Supplementary Material: Subset Selection under Noise

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1 Detailed Proofs

This part aims to provide some detailed proofs, which are omitted in our original paper due to space limitation.

Proof of Theorem 1. Let X^* be an optimal subset, i.e., $f(X^*) = OPT$. Let X_i denote the subset after the *i*-th iteration of the greedy algorithm. Then, we have

$$f(X^*) - f(X_i) \leq f(X^* \cup X_i) - f(X_i)$$

$$\leq \frac{1}{\gamma_{X_i,k}} \sum_{v \in X^* \setminus X_i} \left(f(X_i \cup \{v\}) - f(X_i) \right)$$

$$\leq \frac{1}{\gamma_{X_i,k}} \sum_{v \in X^* \setminus X_i} \left(\frac{1}{1 - \epsilon} F(X_i \cup \{v\}) - f(X_i) \right)$$

$$\leq \frac{1}{\gamma_{X_i,k}} \sum_{v \in X^* \setminus X_i} \left(\frac{1}{1 - \epsilon} F(X_{i+1}) - f(X_i) \right)$$

$$\leq \frac{k}{\gamma_{X_k,k}} \left(\frac{1 + \epsilon}{1 - \epsilon} f(X_{i+1}) - f(X_i) \right),$$

where the first inequality is by the monotonicity of f, the second inequality is by the definition of submodularity ratio and $|X^*| \leq k$, the third is by the definition of multiplicative noise, i.e., $F(X) \geq (1-\epsilon) \cdot f(X)$, the fourth is by line 3 of Algorithm 1, and the last is by $\gamma_{X_i,k} \geq \gamma_{X_{i+1},k}$ and $F(X) \leq (1+\epsilon) \cdot f(X)$. By a simple transformation, we can equivalently get

$$f(X_{i+1}) \ge \left(\frac{1-\epsilon}{1+\epsilon}\right) \left(\left(1 - \frac{\gamma_{X_k,k}}{k}\right) f(X_i) + \frac{\gamma_{X_k,k}}{k} OPT \right).$$

Based on this inequality, an inductive proof gives the approximation ratio of the returned subset X_k :

$$f(X_k) \ge \frac{\frac{1-\epsilon}{1+\epsilon} \frac{\gamma X_k, k}{k}}{1-\frac{1-\epsilon}{1+\epsilon} \left(1-\frac{\gamma X_k, k}{k}\right)} \left(1-\left(\frac{1-\epsilon}{1+\epsilon}\right)^k \left(1-\frac{\gamma X_k, k}{k}\right)^k\right) \cdot OPT.$$

Lemma 2 shows the relation between the F values of adjacent subsets, which will be used in the proof of Theorem 3.

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Lemma 2. For any $X \subseteq V$, there exists one item $\hat{v} \in V \setminus X$ such that

$$F(X \cup \{\hat{v}\}) \ge \left(\frac{1-\epsilon}{1+\epsilon}\right) \left(1 - \frac{\gamma_{X,k}}{k}\right) F(X) + \frac{(1-\epsilon)\gamma_{X,k}}{k} \cdot OPT.$$

Proof. Let X^* be an optimal subset, i.e., $f(X^*) = OPT$. Let $\hat{v} \in \arg \max_{v \in X^* \setminus X} F(X \cup \{v\})$. Then, we have $f(X^*) - f(X) \leq f(X^* \cup X) - f(X)$

$$\begin{aligned} X^*) - f(X) &\leq f(X^* \cup X) - f(X) \\ &\leq \frac{1}{\gamma_{X,k}} \sum_{v \in X^* \setminus X} \left(f(X \cup \{v\}) - f(X) \right) \\ &\leq \frac{1}{\gamma_{X,k}} \sum_{v \in X^* \setminus X} \left(\frac{1}{1 - \epsilon} F(X \cup \{v\}) - f(X) \right) \\ &\leq \frac{k}{\gamma_{X,k}} \left(\frac{1}{1 - \epsilon} F(X \cup \{\hat{v}\}) - f(X) \right), \end{aligned}$$

where the first inequality is by the monotonicity of f, the second inequality is by the definition of submodularity ratio and $|X^*| \leq k$, and the third is by $F(X) \geq (1 - \epsilon)f(X)$. By a simple transformation, we can equivalently get

$$F(X \cup \{\hat{v}\}) \ge (1 - \epsilon) \left(\left(1 - \frac{\gamma_{X,k}}{k}\right) f(X) + \frac{\gamma_{X,k}}{k} \cdot OPT \right)$$

By applying $f(X) \ge F(X)/(1+\epsilon)$ to this inequality, the lemma holds.

