

Lecture 17: Learning 5

http://cs.nju.edu.cn/yuy/course_ai15.ashx



Previously...

Learning

Decision tree learning Neural networks Why we can learn Linear models





Nearest Neighbor Classifier

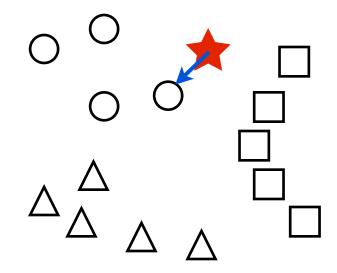
Nearest neighbor

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what looks similar are similar

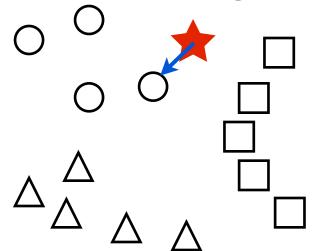


Nearest neighbor

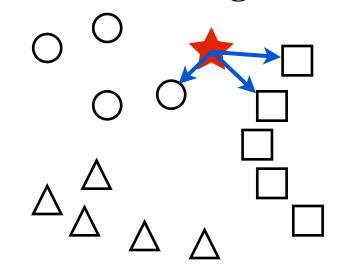


for classification:

1-nearest neighbor:



k-nearest neighbor:



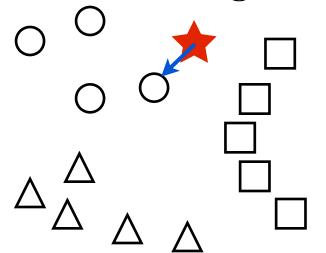
Predict the label as that of the NN or the (weighted) majority of the k-NN

Nearest neighbor

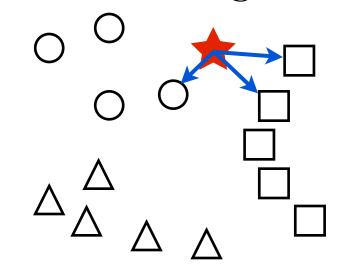


for regression:

1-nearest neighbor:



k-nearest neighbor:

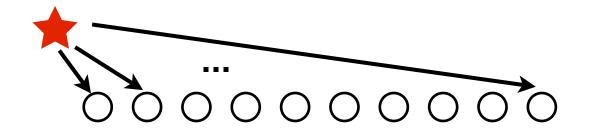


Predict the label as that of the NN or the (weighted) *average* of the k-NN

Search for the nearest neighbor



Linear search



n times of distance calculations $O(dn \ln k)$ d is the dimension, n is the number of samples

Nearest neighbor classifier



- ▶ as classifier, asymptotically less than 2 times of the optimal Bayes error
- naturally handle multi-class
- no training time
- nonlinear decision boundary
- slow testing speed for a large training data set
- have to store the training data
- sensitive to similarity function

nonparametric method



Naive Bayes Classifier

Bayes rule



classification using posterior probability

for binary classification

$$f(x) = \begin{cases} +1, & P(y = +1 \mid \boldsymbol{x}) > P(y = -1 \mid \boldsymbol{x}) \\ -1, & P(y = +1 \mid \boldsymbol{x}) < P(y = -1 \mid \boldsymbol{x}) \end{cases}$$
random, otherwise

in general

$$f(x) = \arg\max_{y} P(y \mid \boldsymbol{x})$$

Bayes rule



classification using posterior probability

for binary classification

$$f(x) = \begin{cases} +1, & P(y = +1 \mid \boldsymbol{x}) > P(y = -1 \mid \boldsymbol{x}) \\ -1, & P(y = +1 \mid \boldsymbol{x}) < P(y = -1 \mid \boldsymbol{x}) \\ \text{random}, & otherwise \end{cases}$$

in general

$$f(x) = \underset{y}{\operatorname{arg max}} P(y \mid \boldsymbol{x})$$

$$= \underset{y}{\operatorname{arg max}} P(\boldsymbol{x} \mid y) P(y) / P(\boldsymbol{x})$$

$$= \underset{y}{\operatorname{arg max}} P(\boldsymbol{x} \mid y) P(y)$$

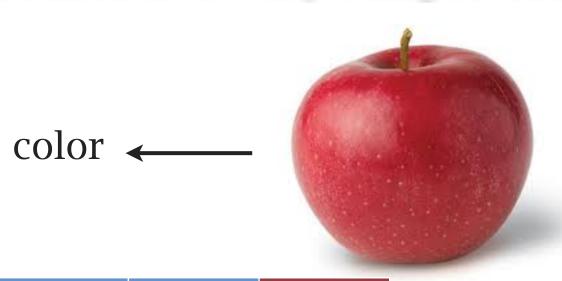
how the probabilities be estimated

$$f(x) = \operatorname*{arg\,max}_{y} P(\boldsymbol{x} \mid y) P(y)$$

estimation the a priori by frequency:

$$P(y) \leftarrow \tilde{P}(y) = \frac{1}{m} \sum_{i} I(y_i = y)$$







id	color	taste
1	red	sweet
2	red	sweet
3	half-red	not-sweet
4	not-red	not-sweet
5	not-red	not-sweet
6	half-red	not-sweet
7	red	sweet
8	not-red	not-sweet
9	not-red	not-sweet
10	half-red	not-sweet
11	red	sweet
12	half-red	not-sweet
13	not-red	not-sweet

$$P(\text{red} \mid \text{sweet}) = 1$$
 $P(\text{half-red} \mid \text{sweet}) = 0$
 $P(\text{not-red} \mid \text{sweet}) = 0$
 $P(\text{sweet}) = 4/13$
 $P(\text{red} \mid \text{not-sweet}) = 0$
 $P(\text{half-red} \mid \text{not-sweet}) = 4/9$
 $P(\text{not-red} \mid \text{not-sweet}) = 5/9$
 $P(\text{not-sweet}) = 9/13$

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7	red	sweet
8	not-red	not-sweet
9	not-red	not-sweet
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what the *f'* would be?

$$f(x) = \operatorname*{arg\,max}_{y} P(\boldsymbol{x} \mid y) P(y)$$

color	taste
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red	sweet
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not-red	not-sweet
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half-red	not-sweet
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half-red	not-sweet
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what the *f'* would be?

