 0.000$	$0.328 {\pm} 0.000$
clean1	(476, 166)	_	0.371	$0.386 {\pm} 0.004$	$0.387 {\pm} 0.006$	$0.393{\pm}0.005$
usps	(7291, 256)	_	0.562	$0.570 {\pm} 0.003$	$0.572{\pm}0.003$	$0.572{\pm}0.003$
scene	(1211, 294)	_	0.254	$0.268 {\pm} 0.003$	$0.272{\pm}0.002$	0.271 ± 0.002
protein	(17766, 356)	_	0.132	0.132 ± 0.000	$0.133{\pm}0.000$	$0.133{\pm}0.000$
colon-cancer	(62, 2000)	_	0.890	0.906 ± 0.011	0.909 ± 0.018	$0.911 {\pm} 0.014$
cifar10	(50000, 3072)	_	0.069	$0.070 {\pm} 0.001$	$0.070 {\pm} 0.001$	$0.071 {\pm} 0.001$
leukemia	(72, 7129)	_	0.947	$0.966 {\pm} 0.009$	$0.968 {\pm} 0.006$	$0.969 {\pm} 0.007$
smallNORB	(24300, 18432)	_	0.461	$0.535 {\pm} 0.007$	$0.547 {\pm} 0.003$	$0.550{\pm}0.002$
POSS: 0	Count of direct wir	1	9.5	_	1	0
A	verage rank		3.95	2.95	1.85	1.25

PORSS performs the best

Summary

- Constrained optimization
- Constraint handling strategies
 - Penalty functions
 - Stochastic ranking
 - Repair functions
 - Restricting search to the feasible region
 - Decoder functions
 - − Bi-objective reformulation →

Give an example of

→ algorithm design guided by theoretical analysis

References

- A. E. Eiben and J. E. Smith. Introduction to Evolutionary Computing. Chapter 13.
- T. Friedrich, J. He, N. Hebbinghaus, F. Neumann and C. Witt. Approximating covering problems by randomized search heuristics using multi-objective models. *Evolutionary Computation*, 2010, 18(4): 617-633
- B. Doerr, D. Johannsen and C. Winzen. Multiplicative drift analysis. *Algorithmica*, 2012, 64: 673-697
- X. Lai, Y. Zhou, J. He and J. Zhang. Performance analysis of evolutionary algorithms for the minimum label spanning tree problem. *IEEE Transactions on Evolutionary Computation*, 2014, 18(6): 860-872
- F. Neumann and I. Wegener. Minimum spanning trees made easier via multiobjective optimization. *Natural Computing*, 2006, 5(3): 305-319
- T. P. Runarsson and X. Yao. Stochastic ranking for constrained evolutionary optimization. *IEEE Transactions on Evolutionary Computation*, 2000, 4(3): 284-294

References

- F. Neumann and I. Wegener. Randomized local search, evolutionary algorithms, and the minimum spanning tree problem. *Theoretical Computer Science*, 2007, 378(1): 32-40
- F. Neumann, J. Reichel and M. Skutella. Computing minimum cuts by randomized search heuristics. *Algorithmica*, 2011, 59(3): 323-342
- C. Qian, Y. Yu and Z.-H. Zhou. On constrained Boolean Pareto optimization. In: *Proceedings of the 24th International Joint Conference on Artificial Intelligence* (*IJCAI'15*), 2015, pages 389-395, Buenos Aires, Argentina
- C. Qian, Y. Yu and Z.-H. Zhou. Subset selection by Pareto optimization. In: *Advances in Neural Information Processing Systems 28 (NIPS'15)*, 2015, pages 1765-1773, Montreal, Canada
- C. Qian, C. Bian and C. Feng. Subset selection by Pareto optimization with recombination. In: *Proceedings of the 34th AAAI Conference on Artificial Intelligence (AAAI'20)*, New York, NY, 2020, pp.2408-2415.

Task:

- Apply POSS to solve the subset selection (submodular optimization) problem
- Apply NSGA-II to solve the subset selection problem
- Apply MOEA/D to solve the subset selection problem
- Improve the above algorithms (e.g., the way of biobjective reformulation or the employed MOEA)

Deadline: Jan. 31