

Lecture 17: Learning 6

http://cs.nju.edu.cn/yuy/course_ai16.ashx



Previously...

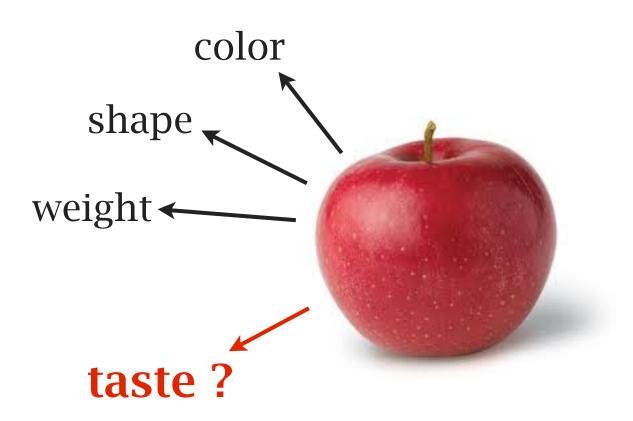
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Learning

Decision tree learning
Neural networks
Why we can learn
Linear models
Nearest neighbor classifier
Native Bayes classifier

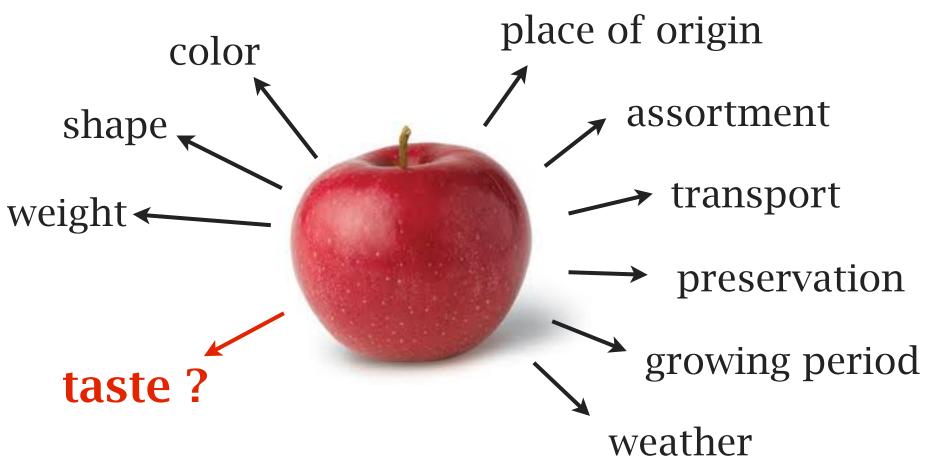
The importance of features





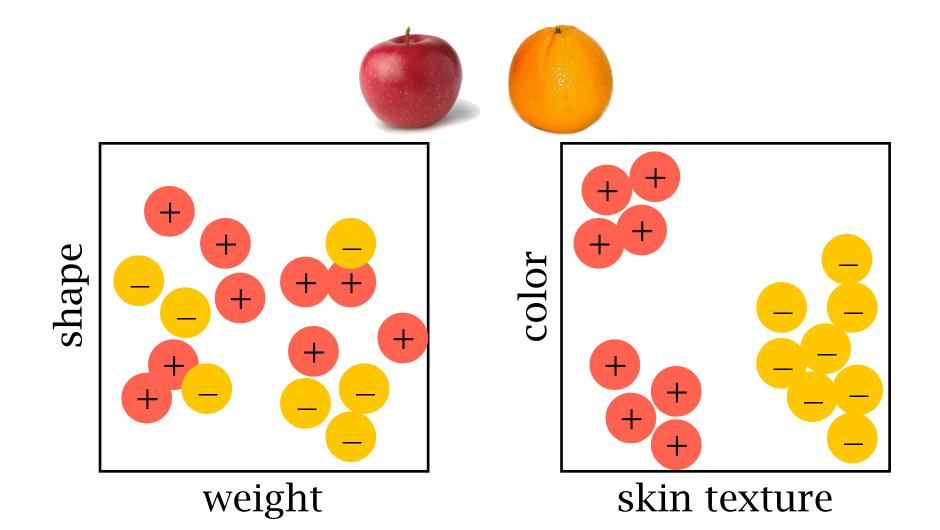
The importance of features





The importance of features

features determine the instance distribution good features lead to better learning results



Feature processing



a good feature set is more important than a good classifier

feature selection

feature extraction

Feature selection



To select a set of good features from a given feature set

Improve learning performance reduce classification error

Reduce the time/space complexity of learning

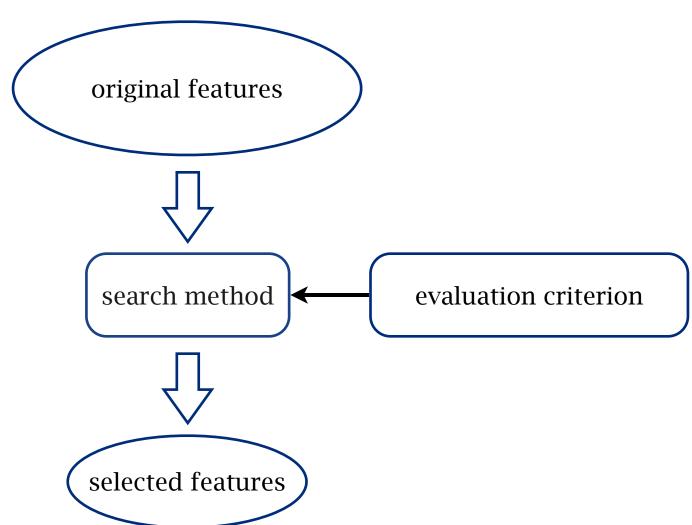
Improve the interpretability

Better data visualization

Saving the cost of observing features

Feature selection

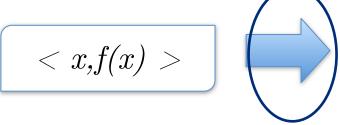




Evaluation criteria



classifier independent



dependency based criteria information based criteria distance based criteria classifier internal weighting