$$f(x) = \operatorname*{arg\,max}_{y} P(\boldsymbol{x} \mid y) P(y)$$

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 $P(\text{red} \mid \text{not-sweet})P(\text{not-sweet}) = 0$

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$$P(\text{red} \mid \text{sweet})P(\text{sweet}) = 4/13$$

 $P(\text{red} \mid \text{not-sweet})P(\text{not-sweet}) = 0$

$$P(\text{half-red} \mid \text{sweet})P(\text{sweet}) = 0$$

$$P(\text{half-red} \mid \text{not-sweet})P(\text{not-sweet}) = \frac{4}{9} \times \frac{9}{13} = \frac{4}{13}$$

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what the *f'* would be?

$$f(x) = \arg\max_{y} P(\boldsymbol{x} \mid y) P(y)$$

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$$P(\text{half-red} \mid \text{not-sweet})P(\text{not-sweet}) = \frac{4}{9} \times \frac{9}{13} = \frac{4}{13}$$

perfect but not realistic

$$f(x) = \operatorname*{arg\,max}_{y} P(\boldsymbol{x} \mid y) P(y)$$



estimation the a priori by frequency:

$$P(y) \leftarrow \tilde{P}(y) = \frac{1}{m} \sum_{i} I(y_i = y)$$

assume features are conditional independence given the class (naive assumption):

$$P(\boldsymbol{x} \mid y) = P(x_1, x_2, \dots, x_n \mid y)$$

= $P(x_1 \mid y) \cdot P(x_2 \mid y) \cdot \dots P(x_n \mid y)$

decision function:

$$f(x) = \arg\max_{y} \tilde{P}(y) \prod_{i} \tilde{P}(x_i \mid y)$$

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color	weight	sweet?
3	4	yes
2	3	yes
0	3	no
3	2	no
1	4	no

$$P(y = yes) = 2/5$$

 $P(y = no) = 3/5$
 $P(color = 3 | y = yes) = 1/2$

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$$P(y = yes) = 2/5$$

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$$P(color = 3 \mid y = yes) = 1/2$$

$$f(y \mid color = 3, weight = 3) \rightarrow$$

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$$P(y = yes) = 2/5$$

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$$P(color = 3 \mid y = yes) = 1/2$$

$$f(y \mid color = 3, weight = 3) \rightarrow P(color = 3 \mid y = yes)P(weight = 3 \mid y = yes)P(y = yes) = 0.5 \times 0.5 \times 0.4 = 0.1$$

 $P(color = 3 \mid y = no)P(weight = 3 \mid y = no)P(y = no) = 0.33 \times 0.33 \times 0.6 = 0.06$

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$$f(y \mid color = 3, weight = 3) \rightarrow \\ P(color = 3 \mid y = yes)P(weight = 3 \mid y = yes)P(y = yes) = 0.5 \times 0.5 \times 0.4 = 0.1 \\ P(color = 3 \mid y = no)P(weight = 3 \mid y = no)P(y = no) = 0.33 \times 0.33 \times 0.6 = 0.06$$

$$f(y \mid color = 0, weight = 1) \rightarrow$$

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color	weight	sweet?
3	4	yes
2	3	yes
0	3	no
3	2	no
1	4	no

$$P(y = yes) = 2/5$$

$$P(y = no) = 3/5$$

$$P(color = 3 \mid y = yes) = 1/2$$

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 $P(color = 3 \mid y = no)P(weight = 3 \mid y = no)P(y = no) = 0.33 \times 0.33 \times 0.6 = 0.06$

$$f(y \mid color = 0, weight = 1) \rightarrow$$

$$P(color = 0 \mid y = yes)P(weight = 1 \mid y = yes)P(y = yes) = 0$$

$$P(color = 0 \mid y = no)P(weight = 1 \mid y = no)P(y = no) = 0$$

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$color=\{0,1,2,3\}$ weight= $\{0,1,2,3,4\}$

color	weight	sweet?
3	4	yes
2	3	yes
0	3	no
3	2	no
1	4	no

color	sweet?
0	yes
1	yes
2	yes
3	yes

smoothed (Laplacian correction) probabilities:

$$P(color = 0 \mid y = yes) = (0+1)/(2+4)$$

 $P(y = yes) = (2+1)/(5+2)$

for counting frequency, assume every event has happened once.

$$f(y \mid color = 0, weight = 1) \rightarrow P(color = 0 \mid y = yes)P(weight = 1 \mid y = yes)P(y = yes) = \frac{1}{6} \times \frac{1}{7} \times \frac{3}{7} = 0.01$$

$$P(color = 0 \mid y = no)P(weight = 1 \mid y = no)P(y = no) = \frac{2}{7} \times \frac{1}{8} \times \frac{4}{7} = 0.02$$



```
advantages:
    very fast:
      scan the data once, just count: O(mn)
      store class-conditional probabilities: O(n)
      test an instance: O(cn) (c the number of classes)
    good accuracy in many cases
    parameter free
    output a probability
    naturally handle multi-class
disadvantages:
```



