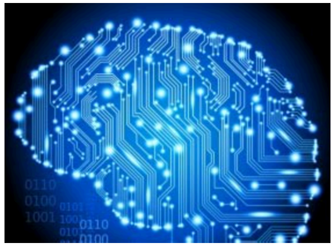
Lecture 4: Search 3

http://cs.nju.edu.cn/yuy/course_ai17.ashx



Previously...

Path-based search

- Uninformed search
  - Depth-first, breadth first, uniform-cost search
- Informed search
  - Best-first, **A* search**

Adversarial search

Competitive environments: Game

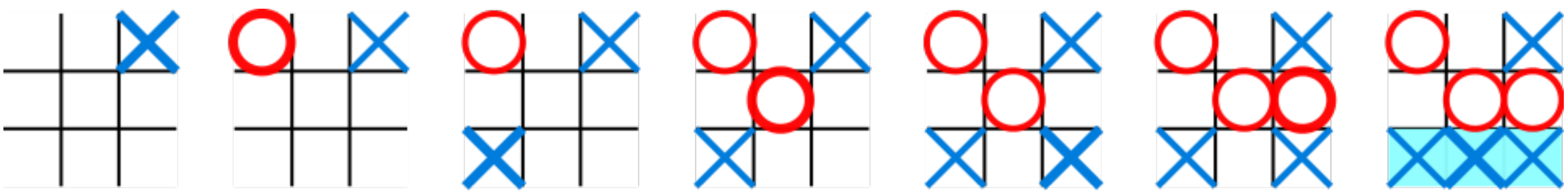
the agents' goals are in conflict

We consider:
* two players
* zero-sum games

Type of games:
* deterministic v.s. chance
* perfect v.s. partially observable information