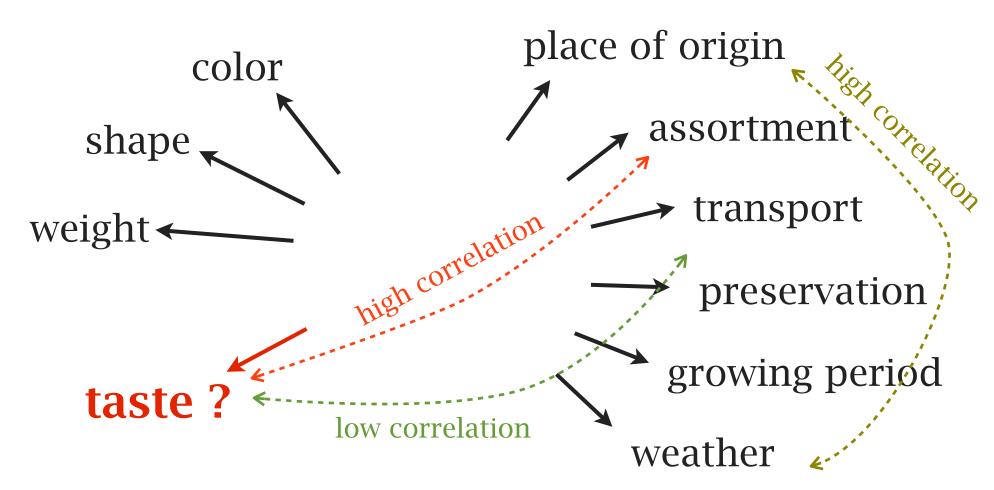
classifier dependent



Dependency based criteria

How a feature set is related with the class

correlation between a feature and the class correlation between two features search: select high correlated low redundant features



Information based criteria

How much a feature set provides information about the class



Information gain:

```
Entropy: H(X) = -\sum_{i} p_{i} \ln(p_{i})
```

Entropy after split:
$$I(X; \text{split}) = \sum_{j} \frac{\# \text{partition } j}{\# \text{all}} H(\text{partition } j)$$

Information gain: H(X)-I(X; split)

A simple forward search



sequentially add the next best feature

```
1: F = \text{original feature sets}, C \text{ is the class label}
2: S = \emptyset
3: loop
       a = the best correlated/informative feature in F
4:
      v = \text{the correlation/IG of } a
5:
6: if v < \theta then
           break
7:
8: end if
    F = F/\{a\}
9:
      S = S \cup \{a\}
10:
11: end loop
12: return S
```