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    parameter free
    output a probability
    naturally handle multi-class
disadvantages:
```

the strong assumption may harm the accuracy does not handle numerical features naturally



Ensemble Learning

How can we improve an algorithm



for free

one classifier with error 0.49

How can we improve an algorithm



for free

one classifier with error 0.49

three independent classifiers each with error 0.49

two out of three are wrong: 0.367353

three of them are wrong: 0.117649

majority of the three are wrong: 0.485002

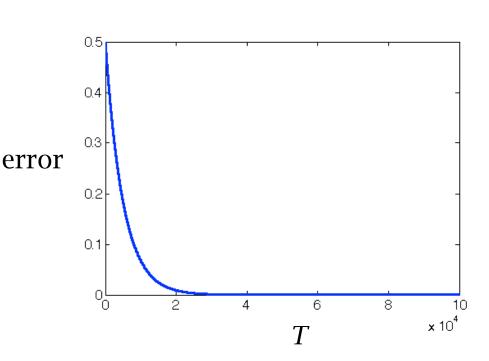
Motivation theories

for binary classification, what if the classifiers give *independent* output and are little bit better than random guess?

each classifier has error 0.49 error of combining T classifiers:

$$\sum_{t=\lceil T/2 \rceil}^{T} {T \choose t} \cdot 0.49^{t} \cdot 0.51^{T-t}$$

$$\leq \frac{1}{2} e^{-2T(0.5-0.49)^{2}}$$



Motivation theories

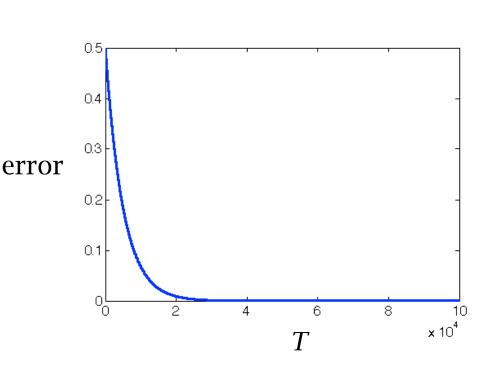
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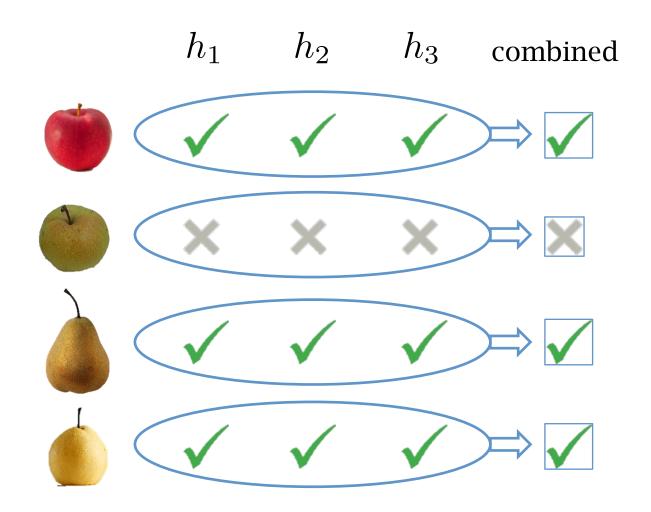
but independent classifiers are not achievable



The importance of diversity



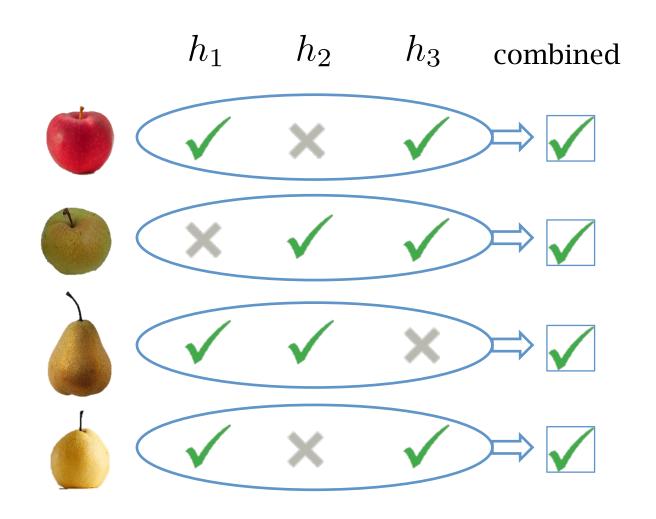
not useful to combine identical base learners



The importance of diversity

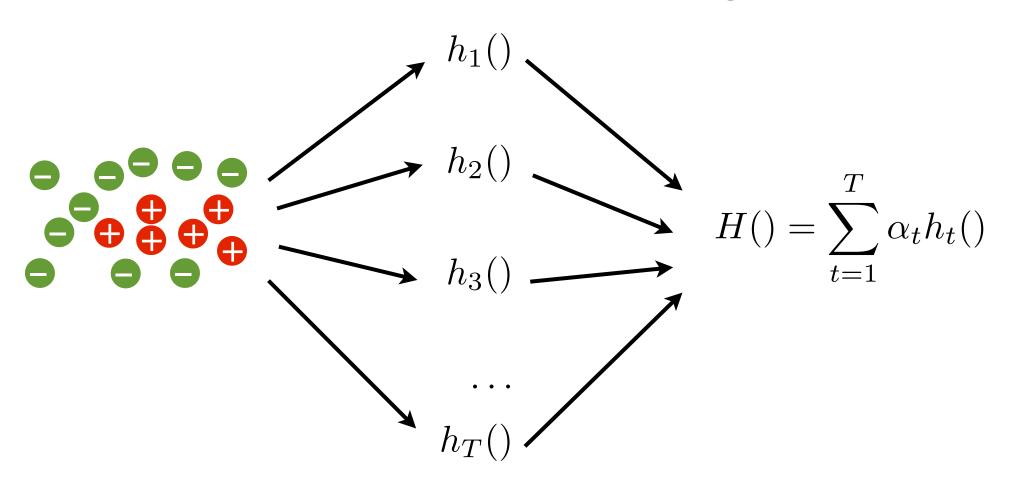


good to combine different learners



Ensemble learning

combination of multiple classifiers/regressors



base learner

combined learner

Ensemble methods



Parallel ensemble

create diverse base learners by introducing randomness

Sequential ensemble

create base learners by complementarity

Parallel ensemble methods