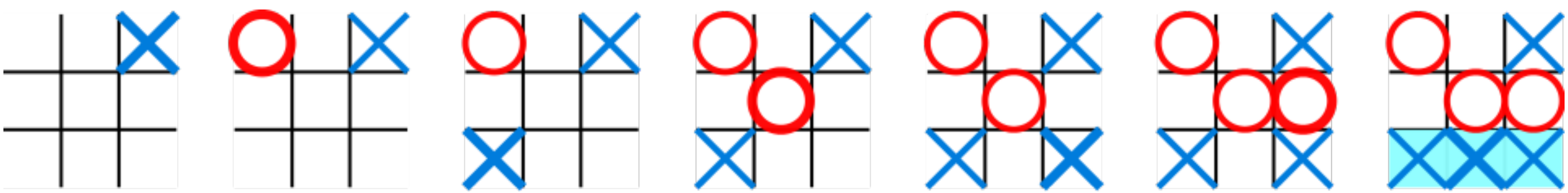
Example

两人轮流在一有九格方盘上划加字或圆圈，谁先把三个同一记号排成横线、直线、斜线，即是胜者



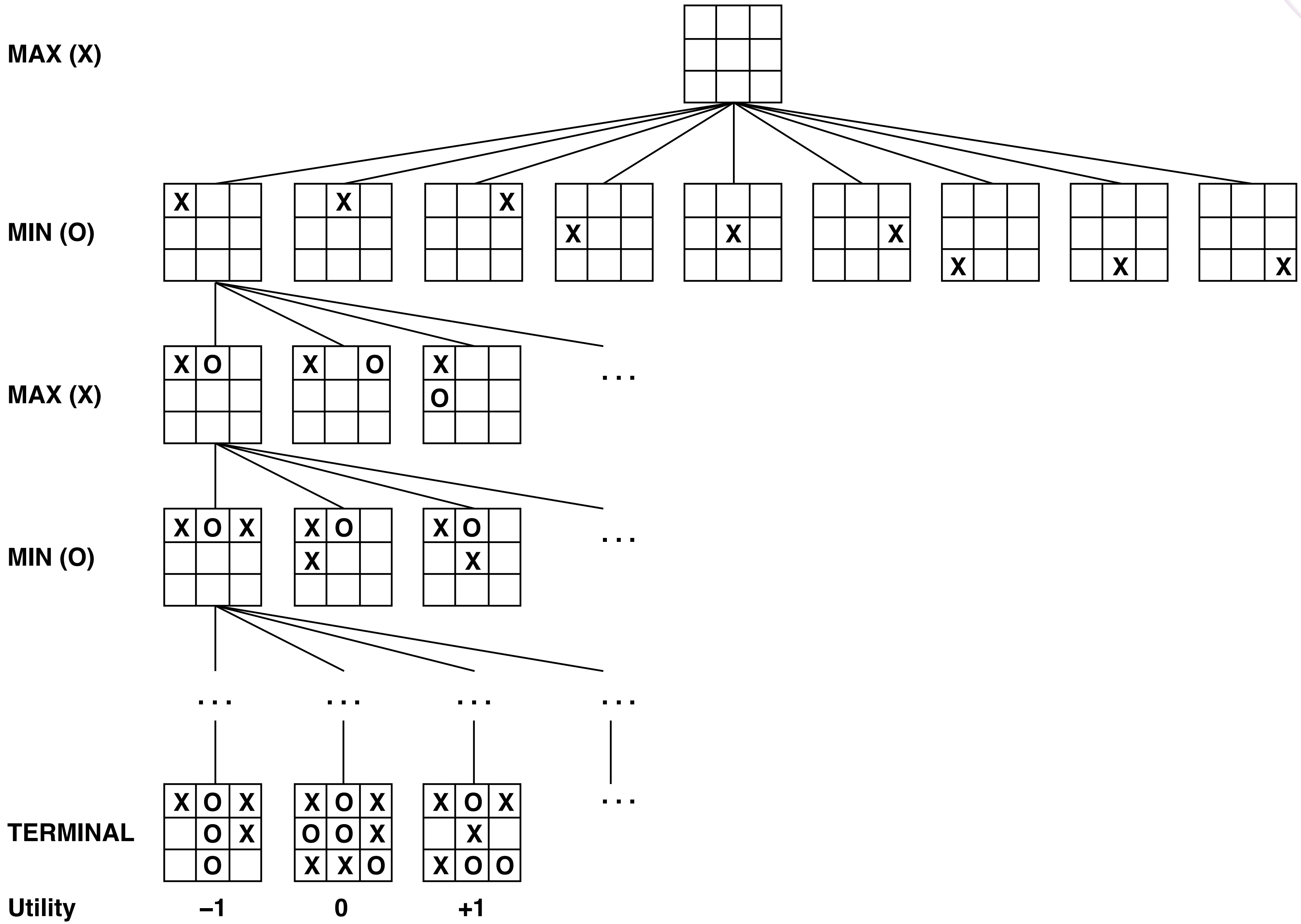
Definition of a game

- S_0: The **initial state**, which specifies how the game is set up at the start.
- PLAYER(s): Defines which player has the move in a state.
- ACTIONS(s): Returns the set of legal moves in a state.
- RESULT(s, a): The **transition model**, which defines the result of a move.
- TERMINAL-TEST(s): A **terminal test**, which is true when the game is over and false otherwise. States where the game has ended are called **terminal states**.
- UTILITY(s, p): A **utility function** (also called an objective function or payoff function),



two players: MAX and MIN

Tic-tac-toe search tree

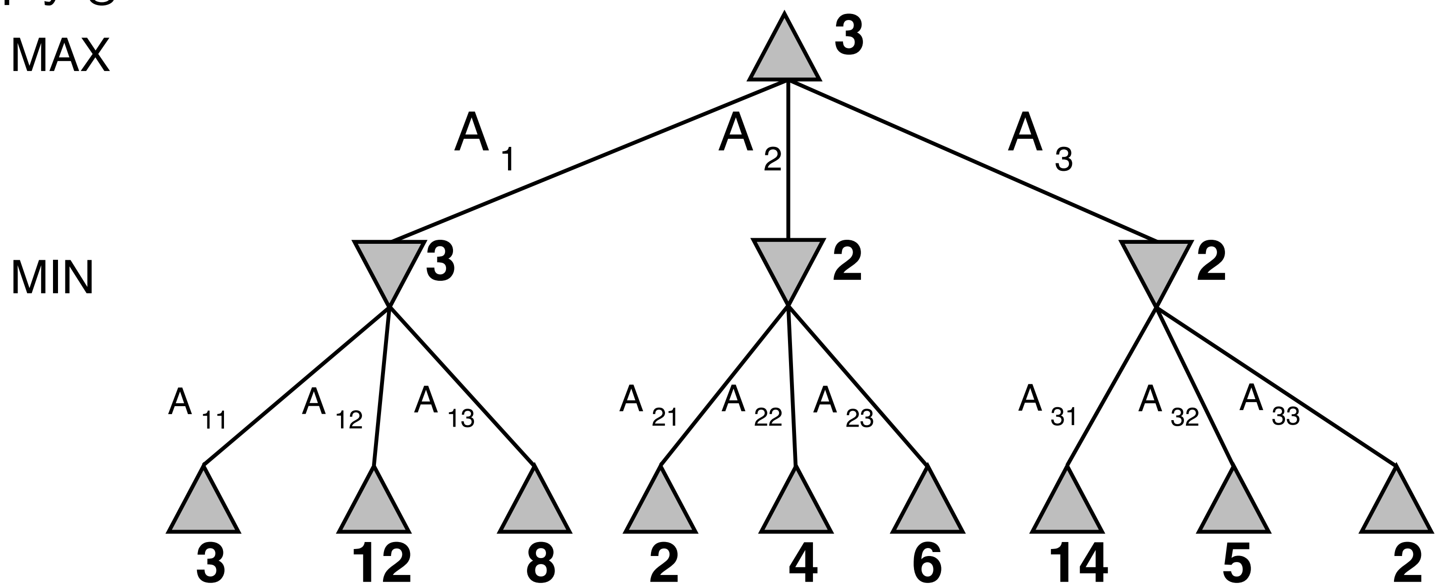


Optimal decision in games

Perfect play for deterministic, perfect-information games

Idea: choose move to position with highest minimax value
= best achievable payoff against best play

E.g., 2-ply game:



$$\text{MINIMAX}(s) = \begin{cases} \text{UTILITY}(s) & \text{if TERMINAL-TEST}(s) \\ \max_{a \in Actions(s)} \text{MINIMAX}(\text{RESULT}(s,a)) & \text{if PLAYER}(s) = \text{MAX} \\ \min_{a \in Actions(s)} \text{MINIMAX}(\text{RESULT}(s,a)) & \text{if PLAYER}(s) = \text{MIN} \end{cases}$$