A simple forward search

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1: F = \text{original feature sets}, C \text{ is the class label}
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       a = the best correlated/informative feature in F
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5:
    if v < \theta then
           break
7:
   end if
8:
    F = F/\{a\}
9:
   S = S \cup \{a\}
10:
   for a' \in F do
11:
           v' = the correlation/IG of a' to a
12:
           if v' > \alpha \cdot v then F = F/\{a'\}
13:
           end if
14:
       end for
15:
16: end loop
17: return S
```

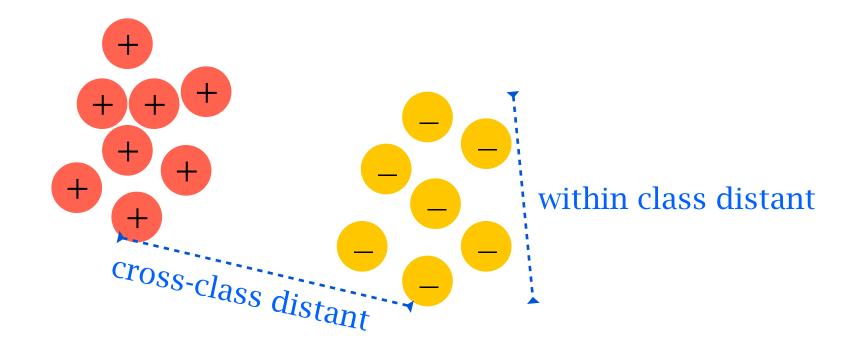


remove redundant features

Distance based criteria

Examples in the same class should be near Examples in different classes should be far





select features to optimize the distance

Distance based criteria



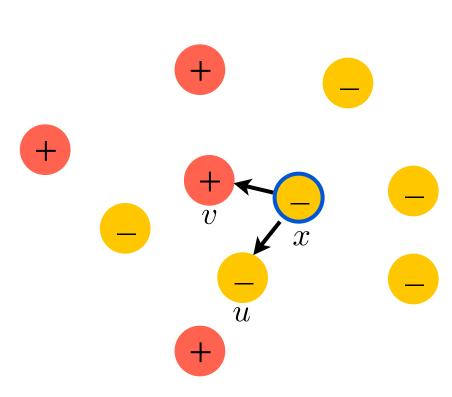
Relief: feature weighting based on distance

$$\mathbf{w} = 0$$

- 1. random select an instance *x*
- 2. find the nearest same-class instance u (according to *w*)
- 3. find the nearest diff-class instance v (according *w*)

4.
$$w = w - |x - u| + |x - v|$$

5. goto 1 for *m* times



select the features whose weights are above a threshold

Feature weighting from classifiers

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Many classification algorithms perform feature selection and weighting internally

decision tree: select a set of features by recursive IG

random forest: weight features by the frequency of using a feature

linear model: a natural feature weighting

select features from these models' internal feature weighting

note the difference to FS for classification



select features to maximize the performance of the following learning task

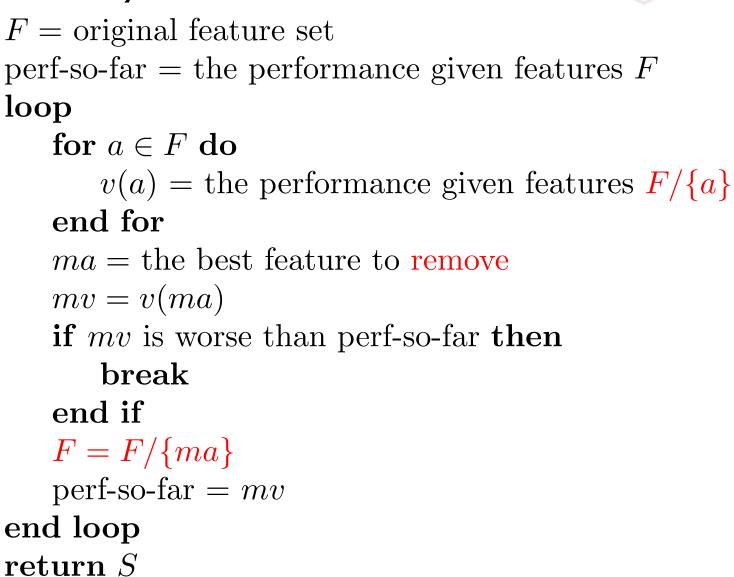