Diversity generating categories:

Data Sample Manipulation bootstrap sampling/Bagging

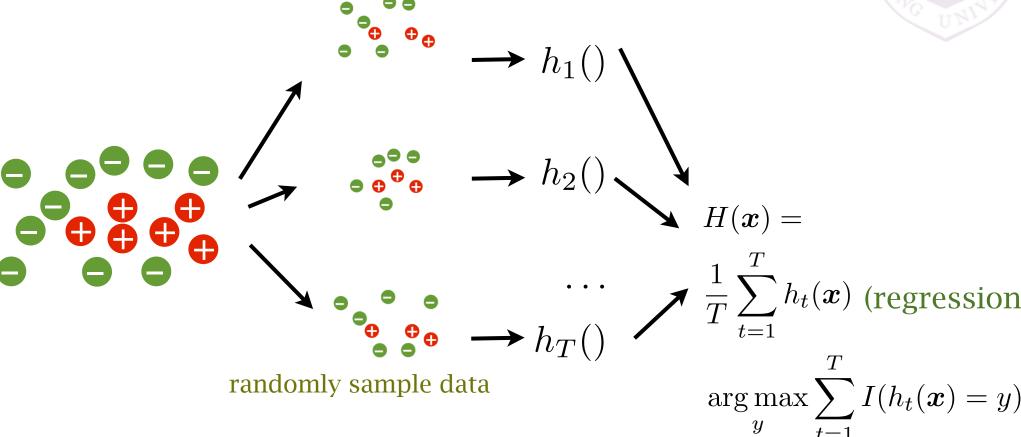
Input Feature Manipulation random subspace

Output Representation Manipulation flipping output/output smearing

Learning Parameter Manipulation random initialization Random Forests

combine two or more categories

Data Sample Manipulation: Bagging



Base classifiers should be sensitive to sampling

- » decision tree, neural network are good
- » NB, linear classifier are not

Good for handling large data set



(classification)

Data Sample Manipulation: Bagging

Input: *D*: Data set $\{(x_1, y_1), (x_2, y_2), \dots, (x_m, y_m)\};$

£: Base learning algorithm;

T: Number of base learners.

Process:

- 1. **for** t = 1, ..., T:
- 2. $h_t = \mathfrak{L}(D, \mathfrak{D}_{bs})$ % \mathfrak{D}_{bs} is the bootstrap distribution
- 3. **end**

Output:
$$H(\boldsymbol{x}) = \max_{y \in \mathcal{Y}} \sum_{t=1}^{T} \mathbb{I}(h_t(\boldsymbol{x}) = y)$$

sample with replacement

Base classifiers should be sensitive to sampling

- » decision tree, neural network are good
- » NB, linear classifier are not

Good for handling large data set

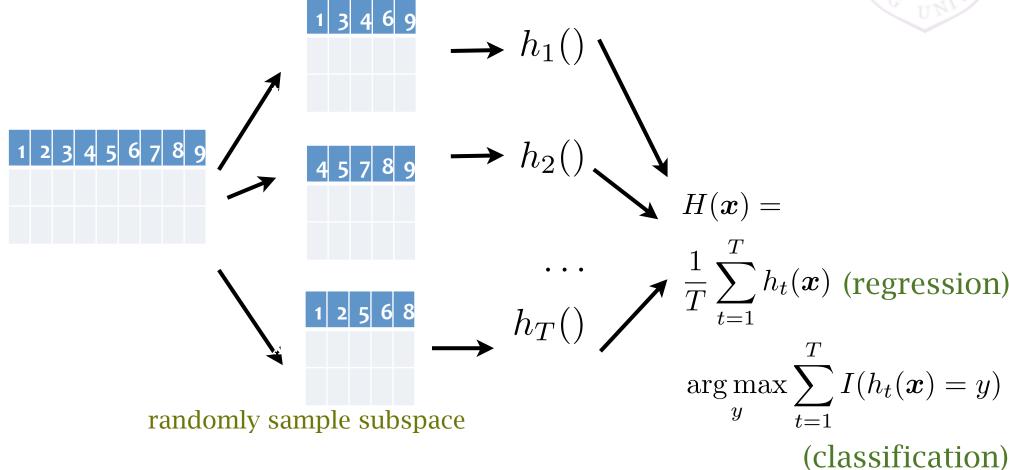




Leo Breiman 1928-2005

Input Feature Manipulation: Random subspace





Data should be rich in features Good for handling high dimensional data

Input Feature Manipulation: Random subspace

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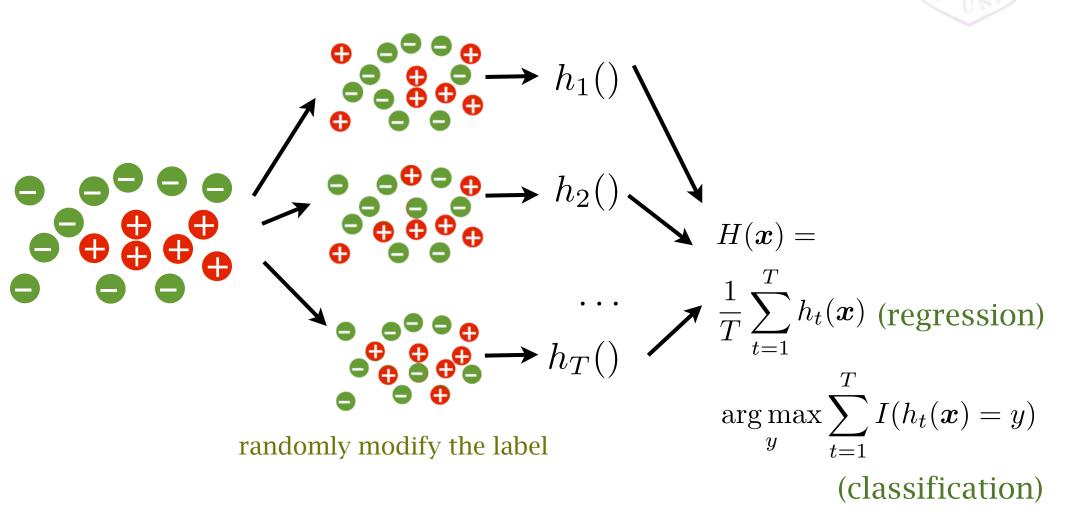
```
Input: D: Data set \{(\boldsymbol{x}_1, y_1), (\boldsymbol{x}_2, y_2), \cdots, (\boldsymbol{x}_m, y_m)\}; \mathcal{L}: Base learning algorithm; T: Number of base learners; d: Dimension of subspaces.
```