Minimax algorithm

function MINIMAX-DECISION(*state*) **returns** *an action*
    inputs: *state*, current state in game

    return the *a* in ACTIONS(*state*) maximizing MIN-VALUE(RESULT(*a*, *state*))

---

function MAX-VALUE(*state*) **returns** *a utility value*
    if TERMINAL-TEST(*state*) **then return** UTILITY(*state*)
    $v \leftarrow -\infty$
    for *a*, *s* in SUCCESSORS(*state*) **do** $v \leftarrow$ MAX(v, MIN-VALUE(s))
    return v

---

function MIN-VALUE(*state*) **returns** *a utility value*
    if TERMINAL-TEST(*state*) **then return** UTILITY(*state*)
    $v \leftarrow \infty$
    for *a*, *s* in SUCCESSORS(*state*) **do** $v \leftarrow$ MIN(v, MAX-VALUE(s))
    return v

Properties of Minimax

Complete?? Yes, if tree is finite (chess has specific rules for this)

Optimal?? Yes, against an optimal opponent. Otherwise??

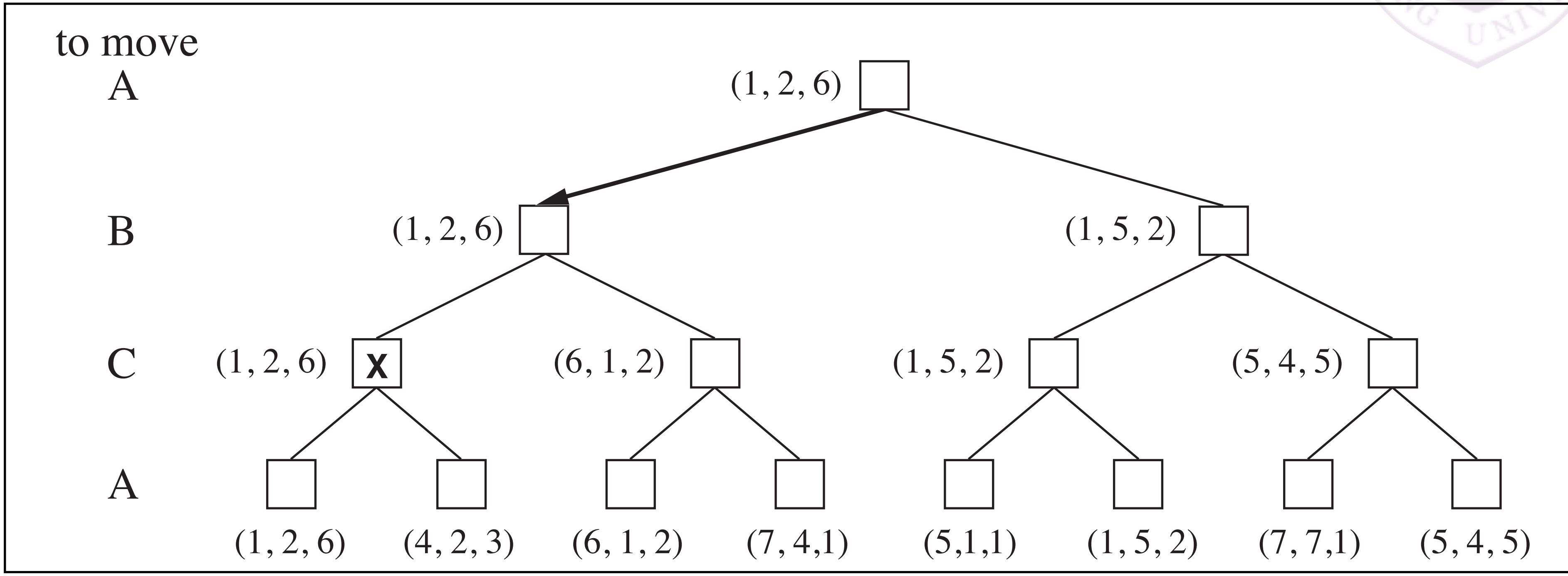
Time complexity?? $O(b^m)$

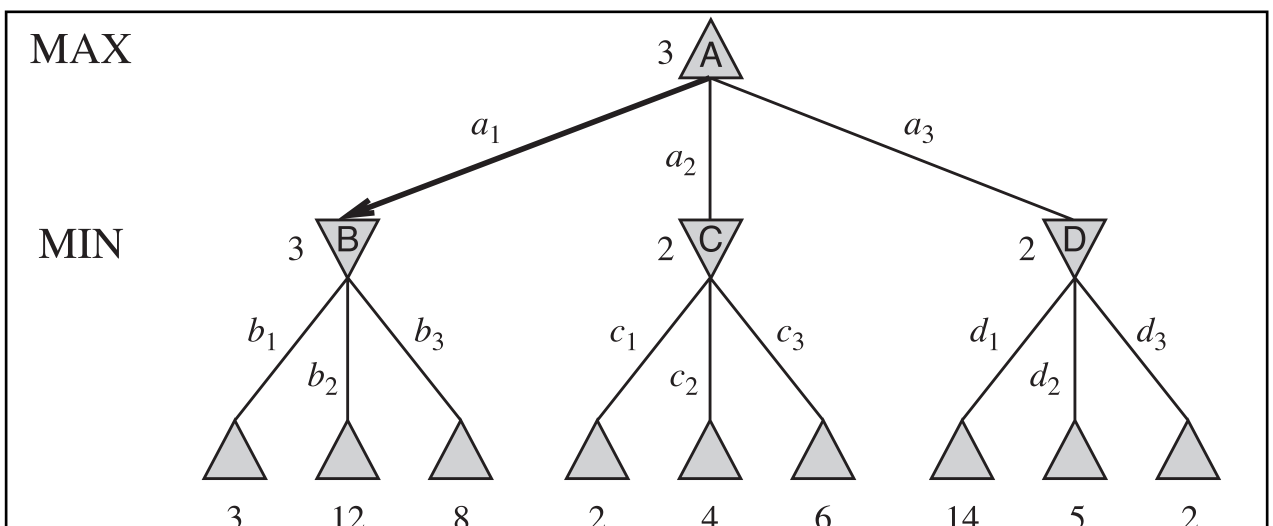
Space complexity?? $O(bm)$ (depth-first exploration)

For chess, $b \approx 35$, $m \approx 100$ for "reasonable" games
$\Rightarrow$ exact solution completely infeasible

Multiple players

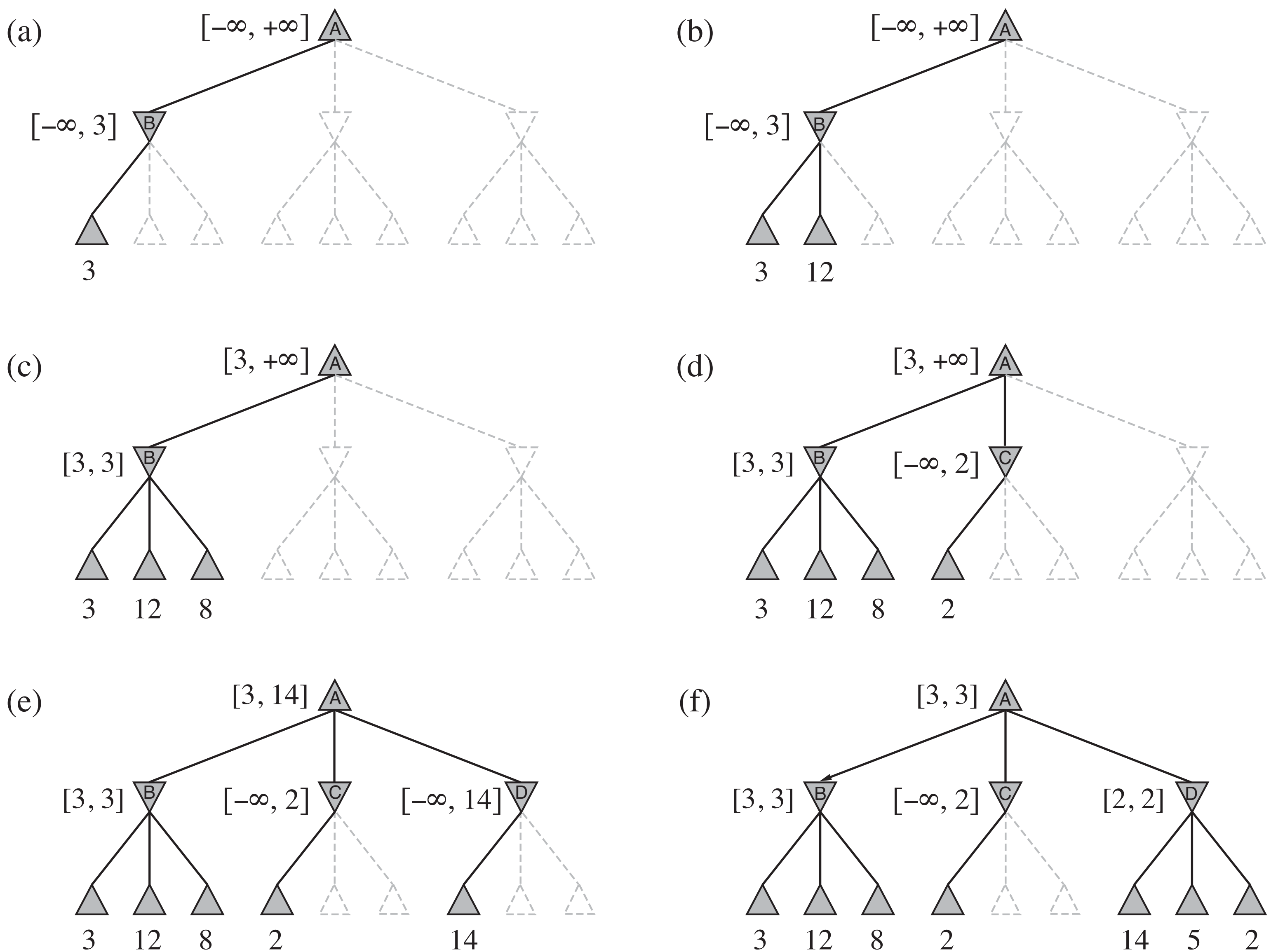
a vector $\langle v_A, v_B, v_C \rangle$ is used for 3 players