Proof of Theorem 3. Let J_{\max} denote the maximum value of $j \in [0, k]$ such that in P, there exists a solution x with $|x| \le j$ and

$$F(\boldsymbol{x}) \geq \frac{(1-\epsilon)\frac{\gamma_{\min}}{k}}{1-\frac{1-\epsilon}{1+\epsilon}\left(1-\frac{\gamma_{\min}}{k}\right)} \left(1-\left(\frac{1-\epsilon}{1+\epsilon}\right)^{j}\left(1-\frac{\gamma_{\min}}{k}\right)^{j}\right) \cdot OPT.$$

We analyze the expected number of iterations until $J_{\max} = k$, which implies that there exists one solution \boldsymbol{x} in P satisfying that $|\boldsymbol{x}| \leq k$ and $F(\boldsymbol{x}) \geq \frac{(1-\epsilon)\frac{\gamma_{\min}}{k}}{1-\frac{1-\epsilon}{1+\epsilon}(1-\frac{\gamma_{\min}}{k})}(1-(\frac{1-\epsilon}{1+\epsilon})^k(1-\frac{\gamma_{\min}}{k})^k) \cdot OPT$. Since $f(\boldsymbol{x}) \geq F(\boldsymbol{x})/(1+\epsilon)$, the desired approximation bound has been reached when $J_{\max} = k$.

The initial value of J_{max} is 0, since POSS starts from $\{0\}^n$. Assume that currently $J_{\text{max}} = i < k$. Let \boldsymbol{x} be a corresponding solution with the value i, i.e., $|\boldsymbol{x}| \leq i$ and

$$F(\boldsymbol{x}) \ge \frac{(1-\epsilon)\frac{\gamma_{\min}}{k}}{1-\frac{1-\epsilon}{1+\epsilon}\left(1-\frac{\gamma_{\min}}{k}\right)} \left(1-\left(\frac{1-\epsilon}{1+\epsilon}\right)^{i}\left(1-\frac{\gamma_{\min}}{k}\right)^{i}\right) \cdot OPT.$$
(1)

It is easy to see that J_{max} cannot decrease because deleting x from P (line 6 of Algorithm 2) implies that x is weakly dominated by the newly generated solution x', which must have a smaller size and a larger F value. By Lemma 2, we know that flipping one specific 0 bit of x (i.e., adding a specific item) can generate a new solution x', which satisfies that

$$F(\mathbf{x'}) \ge \left(\frac{1-\epsilon}{1+\epsilon}\right) \left(1-\frac{\gamma_{\mathbf{x},k}}{k}\right) F(\mathbf{x}) + \frac{(1-\epsilon)\gamma_{\mathbf{x},k}}{k} \cdot OPT$$
$$= \frac{1-\epsilon}{1+\epsilon} F(\mathbf{x}) + \left(OPT - \frac{F(\mathbf{x})}{1+\epsilon}\right) \frac{(1-\epsilon)\gamma_{\mathbf{x},k}}{k}.$$

Note that $OPT - \frac{F(\boldsymbol{x})}{1+\epsilon} \ge f(\boldsymbol{x}) - \frac{F(\boldsymbol{x})}{1+\epsilon} \ge 0$. Moreover, $\gamma_{\boldsymbol{x},k} \ge \gamma_{\min}$, since $|\boldsymbol{x}| < k$ and $\gamma_{\boldsymbol{x},k}$ decreases with \boldsymbol{x} . Thus, we have

$$F(\boldsymbol{x'}) \geq \left(\frac{1-\epsilon}{1+\epsilon}\right) \left(1-\frac{\gamma_{\min}}{k}\right) F(\boldsymbol{x}) + \frac{(1-\epsilon)\gamma_{\min}}{k} \cdot OPT.$$

By applying Eq. (1) to the above inequality, we easily get

$$F(\boldsymbol{x'}) \geq \frac{(1-\epsilon)\frac{\gamma_{\min}}{k}}{1-\frac{1-\epsilon}{1+\epsilon}\left(1-\frac{\gamma_{\min}}{k}\right)} \left(1-\left(\frac{1-\epsilon}{1+\epsilon}\right)^{i+1}\left(1-\frac{\gamma_{\min}}{k}\right)^{i+1}\right) \cdot OPT.$$