```
Process:
1. for t = 1, ..., T:
2. \mathcal{F}_t = RS(D, d) % \mathcal{F}_t is a set of d randomly selected features;
3. D_t = Map_{\mathcal{F}_t}(D) % D_t keeps only the features in \mathcal{F}_t
4. h_t = \mathfrak{L}(D_t) % Train a learner
5. end
```

Output:
$$H(\boldsymbol{x}) = \max_{y \in \mathcal{Y}} \sum_{t=1}^{T} \mathbb{I}\left(h_t\left(Map_{\mathcal{F}_t}\left(\boldsymbol{x}\right)\right) = y\right)$$

Data should be rich in features Good for handling high dimensional data

Output Representation Manipulation: Output flipping



May drastically reduce the accuracy of base learners

Learning Parameter Manipulation: Random forest

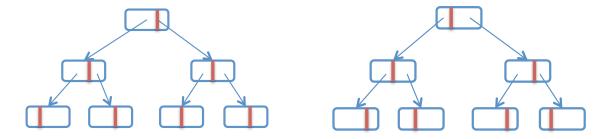
Randomized decision tree

at each node

- 1. randomly select a subset of features
- 2. use select a feature (and split point) from the subset to split the data

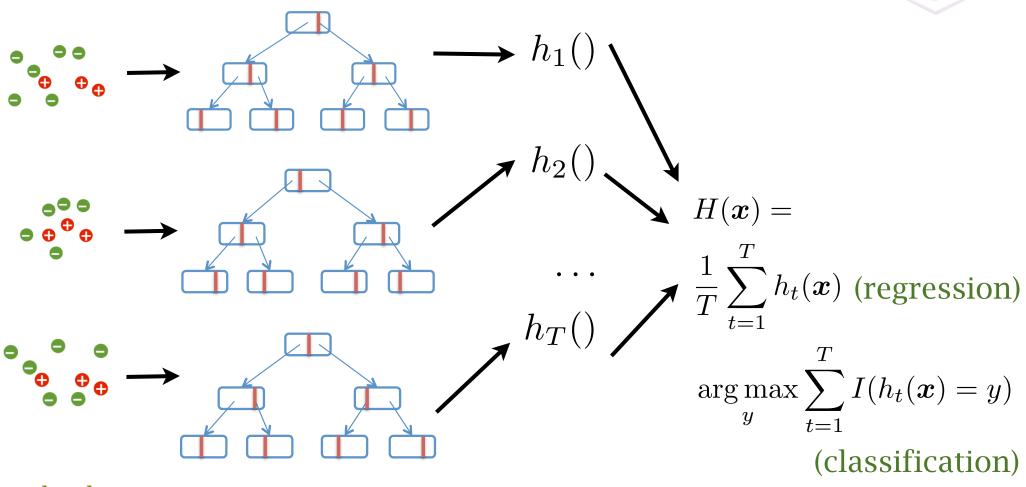
decision tree: select the best split from ALL features/splits

(other variants are available)



every run produce a different tree

Learning Parameter Manipulation: Random forest



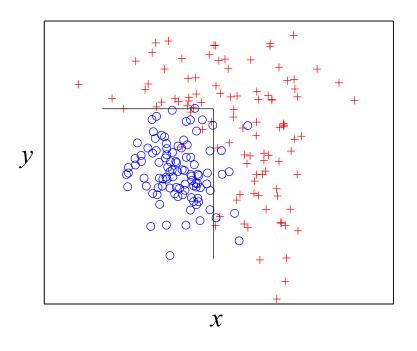
randomly sample data

randomized decision tree

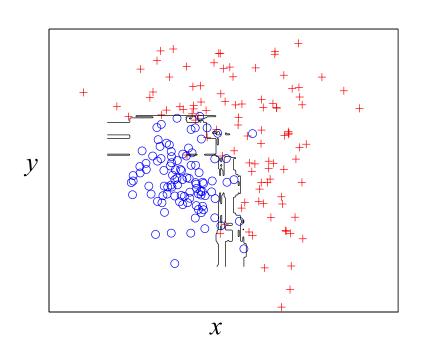
Bagging of randomized decision tree

Random forest









decision boundary of random forest



Diversity generating categories:

Data Sample Manipulation
bootstrap sampling/Bagging
Input Feature Manipulation
random subspace
Output Representation Manipulation
flipping output/output smearing
Learning Parameter Manipulation
random initialization
Random Forests

obtain diversity by randomization



Simple combination:

$$\frac{1}{T} \sum_{t=1}^{T} h_t(\boldsymbol{x})$$
 (simple average for regression)

$$\arg\max_{y} \sum_{t=1}^{T} I(h_t(\boldsymbol{x}) = y) \quad \text{(majority vote for classification)}$$



model-weighted combination: better model has higher weight

$$\frac{1}{T} \sum_{t=1}^{T} w_t h_t(\boldsymbol{x})$$
 (simple average for regression)

$$\underset{y}{\operatorname{arg\,max}} \sum_{t=1}^{T} w_t I(h_t(\boldsymbol{x}) = y)$$
 (majority vote for classification)



instance-weighted combination: weight by the confidence of the model

decision tree: the purity of the leave node

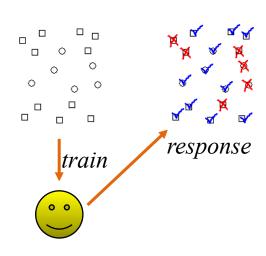
$$\frac{1}{T} \sum_{t=1}^{T} w_t(\boldsymbol{x}) h_t(\boldsymbol{x}) \quad \text{(simple average for regression)}$$

$$\arg\max_{y} \sum_{t=1}^{T} w_t(\boldsymbol{x}) I(h_t(\boldsymbol{x}) = y) \text{ (majority vote for classification)}$$

Sequential ensemble methods

Generate learners sequentially, focus on previous errors



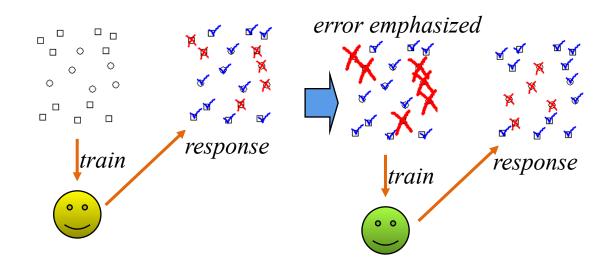


so that the combination of learners will have a high accuracy