Alpha-Beta pruning

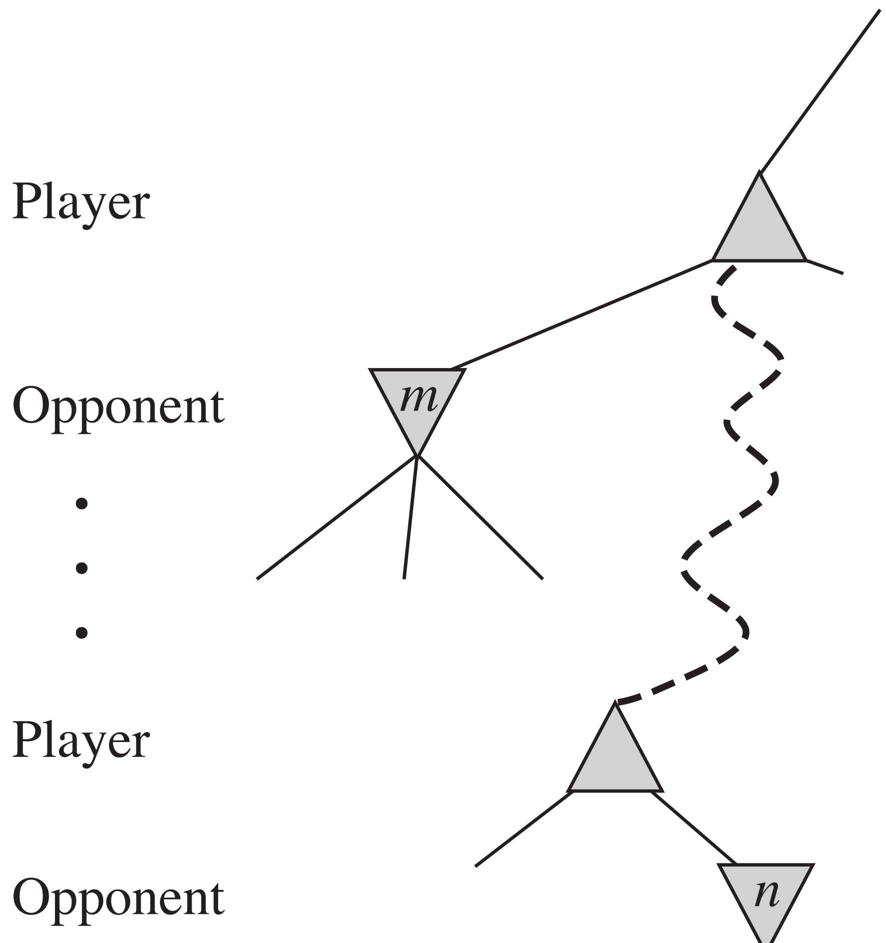
not all branches are needed



Alpha-Beta pruning

$\alpha =$ the value of the best (i.e., highest-value) choice we have found so far at any choice point along the path for MAX.

$\beta =$ the value of the best (i.e., lowest-value) choice we have found so far at any choice point along the path for MIN.



Alpha-Beta pruning

function ALPHA-BETA-SEARCH(*state*) **returns** an action
  $v \leftarrow$ MAX-VALUE($state, -\infty, +\infty$)
  return the *action* in ACTIONS(*state*) with value v

---

function MAX-VALUE($state, \alpha, \beta$) **returns** *a utility value*
  if TERMINAL-TEST(*state*) **then return** UTILITY(*state*)
  $v \leftarrow -\infty$
  for each a **in** ACTIONS(*state*) **do**
    $v \leftarrow$ MAX(v, MIN-VALUE(RESULT(s,a), α, β))
    if $v \geq \beta$ **then return** v
    $\alpha \leftarrow$ MAX(α, v)
  return v

---

function MIN-VALUE($state, \alpha, \beta$) **returns** *a utility value*
  if TERMINAL-TEST(*state*) **then return** UTILITY(*state*)
  $v \leftarrow +\infty$
  for each a **in** ACTIONS(*state*) **do**
    $v \leftarrow$ MIN(v, MAX-VALUE(RESULT(s,a) , α, β))
    if $v \leq \alpha$ **then return** v
    $\beta \leftarrow$ MIN(β, v)
  return v