slow in speed hard to search hard to generalize the selection results

more accurate learning result

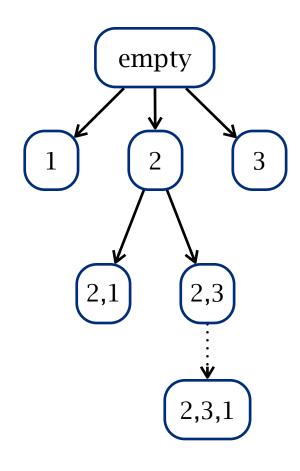
Sequential forward search: add features one-by-one

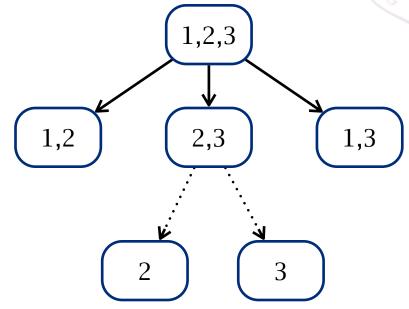
```
F = original feature set
S = \emptyset
perf-so-far = the worst performance value
loop
   for a \in F do
       v(a) = the performance given features S \cup \{a\}
   end for
   ma = the best feature
   mv = v(ma)
   if mv is worse than perf-so-far then
       break
   end if
   S = S \cup ma
   perf-so-far = mv
end loop
return S
```

Sequential backward search: remove features one-by-one



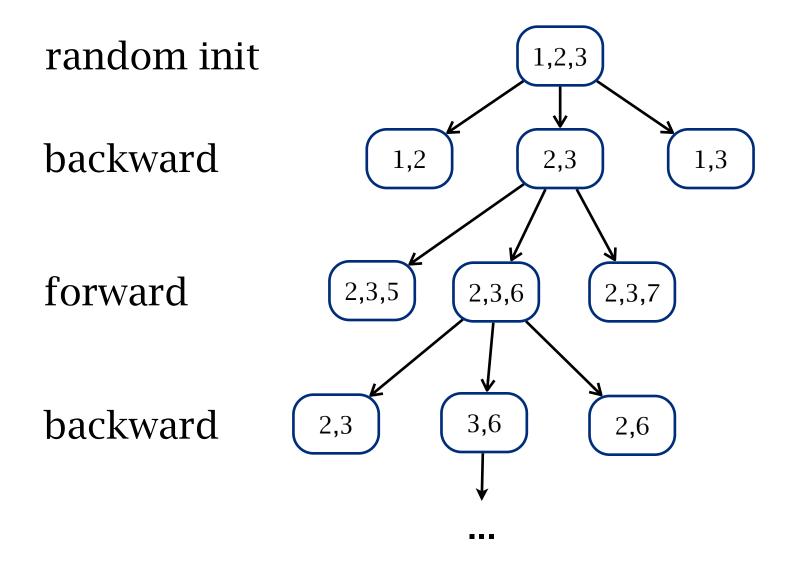






forward faster backward more accurate





combined forward-backward search

Feature extraction



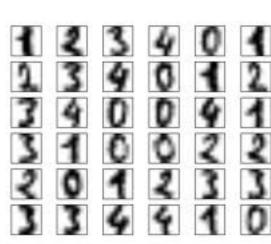
disclosure the inner structure of the data to support a better learning performance

feature extraction construct new features

commonly followed by a feature selection

usually used for low-level features

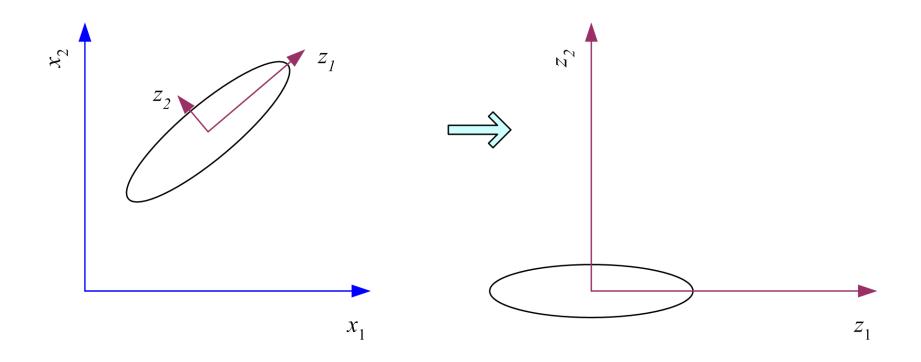
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Principal components analysis (PCA)

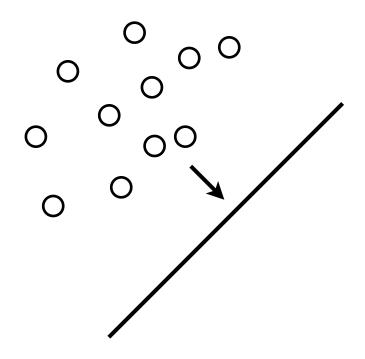
rotate the data to align the directions of the variance

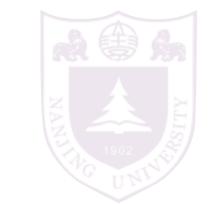


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Principal components analysis (PCA)

the first dimension = the largest variance direction

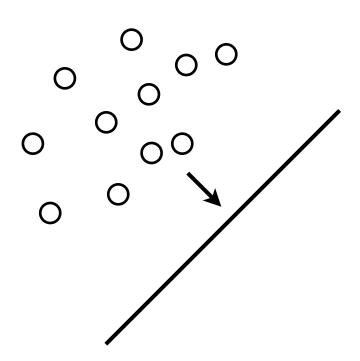




Principal components analysis (PCA)

the first dimension = the largest variance direction

$$z = \boldsymbol{w}^T \boldsymbol{x}$$

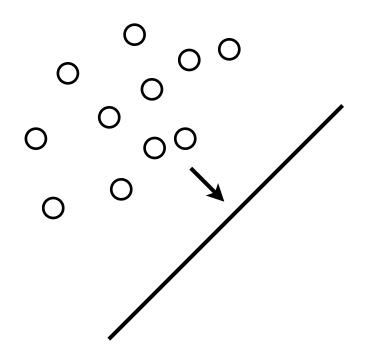




Principal components analysis (PCA)

the first dimension = the largest variance direction

$$z = \mathbf{w}^T \mathbf{x}$$
$$Var(z_1) = \mathbf{w}_1^T \mathbf{\Sigma} \mathbf{w}_1$$