Sequential ensemble methods

Generate learners sequentially, focus on previous errors



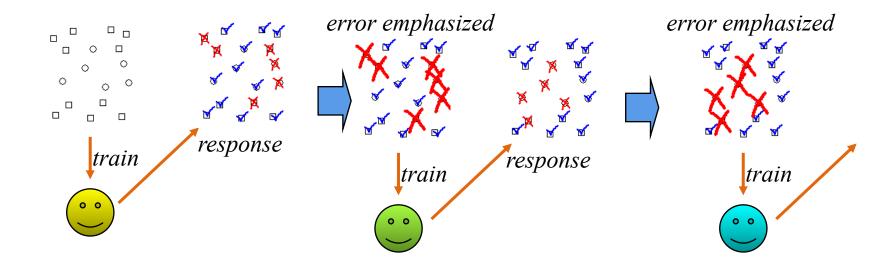


so that the combination of learners will have a high accuracy

Sequential ensemble methods

Generate learners sequentially, focus on previous errors





so that the combination of learners will have a high accuracy



Input: Data set $D = \{(x_1, y_1), (x_2, y_2), \dots, (x_m, y_m)\};$ Base learning algorithm \mathfrak{L} ; Number of learning rounds T.

Process:

- 1. $\mathcal{D}_1(x) = 1/m$. % Initialize the weight distribution
- 2. **for** t = 1, ..., T:
- 3. $h_t = \mathfrak{L}(D, \mathfrak{D}_t)$; % Train a classifier h_t from D under distribution \mathfrak{D}_t
- 4. $\epsilon_t = P_{\boldsymbol{x} \sim \mathcal{D}_t}(h_t(\boldsymbol{x}) \neq f(\boldsymbol{x}));$ % Evaluate the error of h_t
- 5. if $\epsilon_t > 0.5$ then break
- 6. $\alpha_t = \frac{1}{2} \ln \left(\frac{1 \epsilon_t}{\epsilon_t} \right)$; % Determine the weight of h_t

7.
$$\mathcal{D}_{t+1}(\boldsymbol{x}) = \frac{\mathcal{D}_{t}(\boldsymbol{x})}{Z_{t}} \times \begin{cases} \exp(-\alpha_{t}) & \text{if } h_{t}(\boldsymbol{x}) = f(\boldsymbol{x}) \\ \exp(\alpha_{t}) & \text{if } h_{t}(\boldsymbol{x}) \neq f(\boldsymbol{x}) \end{cases}$$

$$= \frac{\mathcal{D}_{t}(\boldsymbol{x}) \exp(-\alpha_{t} f(\boldsymbol{x}) h_{t}(\boldsymbol{x}))}{Z_{t}} \quad \text{\% Update the distribution, where}$$

$$\% Z_{t} \text{ is a normalization factor which}$$

$$\% \text{ enables } \mathcal{D}_{t+1} \text{ to be a distribution}$$

8. **end**

Output:
$$H(\boldsymbol{x}) = \operatorname{sign}\left(\sum_{t=1}^{T} \alpha_t h_t(\boldsymbol{x})\right)$$

fit an additive model, sequentially

$$H(\boldsymbol{x}) = \sum_{t=1}^{T} \alpha_t h_t(\boldsymbol{x})$$

to minimize exponential loss

$$\min e^{-yH(\boldsymbol{x})}$$

by Newton-like method



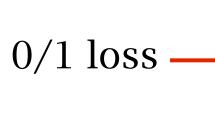
fit an additive model, sequentially

$$H(\boldsymbol{x}) = \sum_{t=1}^{T} \alpha_t h_t(\boldsymbol{x})$$



$$\min e^{-yH(\boldsymbol{x})}$$

by Newton-like method



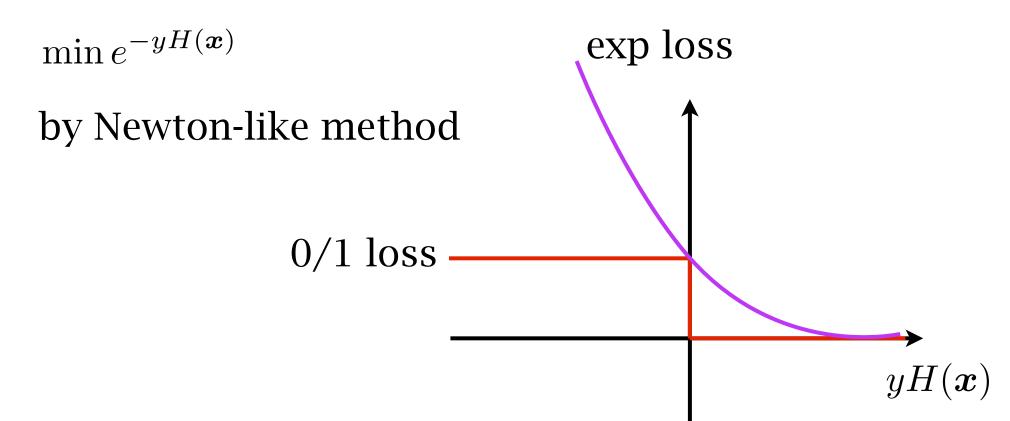


yH(x)

fit an additive model, sequentially

$$H(\boldsymbol{x}) = \sum_{t=1}^{T} \alpha_t h_t(\boldsymbol{x})$$









fit an additive model, sequentially

$$H(\boldsymbol{x}) = \sum_{t=1}^{T} \alpha_t h_t(\boldsymbol{x})$$

to minimize any loss by gradient decent



example: least square regression

$$\min \frac{1}{m} \sum_{i=1}^{m} (H(\boldsymbol{x}_i) - y_i)^2$$

1. fit the first base regressor

$$\min \frac{1}{m} \sum_{i=1}^{m} (h_1(\boldsymbol{x}_i) - y_i)^2$$

then how to train the second base regressor?