Properties of alpha-beta

Pruning **does not** affect final result

Good move ordering improves effectiveness of pruning

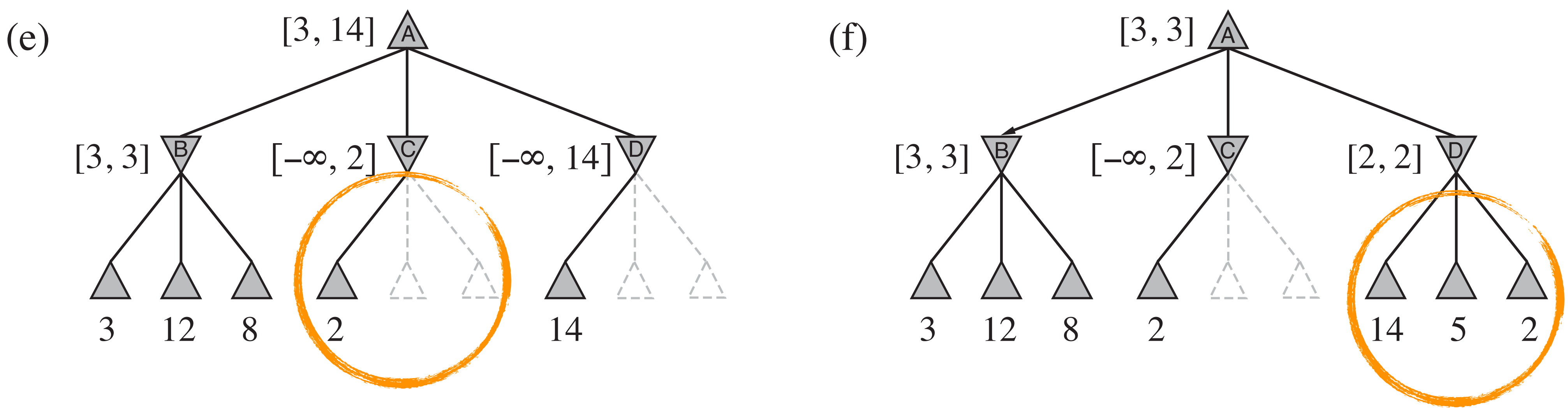
With "perfect ordering," time complexity $= O(b^{m/2})$
$\Rightarrow$ **doubles** solvable depth

A simple example of the value of reasoning about which computations are relevant (a form of metareasoning)

Unfortunately, 35^{50} is still impossible!

The search order is important

it might be worthwhile to try to examine first the successors that are likely to be best



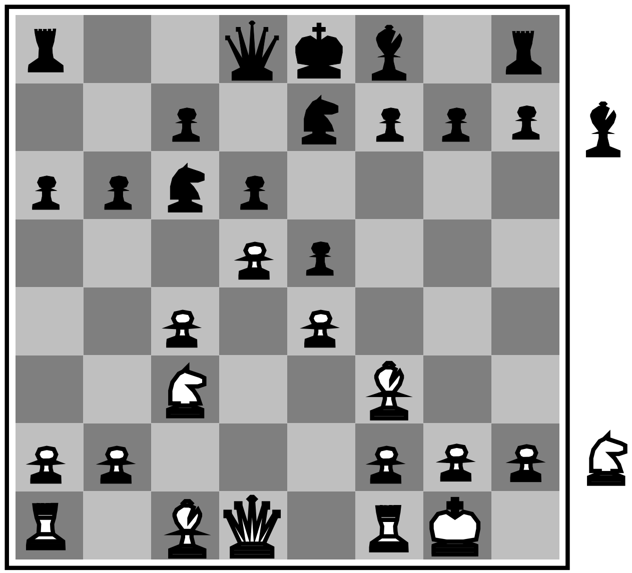
Resource limits

Standard approach:

- Use CUTOFF-TEST instead of TERMINAL-TEST
  e.g., depth limit (perhaps add quiescence search)
- Use EVAL instead of UTILITY
  i.e., evaluation function that estimates desirability of position

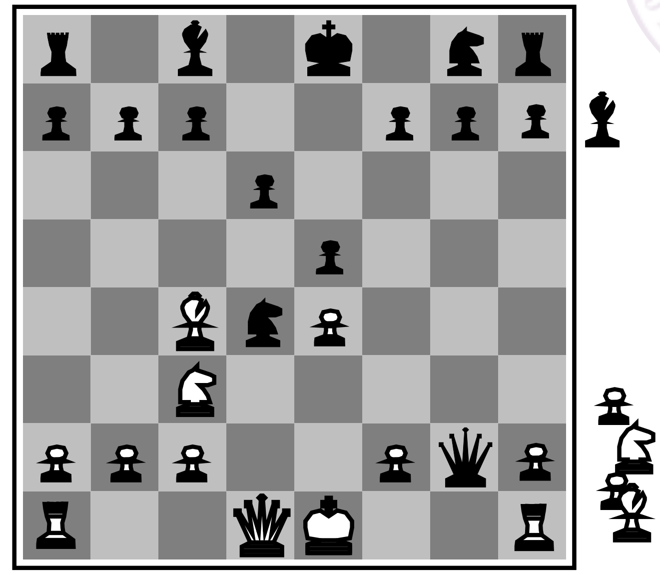
Suppose we have 100 seconds, explore 10^4 nodes/second
$\Rightarrow$ 10^6 nodes per move $\approx 35^{8/2}$
$\Rightarrow$ α–β reaches depth 8 $\Rightarrow$ pretty good chess program