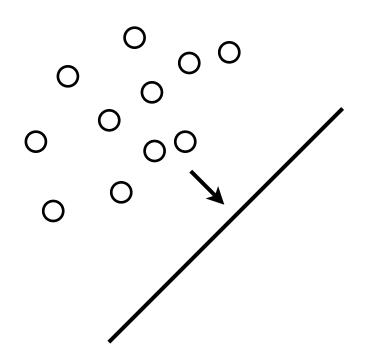
Principal components analysis (PCA)

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$$z = \mathbf{w}^T \mathbf{x}$$
$$Var(z_1) = \mathbf{w}_1^T \mathbf{\Sigma} \mathbf{w}_1$$

find a unit **w** to maximize the variance

$$\max_{\boldsymbol{w}_1} \boldsymbol{w}_1^T \boldsymbol{\Sigma} \boldsymbol{w}_1 - \alpha (\boldsymbol{w}_1^T \boldsymbol{w}_1 - 1)$$





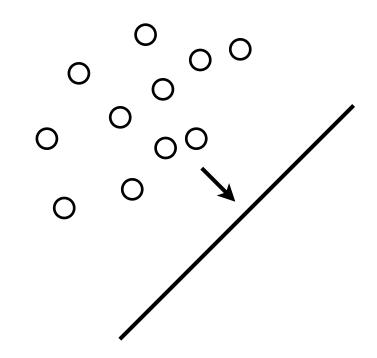
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$$2\Sigma w_1 - 2\alpha w_1 = 0$$
, and therefore $\Sigma w_1 = \alpha w_1$



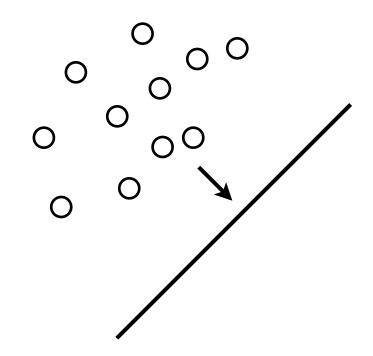
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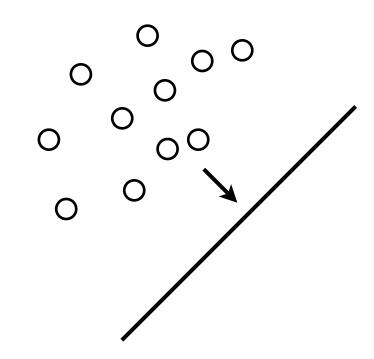
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$$\mathbf{w}_1^T \mathbf{\Sigma} \mathbf{w}_1 = \alpha \mathbf{w}_1^T \mathbf{w}_1 = \alpha$$

w is the eigenvector with the largest eigenvalue

Principal components analysis (PCA)



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Principal components analysis (PCA)

$$\max_{\boldsymbol{w}_2} \boldsymbol{w}_2^T \boldsymbol{\Sigma} \boldsymbol{w}_2 - \alpha (\boldsymbol{w}_2^T \boldsymbol{w}_2 - 1) - \beta (\boldsymbol{w}_2^T \boldsymbol{w}_1 - 0)$$



Principal components analysis (PCA)

$$\max_{\boldsymbol{w}_2} \boldsymbol{w}_2^T \boldsymbol{\Sigma} \boldsymbol{w}_2 - \alpha (\boldsymbol{w}_2^T \boldsymbol{w}_2 - 1) - \beta (\boldsymbol{w}_2^T \boldsymbol{w}_1 - 0)$$

$$2\Sigma w_2 - 2\alpha w_2 - \beta w_1 = 0$$



Principal components analysis (PCA)

$$\max_{\boldsymbol{w}_2} \boldsymbol{w}_2^T \boldsymbol{\Sigma} \boldsymbol{w}_2 - \alpha (\boldsymbol{w}_2^T \boldsymbol{w}_2 - 1) - \beta (\boldsymbol{w}_2^T \boldsymbol{w}_1 - 0)$$

$$2\Sigma w_2 - 2\alpha w_2 - \beta w_1 = 0$$

$$\beta = 0$$
 $\Sigma w_2 = \alpha w_2$