Since $|\mathbf{x}'| = |\mathbf{x}| + 1 \le i + 1$, \mathbf{x}' will be included into P; otherwise, \mathbf{x}' must be dominated by one solution in P (line 5 of Algorithm 2), and this implies that J_{\max} has already been larger than i, which contradicts with the assumption $J_{\max} = i$. After including \mathbf{x}' , $J_{\max} \ge i + 1$. Let P_{\max} denote the largest size of P during the run of POSS. Thus, J_{\max} can increase by at least 1 in one iteration with probability at least $\frac{1}{P_{\max}} \cdot \frac{1}{n}(1-\frac{1}{n})^{n-1} \ge \frac{1}{enP_{\max}}$, where $\frac{1}{P_{\max}}$ is a lower bound on the probability of selecting \mathbf{x} in line 3 of Algorithm 2 and $\frac{1}{n}(1-\frac{1}{n})^{n-1}$ is the probability of flipping only a specific bit of \mathbf{x} in line 4. Then, it needs at most enP_{\max} expected number of iterations to increase J_{\max} . Thus, after $k \cdot enP_{\max}$ expected number of iterations, J_{\max} must have reached k.

From the procedure of POSS, we know that the solutions in P must be non-dominated. Thus, each value of one objective can correspond to at most one solution in P. Because the solutions with $|\mathbf{x}| \geq 2k$ have $-\infty$ value on the first objective, they must be excluded from P. Thus, $P_{\max} \leq 2k$, which implies that the expected number of iterations $\mathbb{E}[T]$ for finding the desired solution is at most $2ek^2n$.

Proof of Proposition 1. Let $\mathcal{A} = \{S_1, \ldots, S_l\}$ and $\mathcal{B} = \{S_{l+1}, \ldots, S_{2l}\}$. For the greedy algorithm, if without noise, it will first select one S_i from \mathcal{A} , and continue to select S_i from \mathcal{B} until reaching the budget. Thus, the greedy algorithm can find an optimal solution. But in the presence of noise, after selecting one S_i from \mathcal{A} , it will continue to select S_i from \mathcal{A} rather than from \mathcal{B} , since for all $X \subseteq \mathcal{A}, S_i \in \mathcal{B}, F(X) = 2 + \delta > 2 = F(X \cup \{S_i\})$. The approximation ratio thus is only 2/(k+1).

For POSS under noise, we show that it can efficiently follow the path $\{0\}^n$ (i.e., \emptyset) $\rightarrow \{S\} \rightarrow \{S\} \cup X_2 \rightarrow \{S\} \cup X_3 \rightarrow \cdots \rightarrow \{S\} \cup X_{k-1}$ (i.e., an optimal solution), where S denotes any element from \mathcal{A} and X_i denotes any subset of \mathcal{B} with size *i*. Note that the solutions on the path will always be kept in the archive P once found, because there is no other solution which can dominate them. The probability of the first " \rightarrow " on the path is at least $\frac{1}{P_{\text{max}}} \cdot \frac{1}{n} (1 - \frac{1}{n})^{n-1}$, since it is sufficient to select $\{0\}^n$ in line 3 of Algorithm 2, and flip one of its first *l* 0-bits and keep other bits unchanged

in line 4. [Multi-bit search] For the second " \rightarrow ", the probability is at least $\frac{1}{P_{\text{max}}} \cdot \frac{\binom{l}{2}}{n^2} (1 - \frac{1}{n})^{n-2}$, since it is sufficient to select $\{S\}$ and flip any two 0-bits in its second half. For the *i*-th " \rightarrow " with $3 \le i \le k-1$, the probability is at least $\frac{1}{P_{\text{max}}} \cdot \frac{l-i+1}{n} (1 - \frac{1}{n})^{n-1}$, since it is sufficient to select the left solution of " \rightarrow " and flip one 0-bit in its second half. Thus, starting from $\{0\}^n$, POSS can follow the path in

$$enP_{\max} \cdot \left(\frac{1}{l} + \frac{4}{l-1} + \sum_{i=3}^{k-1} \frac{1}{l-i+1}\right) = O(nP_{\max}\log n)$$

expected number of iterations. Since $P_{\max} \leq 2k$, the number of iterations for finding an optimal solution is $O(kn \log n)$ in expectation.