Evaluation functions



Black to move

White slightly better



White to move

Black winning

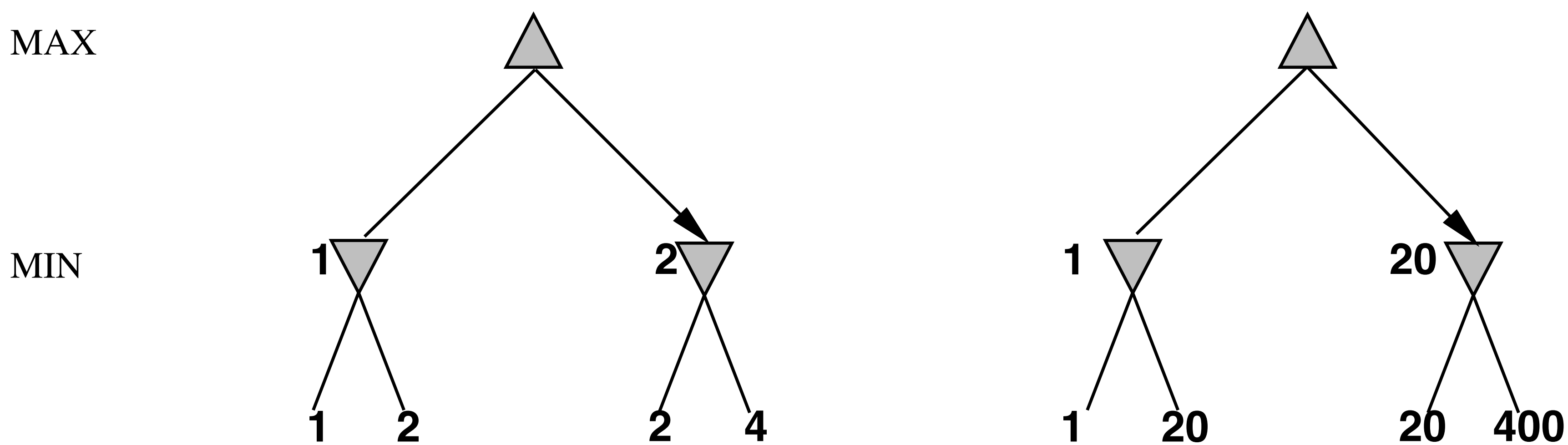
For chess, typically linear weighted sum of features

$$Eval(s) = w_1 f_1(s) + w_2 f_2(s) + \ldots + w_n f_n(s)$$

e.g., $w_1 = 9$ with
$f_1(s) =$ (number of white queens) – (number of black queens), etc.

H-Minimax

$$\text{H-MINIMAX}(s,d) = \begin{cases} \text{EVAL}(s) & \text{if CUTOFF-TEST}(s,d) \\ \max_{a \in Actions(s)} \text{H-MINIMAX}(\text{RESULT}(s,a), d+1) & \text{if PLAYER}(s) = \text{MAX} \\ \min_{a \in Actions(s)} \text{H-MINIMAX}(\text{RESULT}(s,a), d+1) & \text{if PLAYER}(s) = \text{MIN}. \end{cases}$$



Behaviour is preserved under any **monotonic** transformation of EVAL

Only the order matters:

payoff in deterministic games acts as an ordinal utility function

Deterministic games in practice

Checkers: Chinook ended 40-year-reign of human world champion Marion Tinsley in 1994. Used an endgame database defining perfect play for all positions involving 8 or fewer pieces on the board, a total of 443,748,401,247 positions.

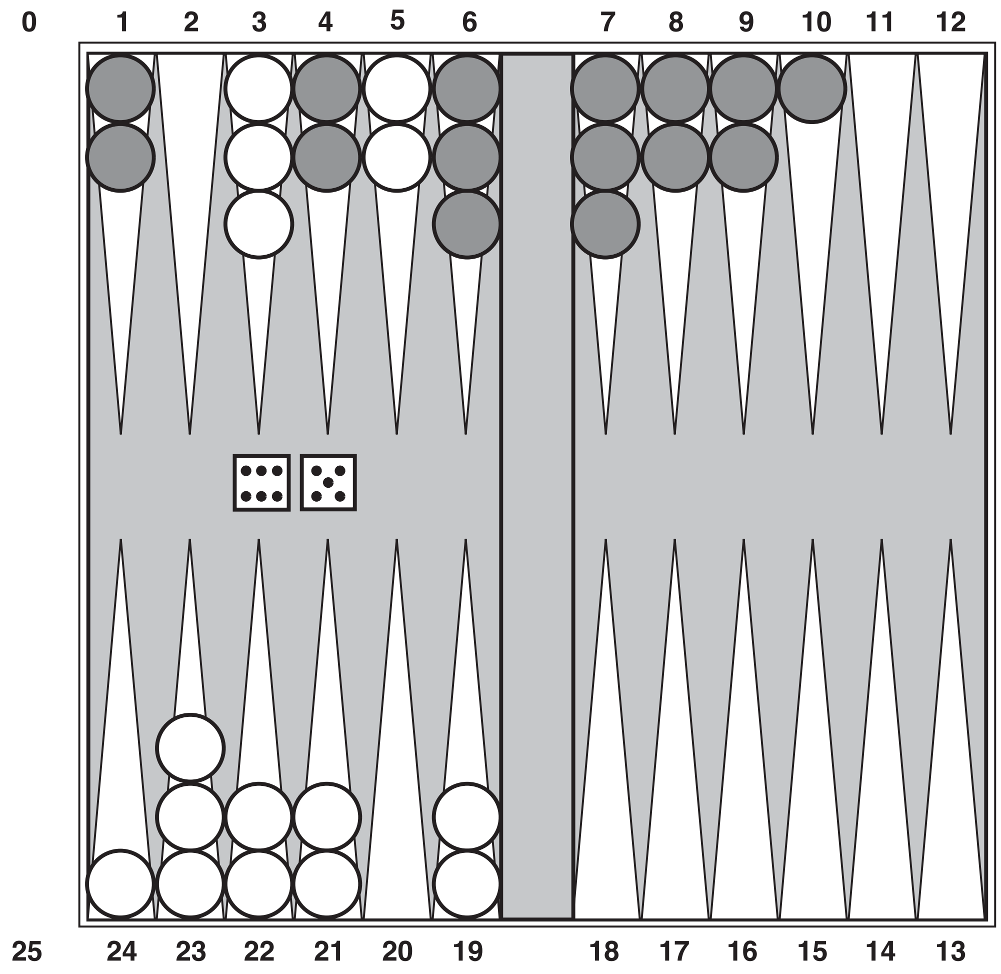
Chess: Deep Blue defeated human world champion Gary Kasparov in a six-game match in 1997. Deep Blue searches 200 million positions per second, uses very sophisticated evaluation, and undisclosed methods for extending some lines of search up to 40 ply.