Principal components analysis (PCA)

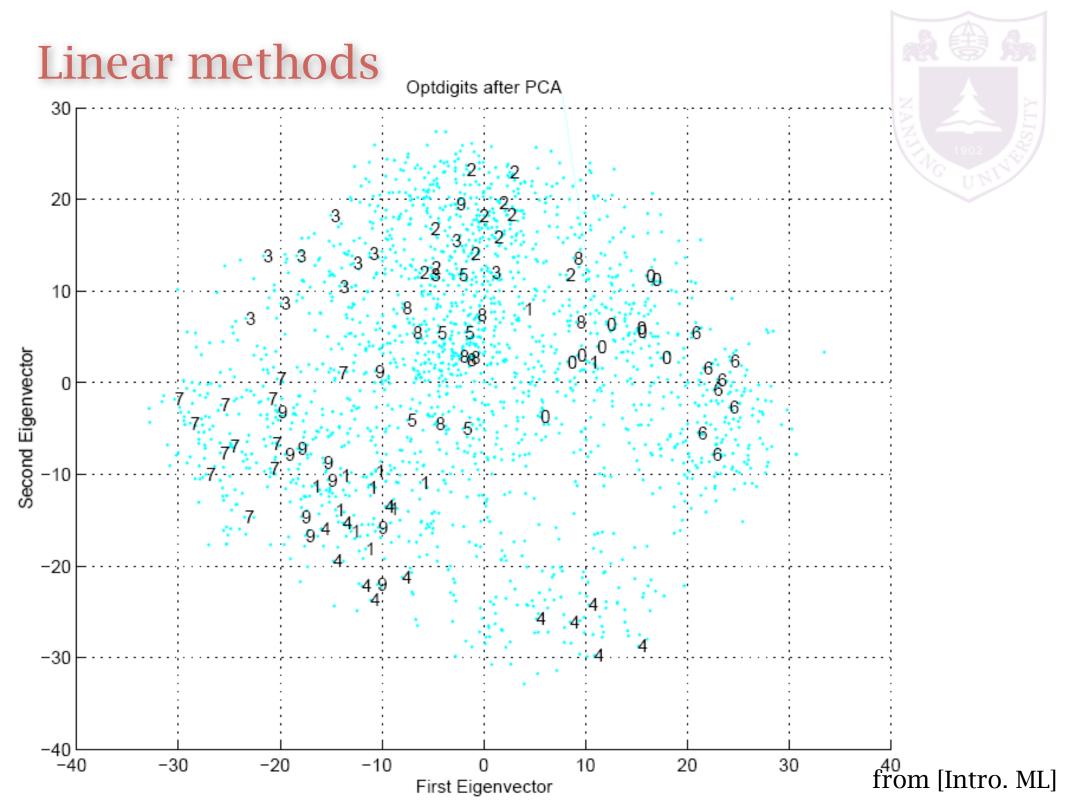
the second dimension = the largest variance direction orthogonal to the first dimension

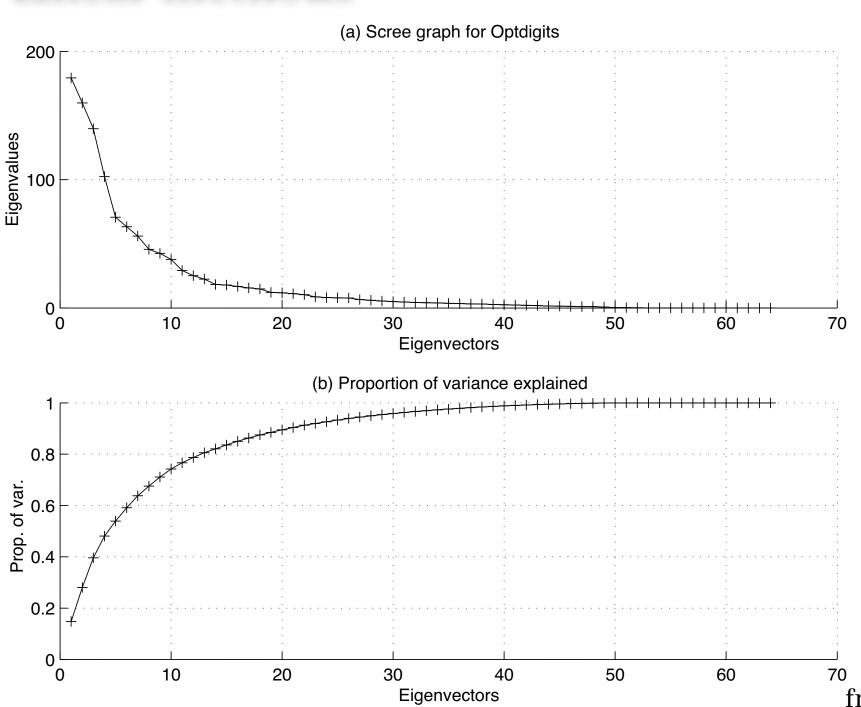
$$\max_{\mathbf{w}_2} \mathbf{w}_2^T \mathbf{\Sigma} \mathbf{w}_2 - \alpha (\mathbf{w}_2^T \mathbf{w}_2 - 1) - \beta (\mathbf{w}_2^T \mathbf{w}_1 - 0)$$

$$2\Sigma w_2 - 2\alpha w_2 - \beta w_1 = 0$$

$$\beta = 0$$
 $\Sigma w_2 = \alpha w_2$

w's are the eigenvectors sorted by the eigenvalues







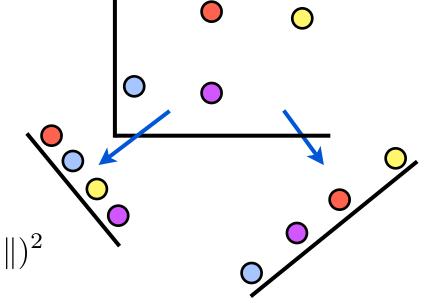
from [Intro. ML]

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Multidimensional Scaling (MDS)

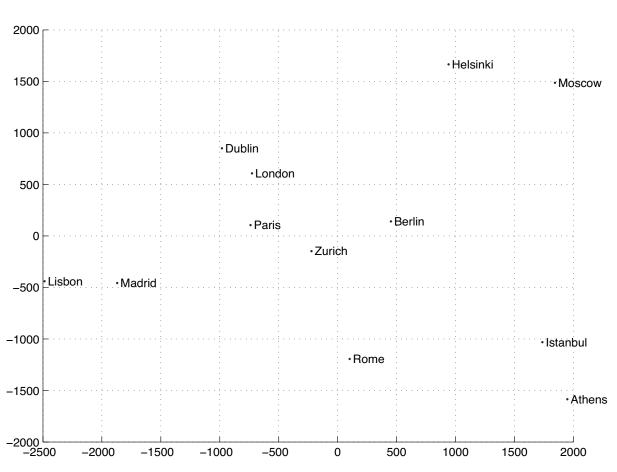
keep the distance into a lower dimensional space

for linear transformation, W is an n*k matrix



$$\arg\min_{W} \sum_{i,j} (\|\boldsymbol{x}_{i}^{\top}W - \boldsymbol{x}_{j}^{\top}W\| - \|\boldsymbol{x}_{i} - \boldsymbol{x}_{j}\|)^{2}$$







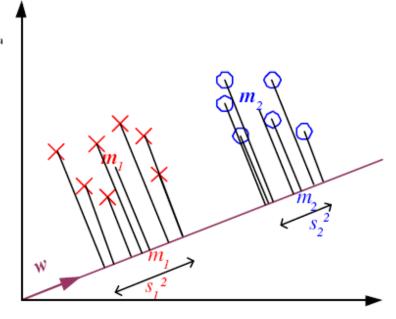
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Linear Discriminant Analysis (LDA)

find a direction such that the two classes are well separated *

$$z = \boldsymbol{w}^T \boldsymbol{x}$$

m be the mean of a class s^2 be the variance of a class



maximize the criterion

$$J(\mathbf{w}) = \frac{(m_1 - m_2)^2}{s_1^2 + s_2^2}$$



$$(m_1 - m_2)^2 = (\mathbf{w}^T \mathbf{m}_1 - \mathbf{w}^T \mathbf{m}_2)^2$$

$$= \mathbf{w}^T (\mathbf{m}_1 - \mathbf{m}_2) (\mathbf{m}_1 - \mathbf{m}_2)^T \mathbf{w}$$

$$= \mathbf{w}^T \mathbf{S}_B \mathbf{w}$$



$$(m_1 - m_2)^2 = (\mathbf{w}^T \mathbf{m}_1 - \mathbf{w}^T \mathbf{m}_2)^2$$

$$= \mathbf{w}^T (\mathbf{m}_1 - \mathbf{m}_2) (\mathbf{m}_1 - \mathbf{m}_2)^T \mathbf{w}$$

$$= \mathbf{w}^T \mathbf{S}_B \mathbf{w}$$

$$s_1^2 = \sum_t (\mathbf{w}^T \mathbf{x}^t - \mathbf{m}_1)^2 r^t$$