$$\min \frac{1}{m} \sum_{i=1}^{m} (h_1(\boldsymbol{x}_i) + h_2(\boldsymbol{x}_i) - y_i)^2$$

gradient descent in function space



$$\min \frac{1}{m} \sum_{i=1}^{m} (h_1(\boldsymbol{x}_i) + h_2(\boldsymbol{x}_i) - y_i)^2$$

gradient descent in function space

$$h_{\text{new}} \leftarrow -\frac{\partial (H-f)^2}{\partial H} = -2(H-f)$$

this function is not directly operable

operate through data

$$\forall \boldsymbol{x}_i : \hat{y}_i = -2(H(\boldsymbol{x}_i) - y_i)$$

fit h_2 point-wisely

$$h_{\text{new}} = \arg\min_{h} \frac{1}{m} \sum_{i=1}^{m} (h(x_i) - \hat{y}_i)^2$$



- 1. $h_0 = 0, H_0 = h_0$
- 2. For t = 1 to T
- 3. let $\forall x_i : y_i = -2(H_{t-1}(x_i) y_i)$
- 4. solve $h_t = \arg\min_{h} \frac{1}{m} \sum_{i=1}^{m} (h(x_i) y_i)^2$

(by some least square regression algorithm)

- 5. $H_t = H_{t-1} + \eta h_t$ (usually set $\eta = 0.01$)
- 6. next for

Output
$$H_T = \sum_{t=1}^{T} h_t$$

Gradient boosting (for classification)

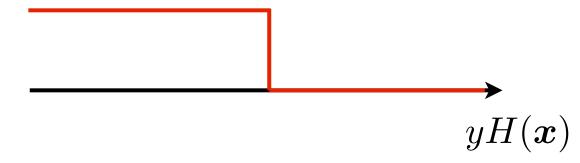




Gradient boosting (for classification)

0-1 loss

$$\min I(yH(\boldsymbol{x}) \leq 0)$$





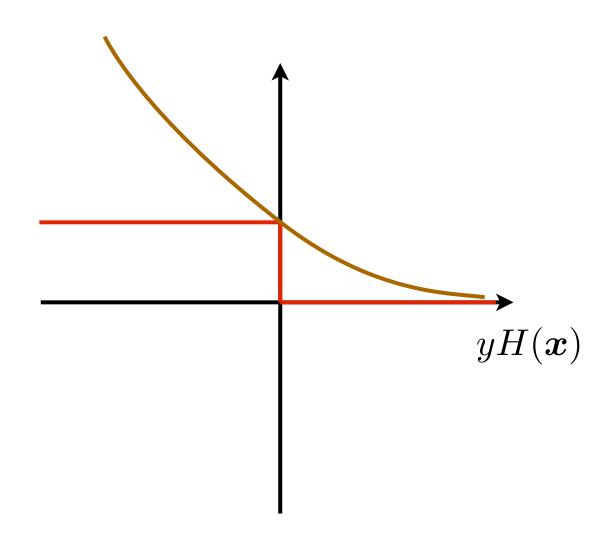
Gradient boosting (for classification)

0-1 loss

$$\min I(yH(\boldsymbol{x}) \le 0)$$

logistic regression

$$\min\log(1 + e^{-yH(\boldsymbol{x})})$$





Gradient boosting (for classification)

0-1 loss

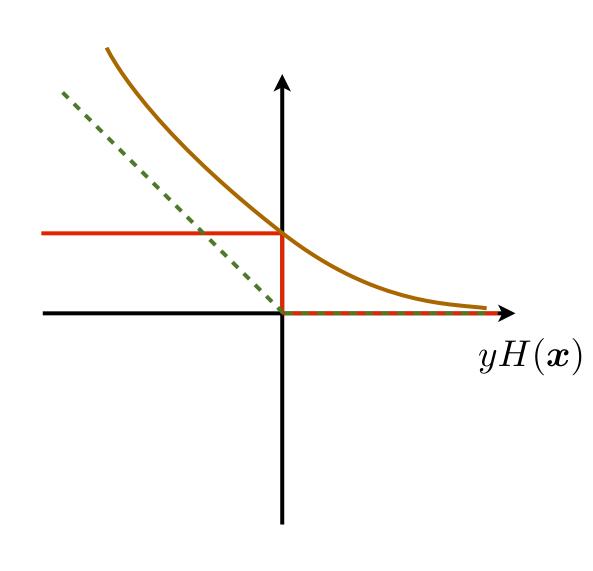
$$\min I(yH(\boldsymbol{x}) \le 0)$$

logistic regression

$$\min \log(1 + e^{-yH(\boldsymbol{x})})$$

perceptron

$$\min \max\{-yH(\boldsymbol{x}),0\}$$





Gradient boosting (for classification)

0-1 loss

$$\min I(yH(\boldsymbol{x}) \le 0)$$

logistic regression

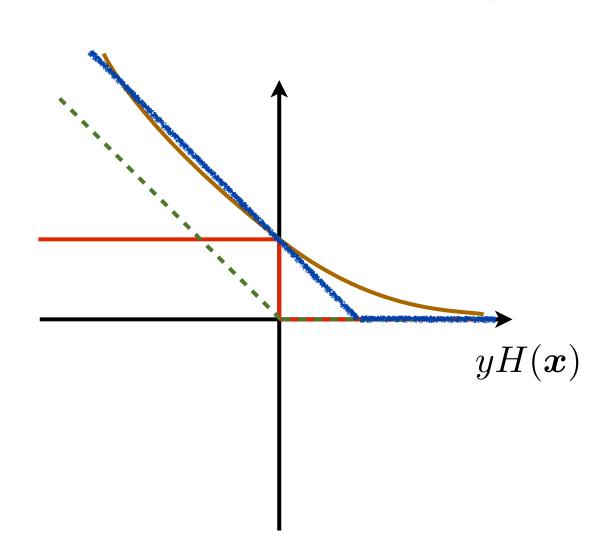
$$\min \log(1 + e^{-yH(\boldsymbol{x})})$$

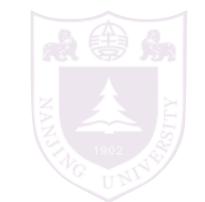
perceptron

$$\min \max\{-yH(\boldsymbol{x}), 0\}$$

hinge loss

$$\min\max\{1-yH(\boldsymbol{x}),0\}$$





Gradient boosting (for classification)

0-1 loss

$$\min I(yH(\boldsymbol{x}) \le 0)$$

logistic regression

$$\min \log(1 + e^{-yH(\boldsymbol{x})})$$

perceptron

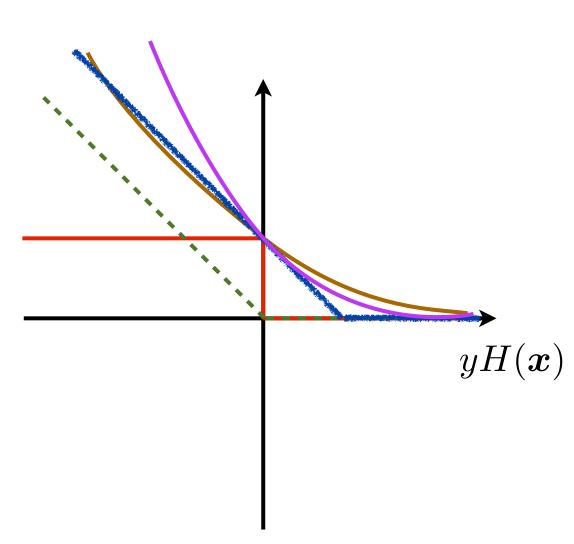
$$\min \max\{-yH(\boldsymbol{x}), 0\}$$

hinge loss

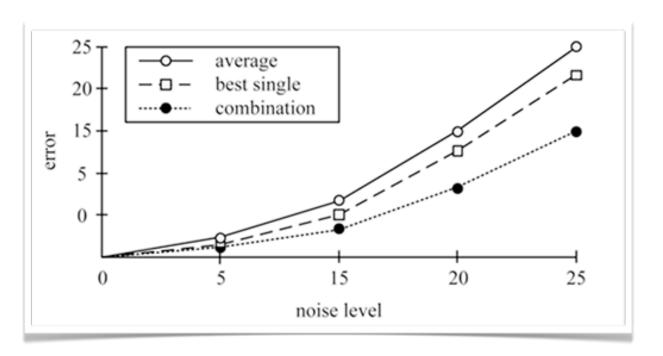
$$\min\max\{1-yH(\boldsymbol{x}),0\}$$

exponential loss

$$\min e^{-yH(\boldsymbol{x})}$$



Hansen and Salamon [PAMI'90] reported an observation that combination of multiple BP-NN is better than the best single BP-NN



for regression task:

mean error of base regressors

$$\frac{1}{T} \sum_{t} (h_t - f)^2$$

$$= \frac{1}{T} \sum_{t} (h_t - H + H - f)^2$$

$$= \frac{1}{T} \sum_{t} (h_t - H)^2 + \frac{1}{T} \sum_{t} (H - f)^2 - 2\frac{1}{T} \sum_{t} (h_t - H)(H - f)$$

$$= \frac{1}{T} \sum_{t} (h_t - H)^2 + (H - f)^2$$