Othello: human champions refuse to compete against computers, who are too good.

Go: human champions refuse to compete against computers, who are too bad. In go, $b > 300$, so most programs use pattern knowledge bases to suggest plausible moves.

Stochastic games

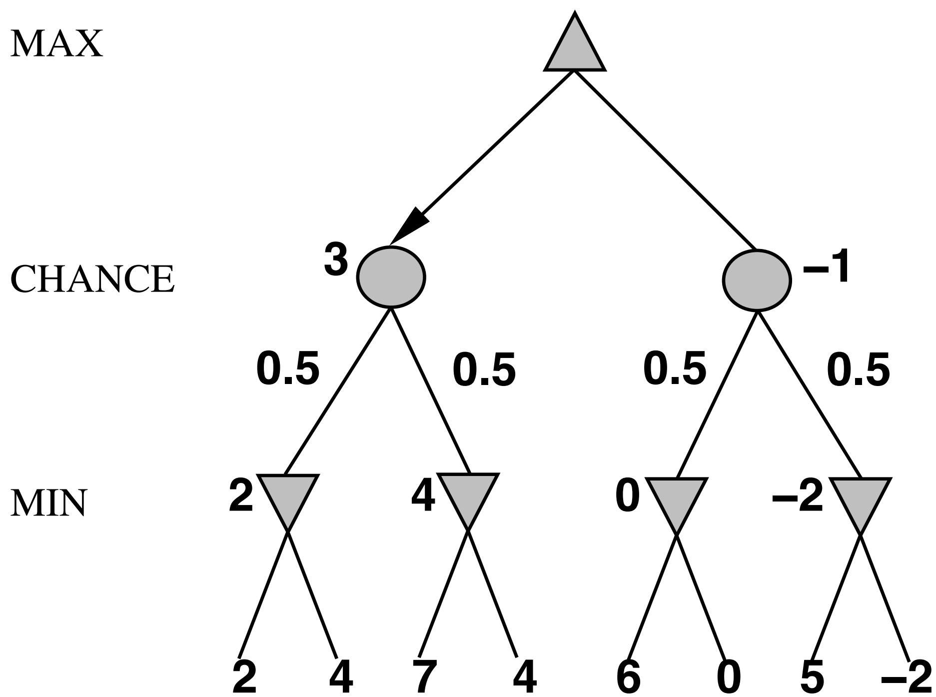
backgammon:



Expect-minimax

In nondeterministic games, chance introduced by dice, card-shuffling

Simplified example with coin-flipping:



$$\text{EXPECTIMINIMAX}(s) =$$
$$\begin{cases} \text{UTILITY}(s) & \text{if TERMINAL-TEST}(s) \\ \max_a \text{EXPECTIMINIMAX}(\text{RESULT}(s,a)) & \text{if PLAYER}(s) = \text{MAX} \\ \min_a \text{EXPECTIMINIMAX}(\text{RESULT}(s,a)) & \text{if PLAYER}(s) = \text{MIN} \\ \sum_r P(r)\text{EXPECTIMINIMAX}(\text{RESULT}(s,r)) & \text{if PLAYER}(s) = \text{CHANCE} \end{cases}$$

Nondeterministic games in practice

Dice rolls increase b: 21 possible rolls with 2 dice
Backgammon $\approx$ 20 legal moves (can be 6,000 with 1-1 roll)

$$\text{depth } 4 = 20 \times (21 \times 20)^3 \approx 1.2 \times 10^9$$

As depth increases, probability of reaching a given node shrinks
$\Rightarrow$ value of lookahead is diminished

α–β pruning is much less effective

TDGammon uses depth-2 search + very good Eval
$\approx$ world-champion level

Games of imperfect information

E.g., card games, where opponent's initial cards are unknown

Typically we can calculate a probability for each possible deal

Seems just like having one big dice roll at the beginning of the game*

Idea: compute the minimax value of each action in each deal,
then choose the action with highest expected value over all deals*

Special case: if an action is optimal for all deals, it's optimal.*

GIB, current best bridge program, approximates this idea by
1) generating 100 deals consistent with bidding information
2) picking the action that wins most tricks on average

Proper analysis

* Intuition that the value of an action is the average of its values in all actual states is **WRONG**

With partial observability, value of an action depends on the information state or belief state the agent is in

Can generate and search a tree of information states

Leads to rational behaviors such as
- ◇ Acting to obtain information
- ◇ Signalling to one's partner
- ◇ Acting randomly to minimize information disclosure