$$= \sum_t \mathbf{w}^T (\mathbf{x}^t - \mathbf{m}_1) (\mathbf{x}^t - \mathbf{m}_1)^T \mathbf{w} r^t$$

$$= \mathbf{w}^T \mathbf{S}_1 \mathbf{w}$$



$$(m_{1} - m_{2})^{2} = (w^{T} m_{1} - w^{T} m_{2})^{2}$$

$$= w^{T} (m_{1} - m_{2}) (m_{1} - m_{2})^{T} w$$

$$= w^{T} S_{B} w$$

$$s_{1}^{2} = \sum_{t} (w^{T} x^{t} - m_{1})^{2} r^{t}$$

$$= \sum_{t} w^{T} (x^{t} - m_{1}) (x^{t} - m_{1})^{T} w r^{t}$$

$$= w^{T} S_{1} w$$

$$s_{1}^{2} + s_{2}^{2} = w^{T} S_{W} w \qquad S_{W} = S_{1} + S_{2}$$



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Linear Discriminant Analysis (LDA)

$$(m_{1} - m_{2})^{2} = (w^{T} m_{1} - w^{T} m_{2})^{2}$$

$$= w^{T} (m_{1} - m_{2}) (m_{1} - m_{2})^{T} w$$

$$= w^{T} S_{B} w$$

$$s_{1}^{2} = \sum_{t} (w^{T} x^{t} - m_{1})^{2} r^{t}$$

$$= \sum_{t} w^{T} (x^{t} - m_{1}) (x^{t} - m_{1})^{T} w r^{t}$$

$$= w^{T} S_{1} w$$

$$s_{1}^{2} + s_{2}^{2} = w^{T} S_{W} w \qquad S_{W} = S_{1} + S_{2}$$

The objective becomes:

$$J(\mathbf{w}) = \frac{(\mathbf{m}_1 - \mathbf{m}_2)^2}{s_1^2 + s_2^2} = \frac{\mathbf{w}^T \mathbf{S}_B \mathbf{w}}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}} = \frac{|\mathbf{w}^T (\mathbf{m}_1 - \mathbf{m}_2)|^2}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}}$$



Linear Discriminant Analysis (LDA)

The objective becomes:

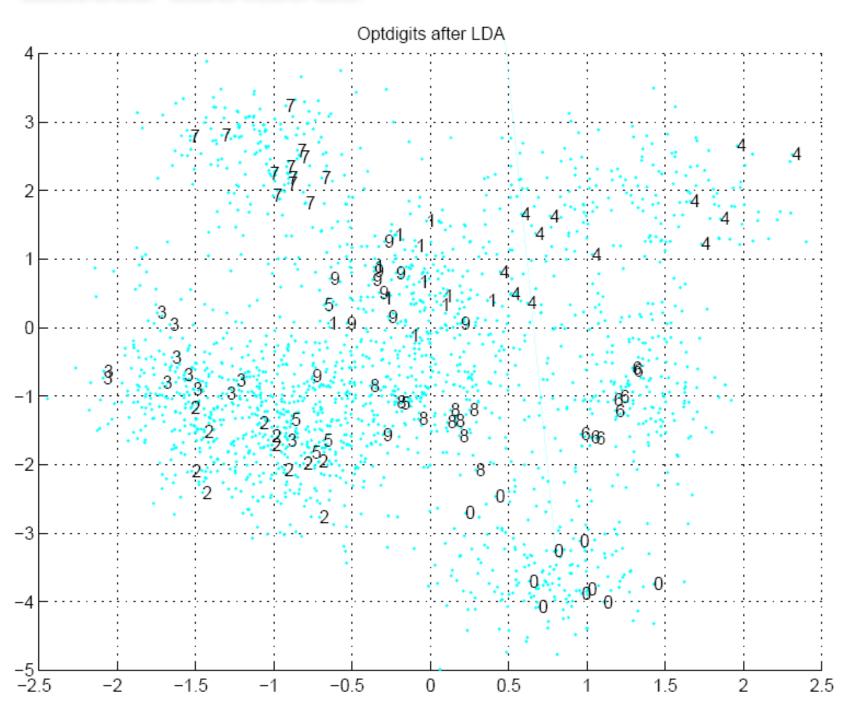
$$J(w) = \frac{(m_1 - m_2)^2}{s_1^2 + s_2^2} = \frac{w^T S_B w}{w^T S_W w} = \frac{|w^T (m_1 - m_2)|^2}{w^T S_W w}$$

$$\frac{\mathbf{w}^T(\mathbf{m}_1 - \mathbf{m}_2)}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}} \left(2(\mathbf{m}_1 - \mathbf{m}_2) - \frac{\mathbf{w}^T(\mathbf{m}_1 - \mathbf{m}_2)}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}} \mathbf{S}_W \mathbf{w} \right) = 0$$

Given that $\mathbf{w}^T (\mathbf{m}_1 - \mathbf{m}_2) / \mathbf{w}^T \mathbf{S}_W \mathbf{w}$ is a constant, we have