 $= \frac{1}{T} \sum_{t} (h_t - H)^2 + (H - f)^2$ error of combined regressor

mean difference to the combined regressor

error of ensemble =

accurate and diverse

mean error of base regressors

- mean difference base regressors to the ensemble



for classification task:



$$err_g(f) \le err_S^{\theta}(f) + \frac{C}{\sqrt{m}} \left(\frac{\ln n \ln \left(m\sqrt{1/n + (1 - 1/n)(1 - q)} \right)}{\theta^2} + \ln \frac{1}{\delta} \right)^{1/2}$$

pairwise diversity

Bias-variance analysis bias varianc**¢** low variance. low bias,

high variance

parallel ensemble: reduce variance use unpruned decision trees

sequential ensemble: reduce bias and variance

high bias

Boosting:



AdaBoost

Boosting:



is weak learnable class equals strong learnable class?

L. Valiant Turing Award 2010



AdaBoost

(Gödel Prize 2003)

AdaBoost is the first practical boosting algorithm

yes! The proof is the boosting algorithm



R. Schapire

Applications

NAN A ALIS

KDDCup: data mining competition organized by ACM SIGKDD

KDDCup 2009: to estimate the churn, appetency and up-selling probability of customers.

An Ensemble of Three Classifiers for KDD Cup 2009: Expanded Linear Model, Heterogeneous Boosting, and Selective Naïve Bayes

Hung-Yi Lo, Kai-Wei Chang, Shang-Tse Chen, Tsung-Hsien Chiang, Chun-Sung Ferng, Cho-Jui Hsieh, Yi-Kuang Ko, Tsung-Ting Kuo, Hung-Che Lai, Ken-Yi Lin, Chia-Hsuan Wang, Hsiang-Fu Yu, Chih-Jen Lin, Hsuan-Tien Lin, Shou-de Lin {D96023, B92084, B95100, B93009, B95108, B92085, B93038, D97944007, R97028, R97117, B94B02009, B93107, CJLIN, HTLIN, SDLIN}@CSIE.NTU.EDU.TW Department of Computer Science and Information Engineering, National Taiwan University Taipei 106, Taiwan

KDDCup 2010: to predict student performance on mathematical problems from logs of student interaction with Intelligent Tutoring Systems. JMLR: Workshop and Conference Proceedings 1: 1-16

KDD Cup 2010

Feature Engineering and Classifier Ensemble for KDD Cup 2010

Hsiang-Fu Yu, Hung-Yi Lo, Hsun-Ping Hsieh, Jing-Kai Lou, Todd G. McKenzie, Jung-Wei Chou, Po-Han Chung, Chia-Hua Ho, Chun-Fu Chang, Yin-Hsuan Wei, Jui-Yu Weng, En-Syu Yan, Che-Wei Chang, Tsung-Ting Kuo, Yi-Chen Lo, Po Tzu Chang, Chieh Po, Chien-Yuan Wang, Yi-Hung Huang, Chen-Wei Hung, Yu-Xun Ruan, Yu-Shi Lin, Shou-de Lin, Hsuan-Tien Lin, Chih-Jen Lin Department of Computer Science and Information Engineering, National Taiwan University Taipei 106, Taiwan

KDDCup 2011, KDDCup 2012, and foreseeably, 2013, 2014 ...

Applications



Netflix Price: if one participating team improves Netflix's own movie recommendation algorithm by 10% accuracy, they would win the grand prize of \$1,000,000.