Proof of Proposition 2. For the greedy algorithm, if without noise, it will first select S_{4l-2} since $|S_{4l-2}|$ is the largest, and then find the optimal solution $\{S_{4l-2}, S_{4l-1}\}$. But in the presence of noise, S_{4l} will be first selected since $F(\{S_{4l}\}) = 2l$ is the largest, and then the solution $\{S_{4l}, S_{4l-1}\}$ is found. The approximation ratio is thus only (3l-2)/(4l-3).

For POSS under noise, we first show that it can efficiently follow the path $\{0\}^n \to \{S_{4l}\} \to \{S_{4l}, S_{4l-1}\} \to \{S_{4l-2}, S_{4l-1}, *\}$, where * denotes any subset S_i with $i \neq 4l - 2, 4l - 1$. In this procedure, we can pessimistically assume that the optimal solution $\{S_{4l-2}, S_{4l-1}\}$ will never be found, since we are to derive a running time upper bound for finding it. Note that the solutions on the path will always be kept in P once found, because no other solutions can dominate them. The probability of " \rightarrow " is at least $\frac{1}{P_{\text{max}}} \cdot \frac{1}{n}(1-\frac{1}{n})^{n-1} \geq \frac{1}{enP_{\text{max}}}$, since it is sufficient to select the solution on the left of " \rightarrow " and flip only one specific 0-bit. Thus, starting from $\{0\}^n$, POSS can follow the path in $3 \cdot enP_{\text{max}}$ expected number of iterations. [Backward search] After that, the optimal solution $\{S_{4l-2}, S_{4l-1}\}$ can be found by selecting $\{S_{4l-2}, S_{4l-1}, *\}$ and flipping a specific 1-bit, which happens with probability at least $\frac{1}{enP_{\text{max}}}$. Thus, the total number of required iterations is at most $4enP_{\text{max}}$ in expectation. Since $P_{\text{max}} \leq 4$, $\mathbb{E}[T] = O(n)$.

For the analysis of PONSS in the original paper, we assume that

$$\Pr(F(\boldsymbol{x}) > F(\boldsymbol{y})) \ge 0.5 + \delta \quad \text{if} \quad f(\boldsymbol{x}) > f(\boldsymbol{y}),$$

where $\delta \in [0, 0.5)$. To show that this assumption holds with i.i.d. noise distribution, we prove the following claim. Note that the value of δ depends on the concrete noise distribution.

Claim 1. If the noise distribution is i.i.d. for each solution x, it holds that

$$\Pr(F(x) > F(y)) \ge 0.5$$
 if $f(x) > f(y)$.

Proof. If $F(x) = f(x) + \xi(x)$, where the noise $\xi(x)$ is drawn independently from the same distribution for each x, we have, for two solutions x and y with f(x) > f(y),

$$\begin{aligned} \Pr(F(\boldsymbol{x}) > F(\boldsymbol{y})) &= \Pr(f(\boldsymbol{x}) + \xi(\boldsymbol{x}) > f(\boldsymbol{y}) + \xi(\boldsymbol{y})) \\ &\geq \Pr(\xi(\boldsymbol{x}) \ge \xi(\boldsymbol{y})) \\ &\geq 0.5, \end{aligned}$$

where the first inequality is by the condition that $f(\boldsymbol{x}) > f(\boldsymbol{y})$, and the last inequality is derived by $\Pr(\xi(\boldsymbol{x}) \ge \xi(\boldsymbol{y})) + \Pr(\xi(\boldsymbol{x}) \le \xi(\boldsymbol{y})) \ge 1$ and $\Pr(\xi(\boldsymbol{x}) \ge \xi(\boldsymbol{y})) = \Pr(\xi(\boldsymbol{x}) \le \xi(\boldsymbol{y}))$ due to that $\xi(\boldsymbol{x})$ and $\xi(\boldsymbol{y})$ are from the same distribution.

If $F(\mathbf{x}) = f(\mathbf{x}) \cdot \xi(\mathbf{x})$, the claim holds similarly.

2 Detailed Experimental Results

This part aims to provide some experimental results, which are omitted in our original paper due to space limitation.



Figure 1: Influence maximization with the budget k = 7 (influence spread: the larger the better): the comparison between PONSS with different θ values, POSS and the greedy algorithm.



Figure 2: Sparse regression with the budget k = 14 (R^2 : the larger the better): the comparison between PONSS with different θ values, POSS and the greedy algorithm.