$$\boldsymbol{w} = c\mathbf{S}_W^{-1}(\boldsymbol{m}_1 - \boldsymbol{m}_2)$$

just take c = 1 and find w





from [Intro. ML]

Example: Face recognition

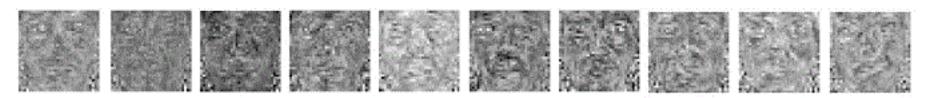


PCA and LDA are commonly used to extract features for face recognition.

Basis of eigenface (PCA):

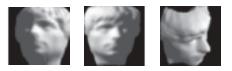


Basis of Fisherface (LDA):

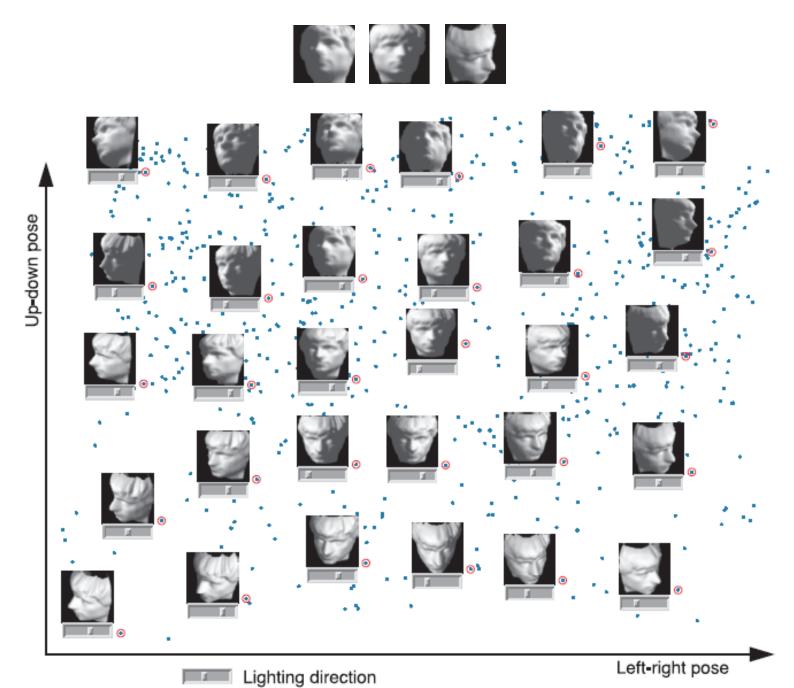








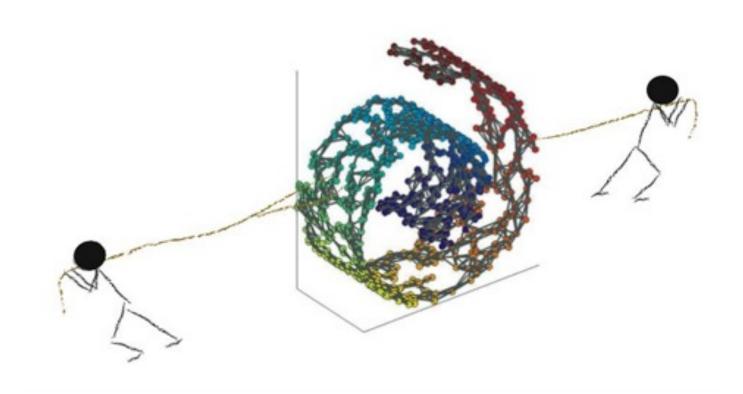






A low intrinsic dimensional data embedded in a high dimensional space

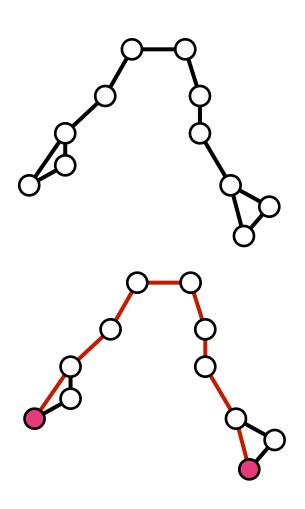
cause a bad distance measure



ISOMAP

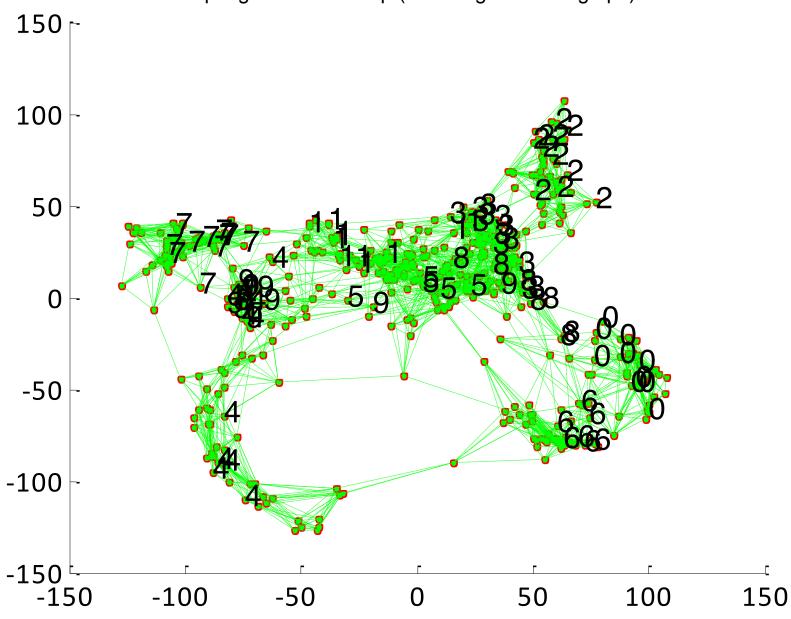
- 1. construct a neighborhood graph (kNN and ε -NN)
- 2. calculate distance matrix as the shortest path on the graph
- 3. apply MDS on the distance matrix





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Optdigits after Isomap (with neighborhood graph).





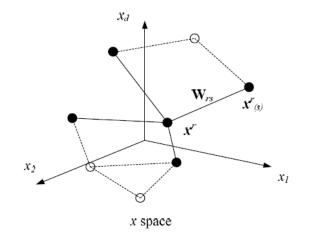
Local Linear Embedding (LLE):

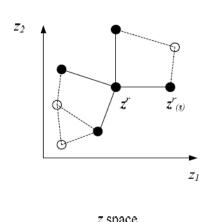
- 1. find neighbors for each instance
- 2. calculate a linear reconstruction for an instance

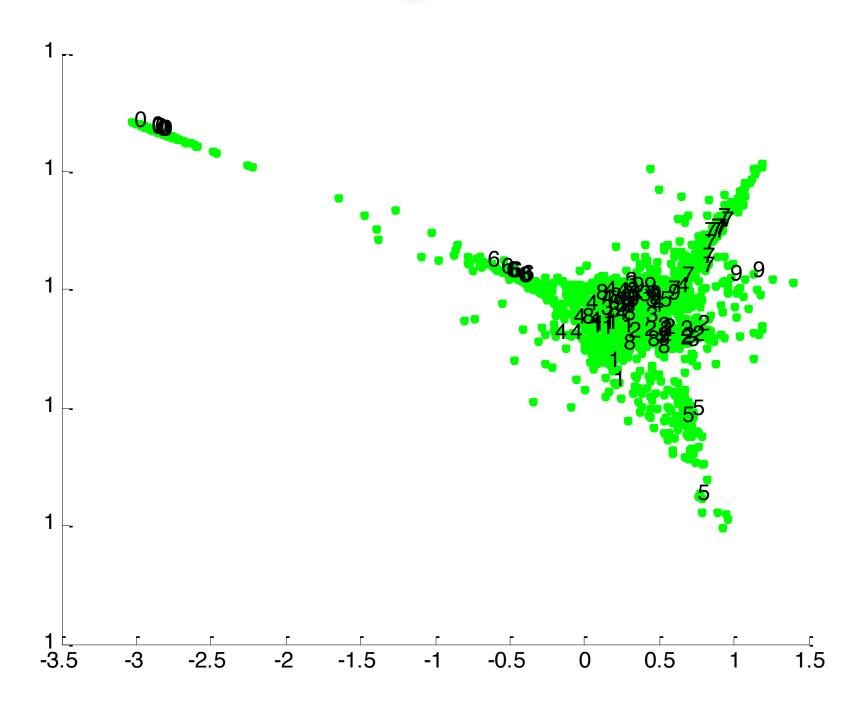
$$\sum_{r} \|\boldsymbol{x}^{r} - \sum_{s} \mathbf{W}_{rs} \boldsymbol{x}_{(r)}^{s}\|^{2}$$

3. find low dimensional instances preserving the reconstruction

$$\sum_{r} \|\mathbf{z}^r - \sum_{s} \mathbf{W}_{rs} \mathbf{z}^s\|^2$$



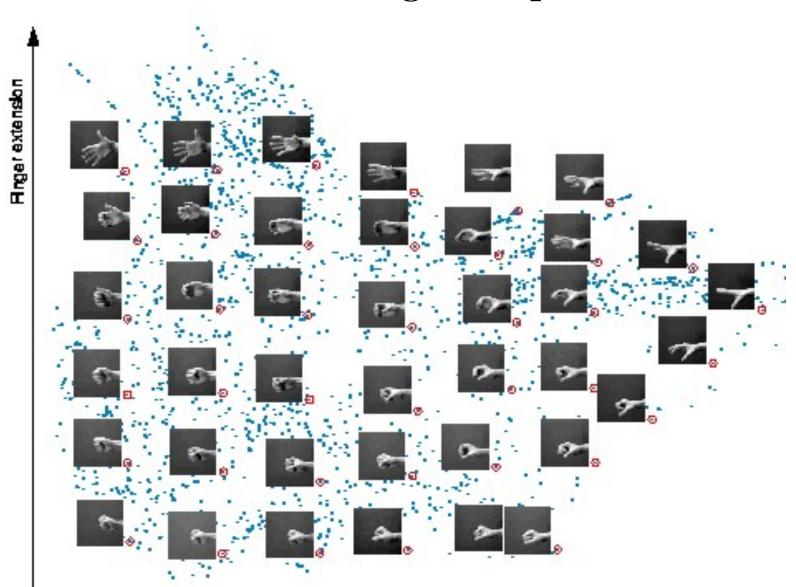






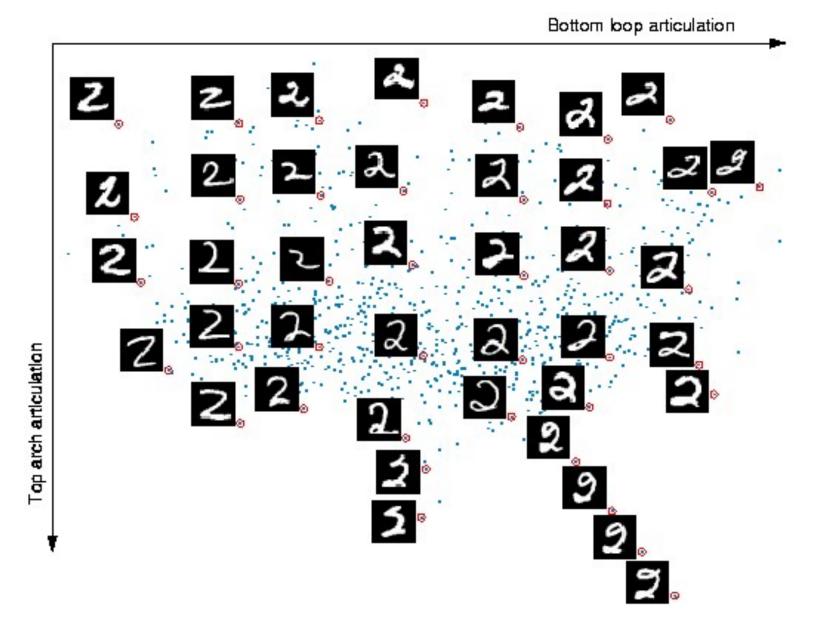
from [Intro. ML]

more manifold learning examples





more manifold learning examples



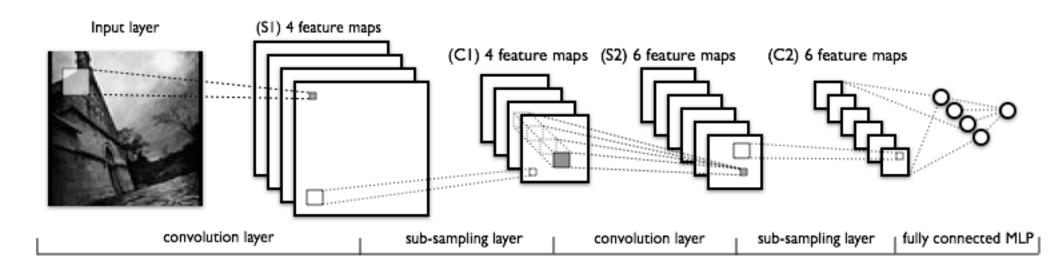


Other feature extraction methods

Most feature extractions are case specific



Convolutional Neural Networks (CNN/LeNet) for general image feature extraction



A summary of approaches

